FACTORY AUTOMATION

Mitsubishi Electric Programmable Controller MELSEC iQ-F Series

Quick Connection Guide

FREQROL-D700 Serial Communication

MELSEC iQ-F series × **FREQROL-D700**

INTRODUCTION

Thank you for purchasing the Mitsubishi Electric MELSEC iQ-F series programmable controllers.
This manual describes the settings for the inverter communication function of the FX5 CPU module.
Before using this product, please read this manual and relevant manuals carefully and develop familiarity with the specifications to handle the product correctly.

Regarding use of this product

- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, please contact Mitsubishi Electric sales office.
- This product has been manufactured under strict quality control. However when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions into the system.

Note

- If in doubt at any stage during the installation of the product, always consult a professional electrical engineer who is qualified and trained to the local and national standards. If in doubt about the operation or use, please contact your local Mitsubishi Electric representative.
- Mitsubishi Electric will not accept responsibility for actual use of the product based on these illustrative examples. Please use it after confirming the function and safety of the equipment and system.
- The content, specification etc. of this manual may be changed, for improvement, without notice.
- The information in this manual has been carefully checked and is believed to be accurate; however, if you notice a doubtful point, an error, etc., please contact your local Mitsubishi Electric representative. When doing so, please provide the manual number given at the end of this manual.
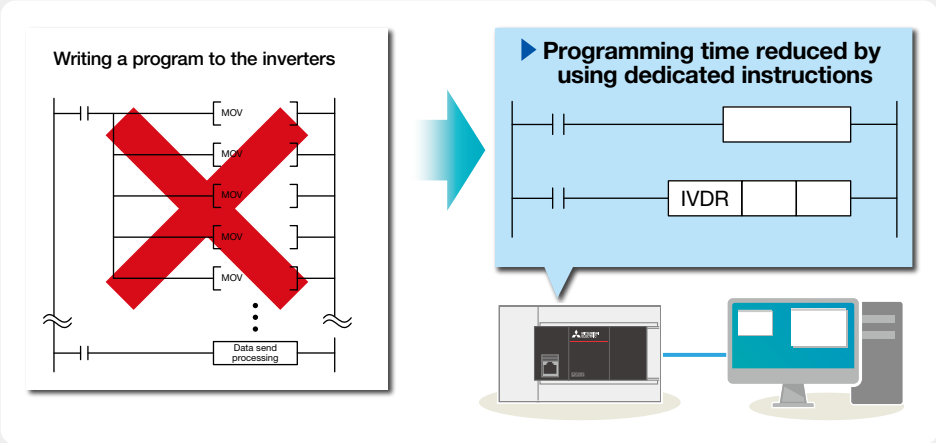
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KEY FEATURES TO FACILITATE OPERATION

Point 1

Easy inverter control using dedicated instructions

Inverter control is facilitated by monitoring and controlling operations and reading and changing parameters using the dedicated instructions.

Writing a program to the inverters

MOV
MOV
MOV
MOV
MOV
Data send processing

▶ **Programming time reduced by using dedicated instructions**

IVDR

Point 2

Easy parameter setting using the setting dial

The scroll speed of the setting dial is adjustable, enhancing the usability. The non-slip surface treatment enables easier turning.

0.00
RUN
STOP RESET
MODE   SET   PU EXT
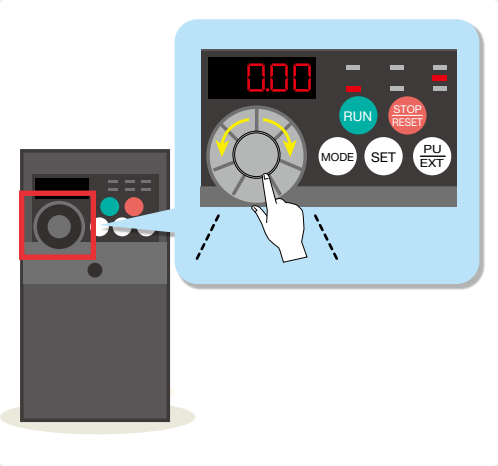
Point 3

Easy connection between internal ports

Maximum 16 inverters can be connected extensively, with the overall cable distance of 50 meters, by using the built-in RS-485 port of the CPU module.
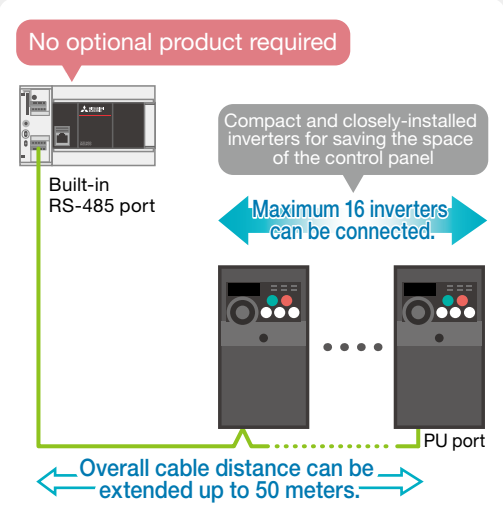
No optional product required

Built-in RS-485 port

Compact and closely-installed inverters for saving the space of the control panel

Maximum 16 inverters can be connected.

PU port

Overall cable distance can be extended up to 50 meters.

1. PREPARATION

1 PREPARATION

2 INVERTER SETTINGS

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4 CHECKING COMMUNICATION STATUS

5 EXAMPLE PROGRAMS

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1.1 Preparatory Steps

Refer to ➡ P.5 .

1 Preparing the required products

Refer to ➡ P.13 .

2 Setting the invertors

GX Works3

Ethernet

Refer to ➡ P.18 .
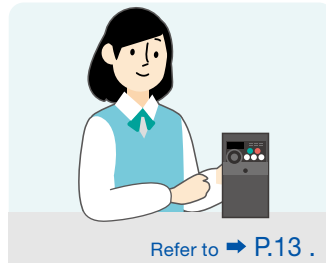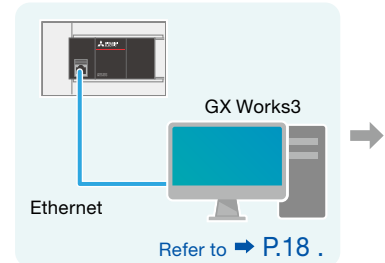
3 Setting the programmable controller and creating communication test programs

Ethernet cable

Refer to ➡ P.25 .
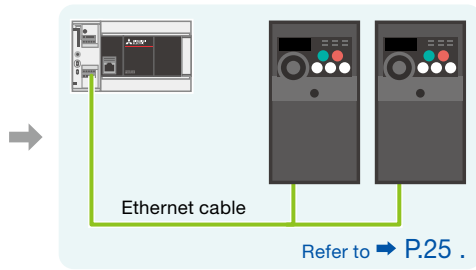
4 Checking the communication status

Refer to ➡ P.27 .
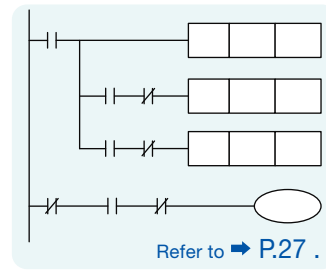
5 Example programs and checking the operation

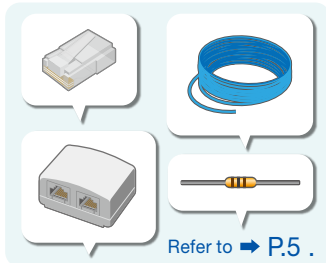## 1.2 Required Products

In this manual, two inverters (FR-D700) are connected to the FX5 CPU module.

▶ **FX5 CPU module**

▶ **Personal computer**

▶ **GX Works3**

▶ **Ethernet cable**

× 2

× 4

- 10BASE-T
  Shielded twisted pair (STP) cable or category 3, 4, or 5 of unshielded twisted pair (UTP) cable

▶ **Terminal block**
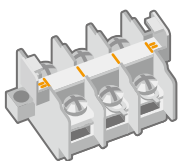
▶ **Terminating resistor 100 Ω, 1/2 W**

(Brown, Black, Brown, Gold)

▶ **Distributor × 2**
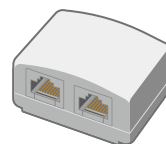
<BMJ-8-28N>
There is no internal connection of pins 2 and 8.

▶ **Inverter (FR-D700) × 2**
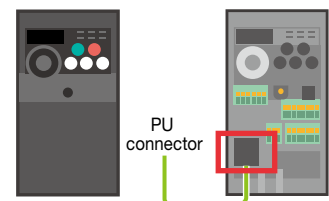
PU connector

Remove the front covers of the inverters to connect the cables to the PU connectors.

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Preparatory Steps | Required Products | System Configuration | Wiring | Connecting a Terminating Resistor

The following items are required for making a LAN cable.

▶ **Ethernet cable**
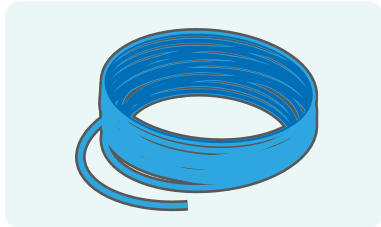
• Cable type:
  10BASE-T cable (category 3, 4, or 5)
• Connection specifications:
  Straight type

▶ **RJ45 connector (modular plug)**

• Using a modular plug with a load bar and clip breakage prevention is recommended.

▶ **Modular cover** Optional
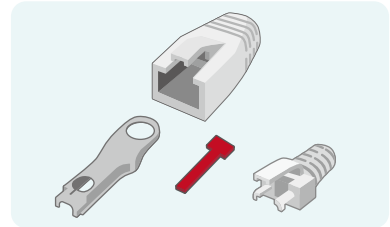
• Using a pre-attached type modular cover is recommended.

Tools

▶ **Crimping tool**
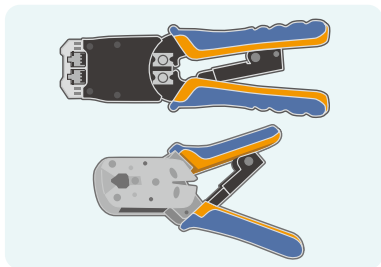
Used to crimp an RJ45 connector.

▶ **Wire stripper** Optional
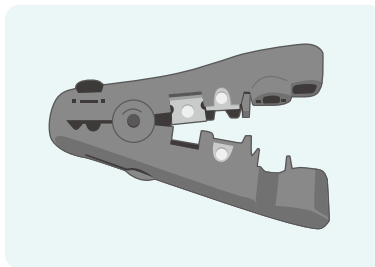
Used to strip cable jackets when connecting the LAN cables. Wiring time can be reduced by using this tool. It can be substituted with a cutter or a pair of scissors.

▶ **LAN cable tester** Optional
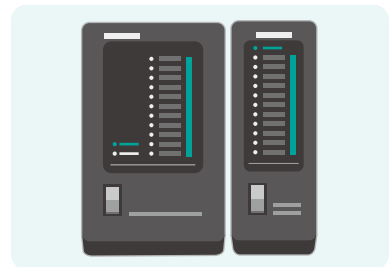
Used to check disconnection of the self-made LAN cable. Using a separator type is recommended.

1. PREPARATION

1.3 System Configuration

This section describes the system configuration in which two inverters (FR-D700) are connected to the FX5 CPU module.

FX5 CPU module

Personal computer

GX Works3

To be installed in advance.

LAN cable

Terminal treatment and wiring (single wire) ➡ P.9 .
Making a LAN cable ➡ P.10 .

Terminating resistor
100 Ω, 1/2 W

Terminal block

Distributor

< BMJ-8-28N >

BMJ-8-28N
(There is no internal connection of pins 2 and 8.)
(A plug with a terminating resistor is not used.)

FR-D700 × 2

<FR-D700 series>

• FR-D720-□K
• FR-D740-□K
• FR-D720S-□K
• FR-D710W-□K

For the power supply wiring of FR-D700 series, refer to
➡ Section 2.1 Wiring in the FR-D700 INSTRUCTION MANUAL (Applied) (IB(NA)-0600366 ENG).
For the power supply wiring of the FX5 CPU module, refer to
➡ Section 6.4 Power Supply Wiring in the MELSEC iQ-F FX5U User's Manual (Hardware) (JY997D55301) and
➡ Section 6.4 Power Supply Wiring in the MELSEC iQ-F FX5UC User's Manual (Hardware) (JY997D61401).

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1.4 Wiring

This section describes the procedures for wiring and terminal treatment of the cables.

▶ Wiring LAN cables (RS-485 port side)

Connect a single wire to a built-in RS-485 port on the terminal block.

| SG | SDB | SDA | RDB | RDA |

Set the terminating resistor selector switch to the 110 Ω position.

Programmable controller

1) Orange and white
2) Orange
3) Green and white
4) Blue
5) Blue and white
6) Green
7) Brown and white
8) Brown

3) Green and white
6) Green

1) 2) 3) 4) 5) 6) 7) 8)

1) ·······▶ 8)

Terminal block

(Brown, Black, Brown, Gold)

Terminating resistor 100 Ω, 1/2 W

Inverter

Inverter

1. PREPARATION

Preparatory Steps | Required Products | System Configuration | Wiring | Connecting a Terminating Resistor
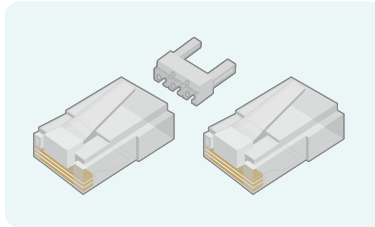
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1.4.1 Cable terminal treatment and wiring (single wire)

Strip the cable jacket, and perform cable terminal treatment for a stranded or solid wire.
Alternatively, use a bar terminal with an insulation sleeve.

▶ Terminal treatment for the stranded or solid wire

Cable jacket stripping length	
FX5U CPU module built-in RS-485 port	FX5UC CPU module built-in RS-485 port
5 mm	9 mm

▶ Using a bar terminals with an insulation sleeve

	Dimensions	Model	Crimping tool
FX5U CPU module built-in RS-485 port	Insulation sleeve / Contact (Crimped) / 2 - 2.5 mm / 14 mm / 6 mm	AI 0.5-6 WH	CRIMPFOX 6 CRIMPFOX 6T-F
FX5UC CPU module built-in RS-485 port	Insulation sleeve / Contact (Crimped) / 2.6 mm / 14 mm / 8 mm	AI 0.5-8 WH	

Screwdriver for the RS-485 terminal block
Use a commercially available small screwdriver with a straight edge, which does not spread at the end, as shown in the figure on the right.

Straight-edge blade
0.4 mm   2.5 mm

<Reference>

Manufacturer	Model
PHOENIX CONTACT Co., Ltd.	SZS0.4 × 2.5

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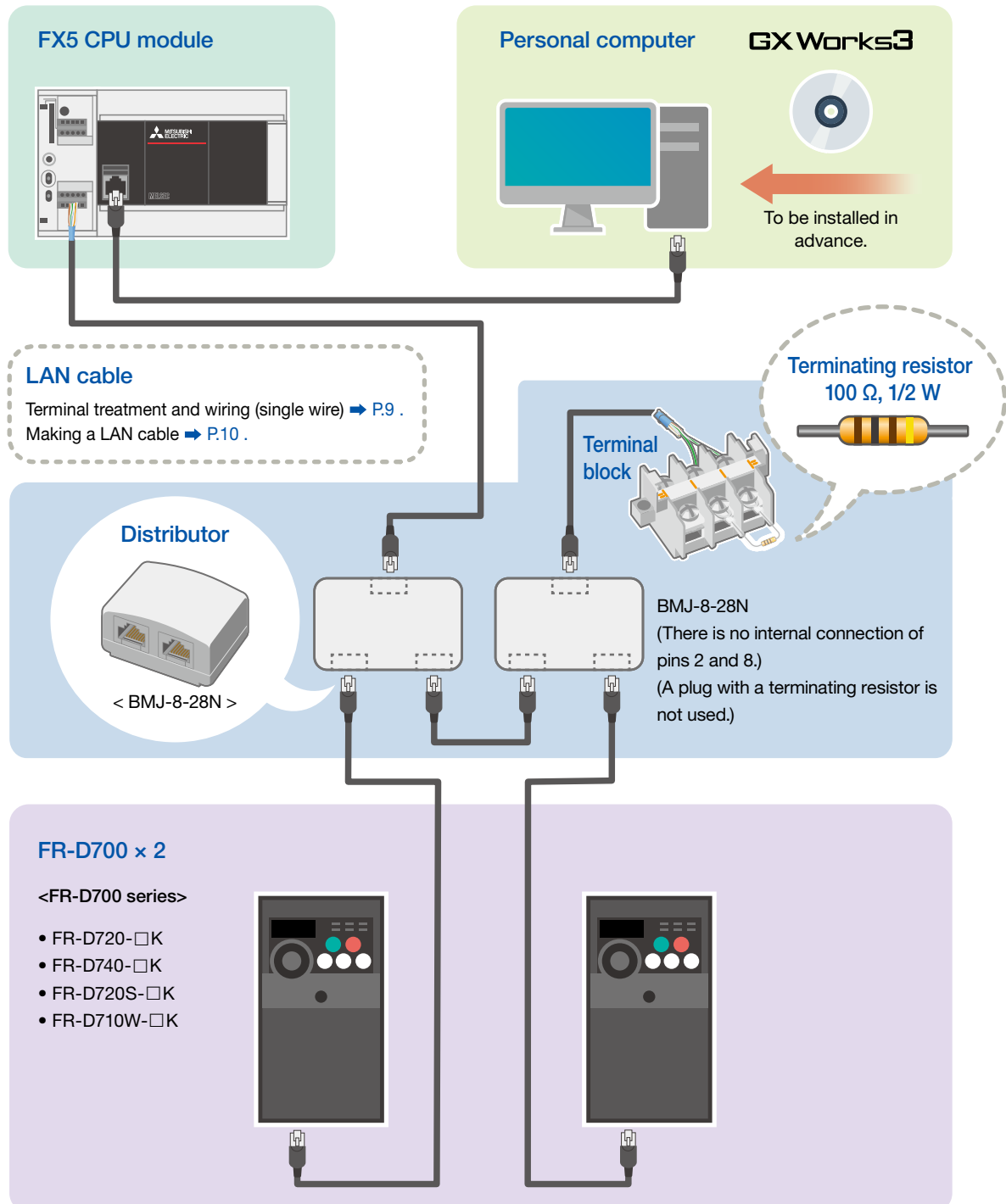# 1. PREPARATION

Preparatory Steps | Required Products | System Configuration | **Wiring** | Connecting a Terminating Resistor

1.4.2 Making a LAN cable

Follow the procedure below when making a LAN cable.

Step 1. Cutting a cable

Cut the cable to a required length.

Step 2. Attaching a modular cover (temporary)

When using a pre-attached type modular cover, attach it to the cable.

← Pay attention to the orientation
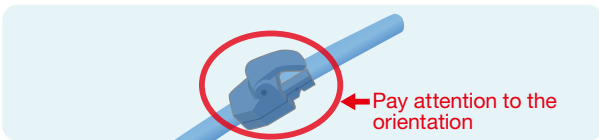
Step 3. Stripping a cable jacket

Strip the cable jacket on both ends using a cable stripper.

It can be substituted with a cutter or a pair of scissors. When using either one of them, be careful not to damage core wires.
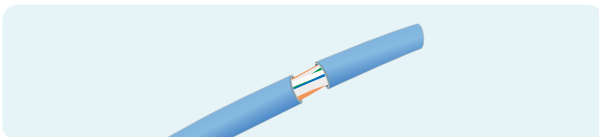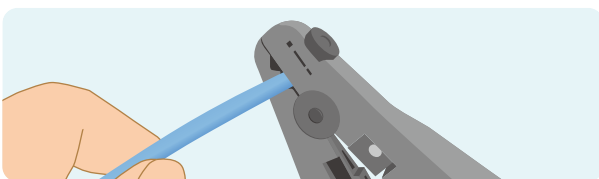
Cut out the cross separator in the cable if applicable.
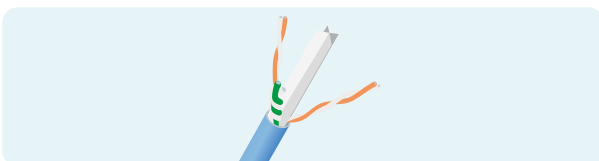
Step 4. Rearranging core wires

Rearrange the core wires in accordance with the type of a LAN cable to be made.

■Front view of the connector (insertion side)
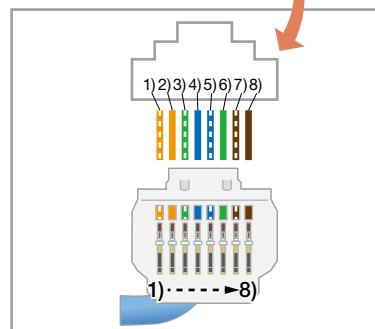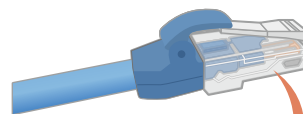
1) 2) 3) 4) 5) 6) 7) 8)

1) ····· ►8)

1) Orange and white
2) Orange
3) Green and white
4) Blue
5) Blue and white
6) Green
7) Brown and white
8) Brown

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Preparatory Steps | Required Products | System Configuration | **Wiring** | Connecting a Terminating Resistor
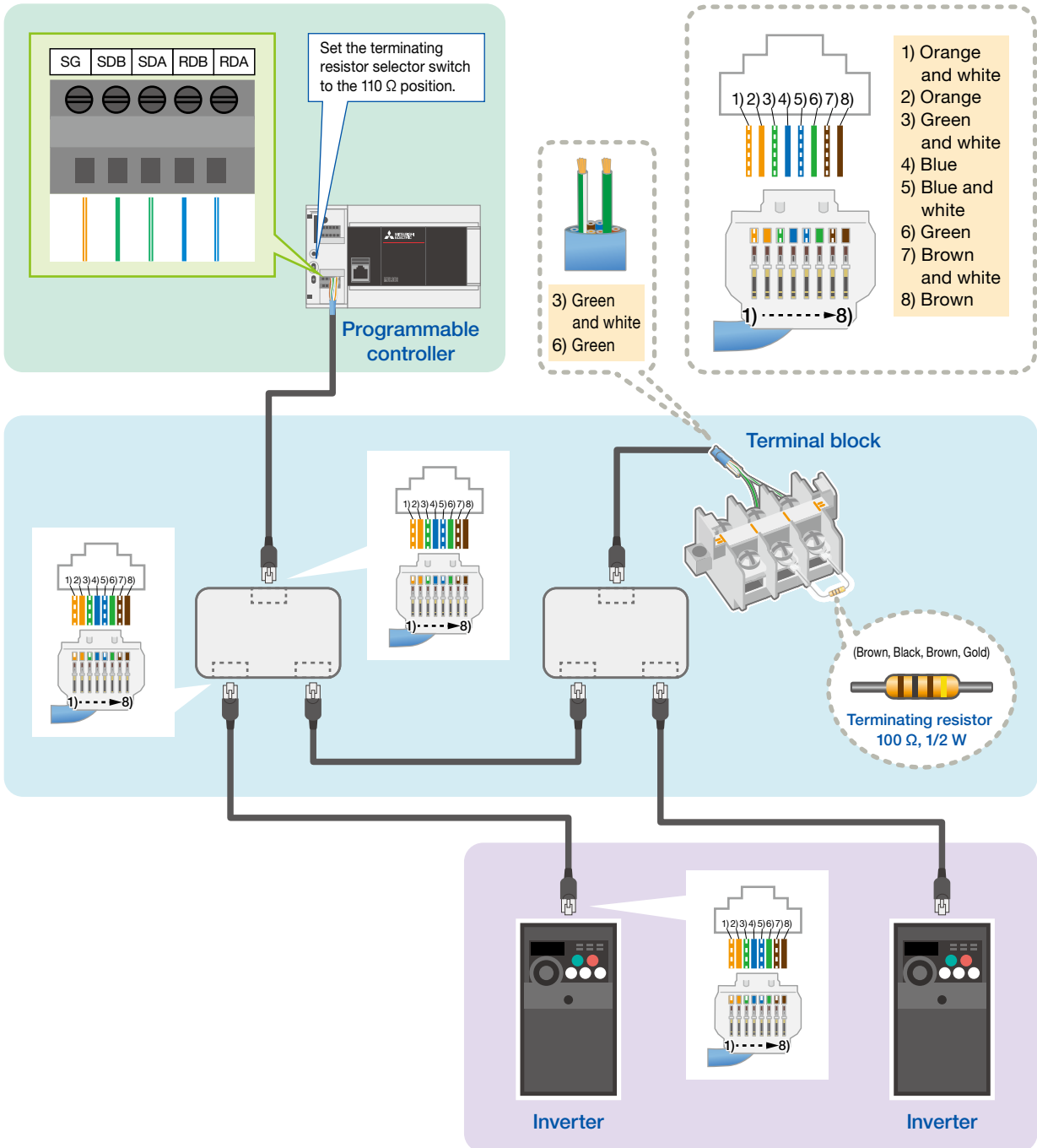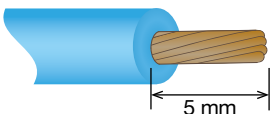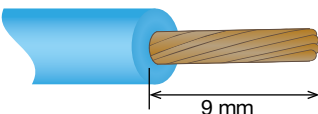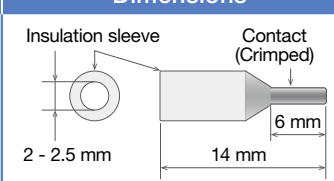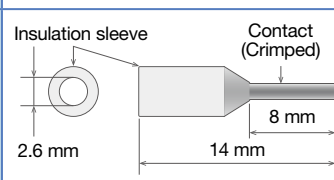
From the previous page

Step 5. Cutting core wires

With a load bar	Without a load bar
1. Insert each core wire through the slot of the load bar.	1. Arrange the core wires, and cut them to approximately 1.5 cm.

Appearance of the load bar
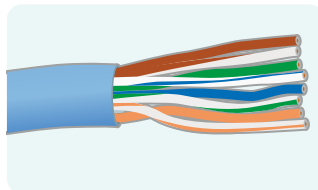
2. Cut the core wires at the edge of the load bar.	2. Insert the core wires into a connector.

Cutting
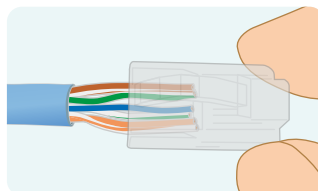
3. Insert the load bar into a connector.	3. Check that the core wires reach the end of the connector.

4. Make sure that the load bar is fully inserted to reach the end of the connector.
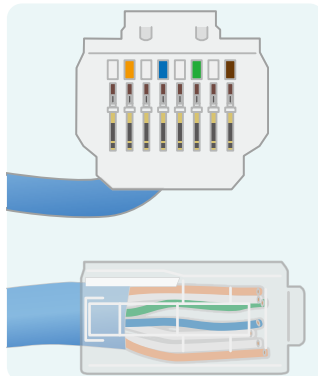
Step 6. Crimping the connector using a crimping tool

Crimp the connector onto the cable using the crimping tool.
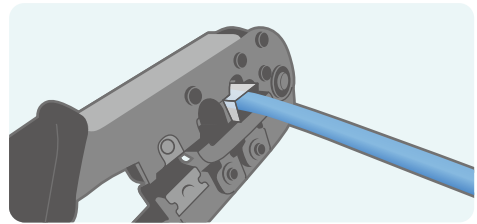
Step 7. Checking the self-made LAN cable

Check that there is no improper connection or disconnection of the self-made LAN cable.
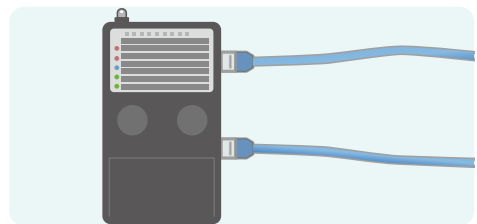
Step 8. Adjusting and fixing the modular cover (When the pre-attached type modular cover is used)

[Before]
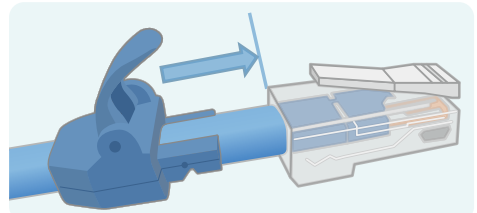
[After]
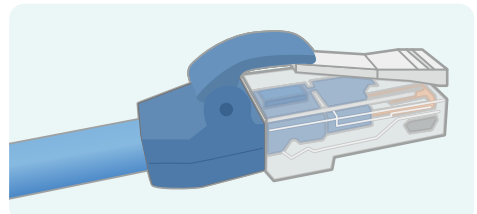
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1.5 Connecting a Terminating Resistor

Connect a terminating resistor of 100 Ω, 1/2 W to the farthest inverter. Connect it across pin 3 (RDA) and pin 6 (RDB) of the distributor.
The following is a typical connection example.

▶ **Connecting the terminating resistor to the inverter using a terminal block**

2. INVERTER SETTINGS

2.1 Names of the Parts on the Operation Panel

Inverter parameters can be set and checked on the operation panel. The parameters are shown on the LCD display.

[Operation panel (enlarged view)]

▶ Monitor (4-digit LED)

Shows the frequency, parameter number, etc.

▶ Operation status LEDs

PU	: Lit to indicate PU operation mode.
EXT	: Lit to indicate External operation mode.
	(Lit at power-ON at initial setting.)
NET	: Lit to indicate Network operation mode.

PU, EXT : Lit to indicate External/PU combined operation mode 1, 2.
All indicators are OFF when the command source is not on the operation panel.

▶ Monitoring status LED

Lit to indicate monitoring mode.

▶ Parameter setting mode LED

Lit to indicate parameter setting mode.

▶ Stop operation

Used to stop operation commands.
Fault can be reset when protective function is activated (fault).

▶ Setting dial

(Setting dial of inverters)
Used to change the frequency and parameter settings.
Press the dial to display the following.
- Displays the set frequency in the monitor mode.
- Present set value is displayed during calibration.
- Displays the order in the fault history mode.

▶ Determination of each setting

When this key is pressed during operation, monitor item changes as below.

Running frequency
↓
Output current
↓
Output voltage

▶ Operation mode switchover

Used to switch between the PU and External operation modes.
When using the External operation mode (operation using a separately connected frequency setting potentiometer and start signal), press this key to light up the EXT LED.
(Press [MODE] simultaneously (0.5 s), or change the Pr.79 (operation mode selection) setting to change to combined mode.)
- PU : PU operation mode
- EXT: External operation mode

Also cancels the PU stop warning.

*: The operation panel cannot be removed from the inverter.

For the names of the parts on the operation panel, refer to
➡ Section 4.1 Operation panel in the FR-D700 Instruction Manual (Applied) (IB(NA)-0600366ENG).

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Names of the Parts on the Operation Panel | **Parameter List** | Parameter Settings | Inverter Reset

2.2 Parameter List

2.2.1 Inverter communication settings (required settings)

The following lists the parameters which are required to be set.

Description	Parameter	Name	Initial value	Setting value (for the first inverter)	Setting value (for the second inverter)	Description
Display setting	Pr.160	Extended function display selection	9999	0	0	0: Displays simple mode and extended parameters.
Communication setting	Pr.117	PU communication station number	0	0	1	Maximum 16 inverters can be connected.
	Pr.118	PU communication speed	192	192	192	48 : 4800 bps 96 : 9600 bps 192 : 19200 bps 384 : 38400 bps
	Pr.119	PU communication stop bit length	1	10	10	10: Data length: 7 bits Stop bit: 1 bit
	Pr.120	PU communication parity check	2	2	2	2: Even parity
	Pr.123	PU communication waiting time setting	9999	9999	9999	Set with communication data.
	Pr.124	PU communication CR/LF selection	1	1	1	1: CR: Provided, LF: Not provided
	Pr.549	Protocol selection	0	0	0	0: Mitsubishi inverter (computer link operation) protocol
Operation mode setting	Pr.79	Operation mode selection	0	0	0	0: At power ON, the inverter is in the External operation mode.
	Pr.340	Communication startup mode selection	0	10	10	1 : Network operation mode 10: Network operation mode (Operation mode can be changed between the PU operation mode and Network operation mode from the operation panel.)

2.2.2 Parameter settings (for adjustment and operation)

Parameter	Name	Setting value during adjustment	Initial value	Setting value (for the first and second inverters)	Description
Pr.121	Number of PU communication retries	9999	1	3 (times)	Set "9999" during adjustment, and set a value from 1 to 10 during operation.
Pr.122	PU communication check time interval	9999	0	5.0 (= 5 seconds)	Set "9999" during adjustment, and set a value in accordance with the system specification during operation. 9999 : During adjustment or when the inverters do not communicate with the programmable controller periodically 0 : When the inverters do not communicate with the programmable controller 1 to 9998: When it is necessary to monitor absence of communications for a certain time and stop the inverters while they are communicating with the programmable controller continuously. When it is necessary to stop the motor when the programmable controller mode is changed from RUN to STOP.

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2.3 Parameter Settings

This section describes the parameter settings on the inverters.
Set Pr.160 (extended function display selection) to "0" to enable the parameter so that relevant parameters are displayed.

▶ Presetting for the inverter communication settings

1. Enabling the following modes for setting the parameters on the operation panel
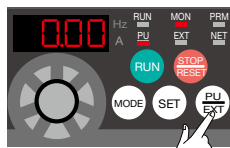
Press (PU/EXT) and switch to PU operation mode. (The PU LED is ON.)
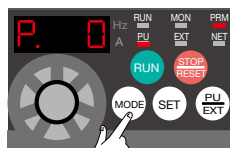
Press (MODE) and switch to parameter setting mode. (The PRM LED is ON.)

2. Enabling the parameter settings

Set the following parameter before the communication parameters are set. ⊙ indicates the setting dial.
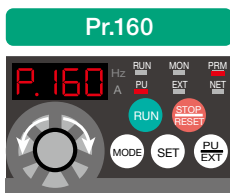
Pr.160

Turn ⊙ and set to P.160 (Pr.160).

Press (SET).
The initial value "9999" is displayed.
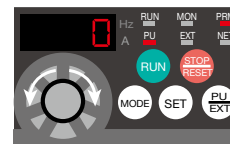
Turn ⊙ and set to 0.
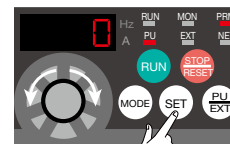
Press (SET).

*: The parameter number and the setting value are displayed alternately after the parameter setting is completed. When the value is not changed, this will not happen.

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The following describes the settings of the required parameters: Pr.117 (PU communication station number) and Pr.340 (communication startup mode selection).

▶ **Communication parameter settings**

■ **Pr.117 (PU communication station number) setting**

Turn ⬤ and set to P.117 (Pr.117).
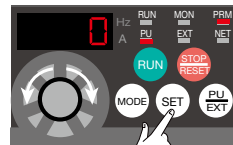
Press SET. The initial value "0" is displayed.
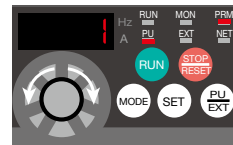
Turn ⬤ and set to a predetermined inverter station number.

- First inverter: 0
- Second inverter: 1
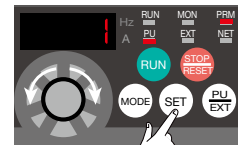
Press SET.

*: The parameter number and the setting value are displayed alternately after the parameter setting is completed. When the value is not changed, this will not happen.

■ **Pr.340 (communication startup mode selection) setting**
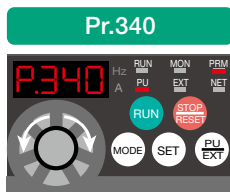
Turn ⬤ and set to P.340 (Pr.340).
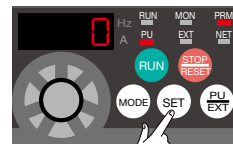
Press SET. The initial value "0" is displayed.
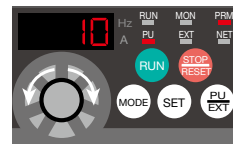
Turn ⬤ and set to 10.
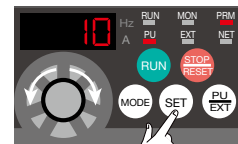
Press SET.

*: The parameter number and the setting value are displayed alternately after the parameter setting is completed. When the value is not changed, this will not happen.

Pr.117 (PU communication station number) and Pr.340 (communication startup mode selection) have been set. Repeat the same procedure for setting other required parameters (P.14).

▶ **Enabling the communication settings**

Power OFF and ON the inverter after all the communication parameters are set.

Check that the NET LED is ON and the NET operation mode is enabled.

> **Point** Power OFF and ON the inverter every time after the initial setting of each parameter is completed. After the setting values of the communication parameters are changed, reset the inverter to reflect new values. ➡ P.17

2.4 Inverter Reset

To reset the inverter, turn OFF the power, and then ON again after the LEDs on the operation panel turn OFF. The inverter will restart about 1 second after reset.

Turn OFF the power, and then ON again after the LEDs on the operation panel turn OFF.

ON

OFF
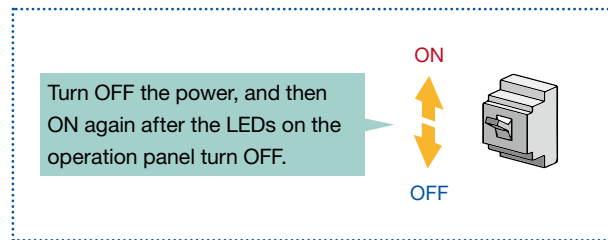
*: Note that the internal thermal integrated value of the electronic thermal relay function and the number of retries are cleared (erased) by resetting the inverter.

> **Point**
> - Make sure to turn OFF the start signal before resetting an inverter fault. Resetting the inverter fault with the start signal ON restarts the motor suddenly.
> - The inverter reset can be executed in the program. ➡ P.20

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Connect the personal computer to the programmable controller, and write the necessary parameters to the programmable controller.

Ethernet cable
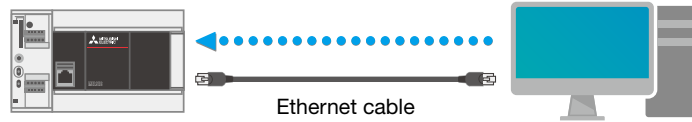
*: Parameters can be set regardless of the inverter connection status.

3.1 Parameter Settings Using GX Works3 (Required Settings)

1 Start GX Works3.

2 Select [Project] ➡ [New].
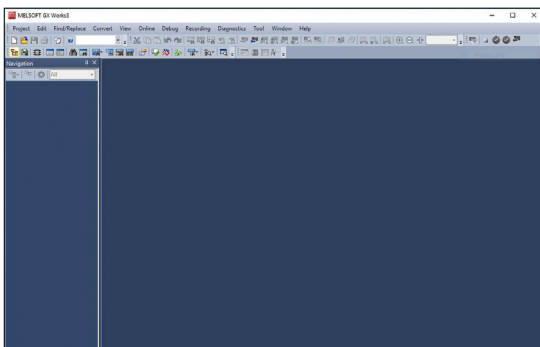
3 On the displayed window, set the following, and click the OK button.

New	
Series	FX5CPU
Type	FX5U
Mode	
Program Language	Ladder

OK   Cancel
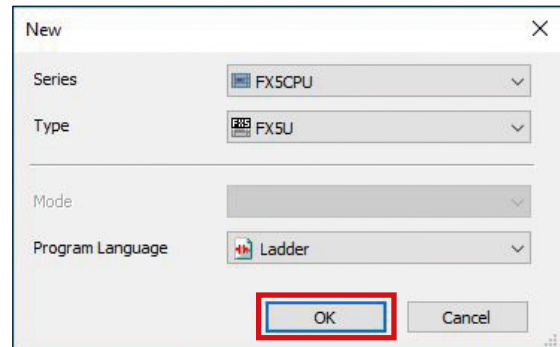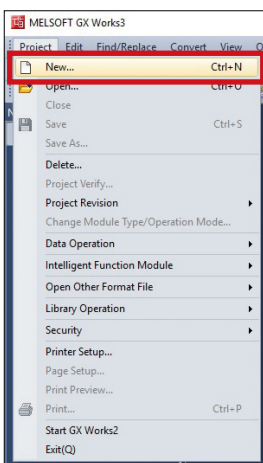
4 In the "Navigation" window, select [Parameter] ➡ [FX5UCPU] ➡ [Module Parameter] ➡ [485 Serial Port].
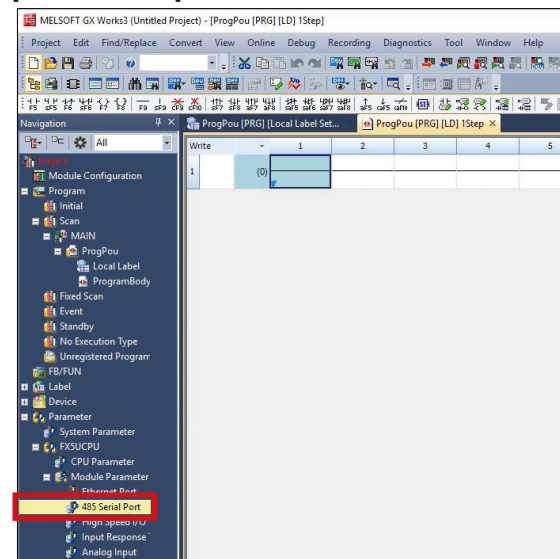
3. PROGRAMMABLE CONTROLLER SETTINGS

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5 Select [Inverter Communication] for the communication protocol type to display the following window.
In the "Advanced Settings" field, set parameters for the inverter.

▶ Basic settings

Item	Setting
⊟ **Communication Protocol Type**	**Set communication protocol type.**
Communication Protocol Type	Inverter Communication
⊟ **Advanced Settings**	**Set detailed setting.**
Data Length	7bit
Parity Bit	Even
Stop Bit	1bit
Baud Rate	19,200bps

📍 **Point**   Set the same parameters for the programmable controller and inverters.

▶ Basic settings

Item	
⊟ Communication Protocol Type	Set communication protocol type.
Communication Protocol Type	Inverter Communication
⊟ Advanced Settings	Set detailed setting.
Data Length	7bit
Parity Bit	Even
Stop Bit	1bit
Baud Rate	19,200bps

Parameter No.	Parameter item	Description	Setting value
Pr.118	PU communication speed	19200 bps	192
Pr.119	PU communication stop bit length	Data length: 7 bits Stop bit: 1 bit	10
Pr.120	PU communication parity check	Even	2

Programmable controller   Inverter
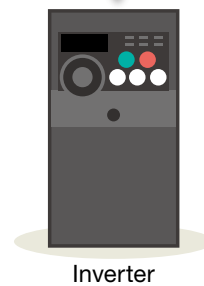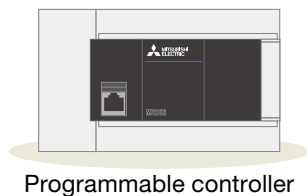
6 After the parameters are set, click the Apply button.
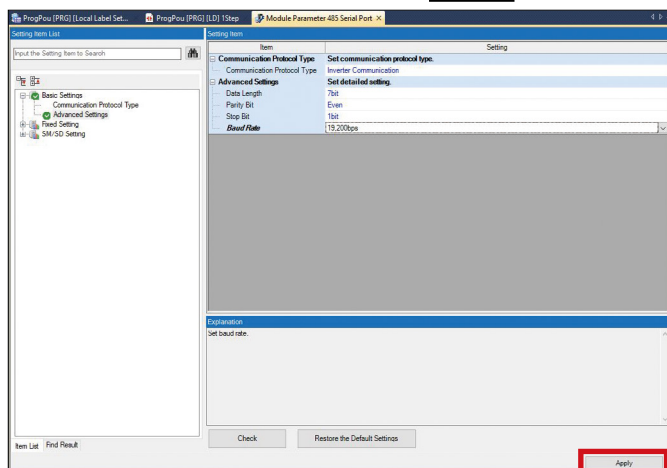
*: In this manual, the parameters set above are written to the programmable controller together with communication test programs, which will be created in the next section.

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| Parameter Settings | Communication Test Programs | Communication Settings | Writing Data to the Programmable Controller |

3.2 Communication Test Programs

These programs reset both inverters by sending the inverter reset command and confirm the following conditions.

- The system has been properly wired.
- The parameters of the programmable controller and inverters have been properly set.

▶ **Inverter reset circuit of the first inverter (station number 0)**

```
  SM402
───┤├──────────────────────────────────────────────[ SET │ M0  ]

   M0
───┤├──────┬──────[ IVDR │ K0 │ H0FD │ H9696 │ K1 │ M1 ]──  Inverter reset
           │
           ├──────[ IVDR │ K0 │ H0FB │ H0 │ K1 │ M4 ]──  Set the network operation
           │                                              mode to the operation mode.
   SM8029  │
────┤├─────┴──────────────────────────────[ RST │ M0 ]
```

▶ **Inverter reset circuit of the second inverter (station number 1)**

```
  SM402
───┤├──────────────────────────────────────────────[ SET │ M120 ]

   M120
───┤├──────┬──────[ IVDR │ K1 │ H0FD │ H9696 │ K1 │ M121 ]──  Inverter reset
           │
           ├──────[ IVDR │ K1 │ H0FB │ H0 │ K1 │ M124 ]──  Set the network operation
           │                                                mode to the operation mode.
   SM8029  │
────┤├─────┴──────────────────────────────[ RST │ M120 ]
```

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Connect the personal computer to the programmable controller.
Perform the communication test before writing the parameters and programs to the programmable controller.

▶ **System configuration example**

Direct connection to the Ethernet ports

Ethernet port

Ethernet cable

Built-in Ethernet port
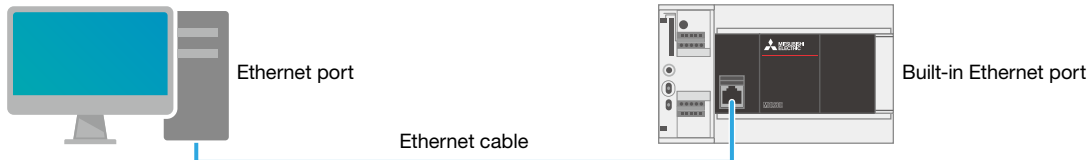
3.3 Communication Settings Using GX Works3

▶ **Communication test procedure**

1 Select [Online] ➡ [Current Connection Destination].
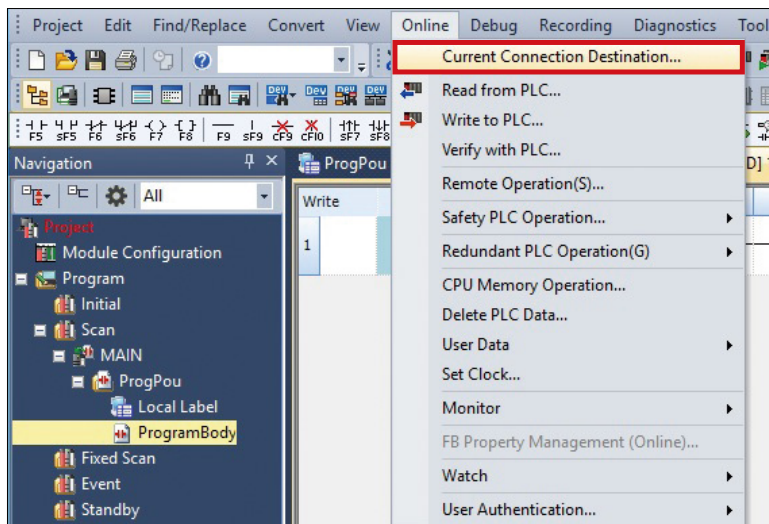
2 Select a connection method.
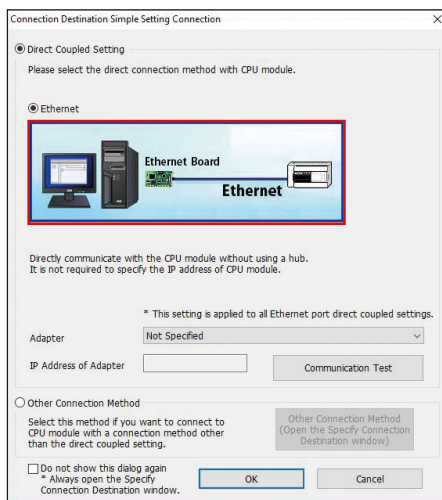
3. PROGRAMMABLE CONTROLLER SETTINGS

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3 An Ethernet adapter of the personal computer, which is used when the programmable controller is directly connected to an Ethernet port, can be specified.
When "Not Specified" is set in "Adapter", select an adapter to be used from the drop-down list.
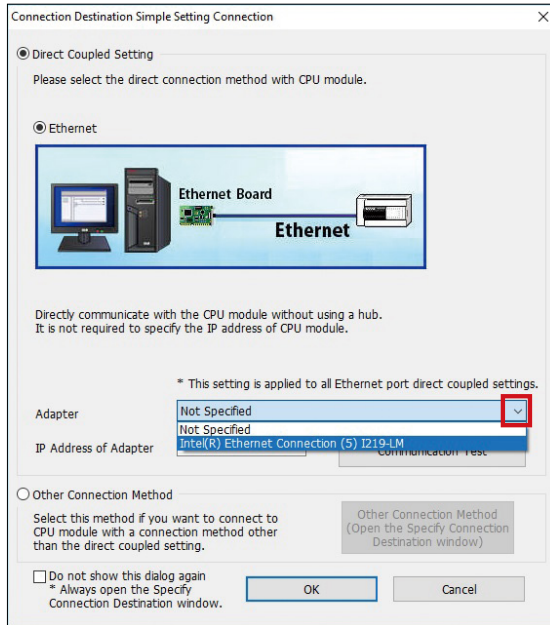
4 After the adapter is selected, click the [Communication Test] button.
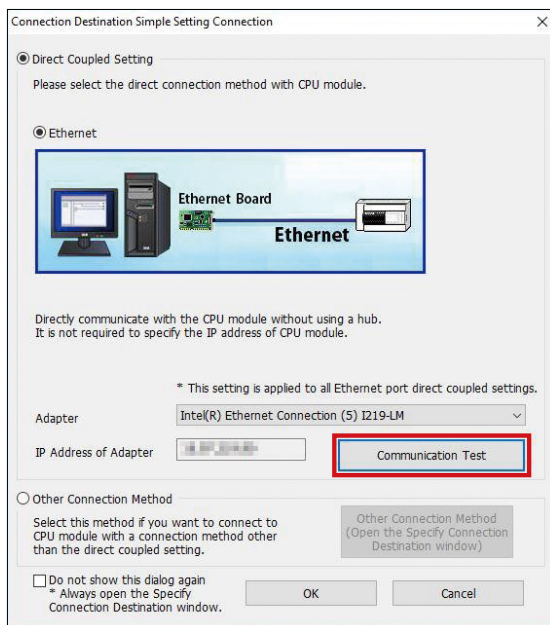
5 When the following window appears, click the ⬜ OK ⬜ button.
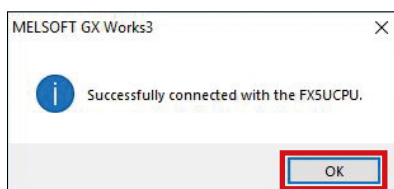
3.4 Writing Data to the Programmable Controller

The following procedure must be completed before the parameters and programs are written to the programmable controller.

1 Select [Convert] ➡ [Rebuild All].
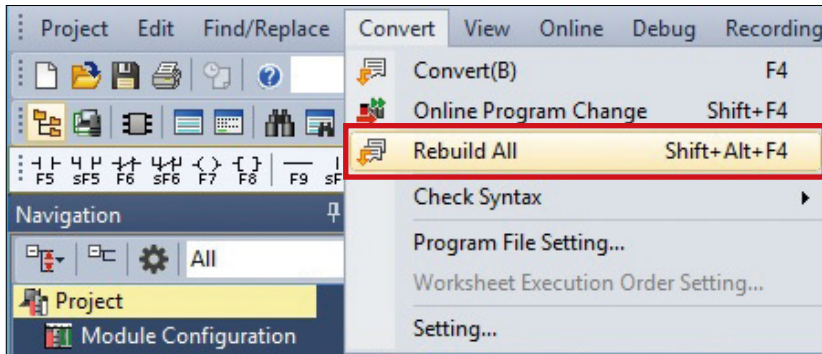
2 Click the OK button.
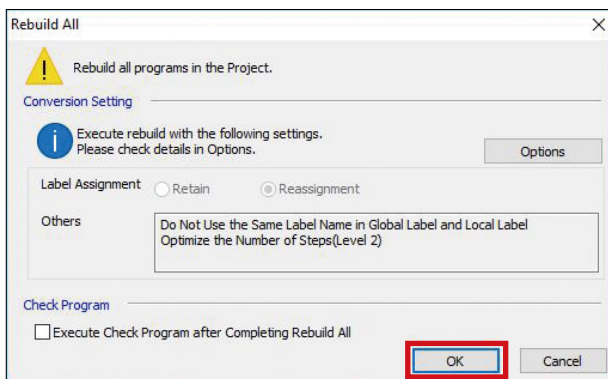
The programs are transferred to the programmable controller.

3 Select [Online] ➡ [Write to PLC].
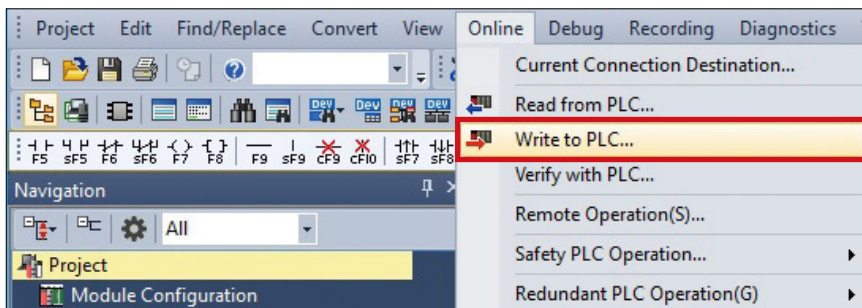
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3. PROGRAMMABLE CONTROLLER SETTINGS

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4 Click the [Parameter + Program] button, and click the [Execute] button.
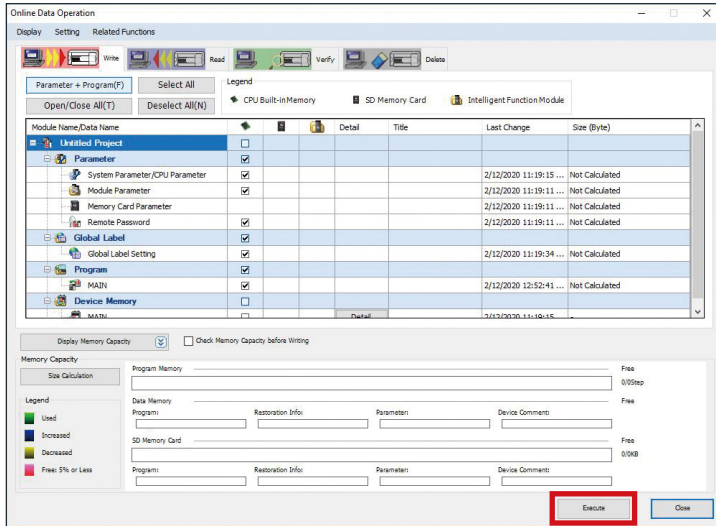
5 Click the [Yes] button.
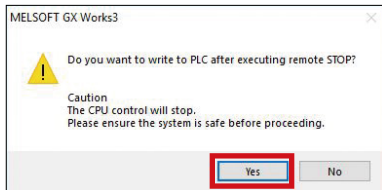
6 Click the [Yes to all] button.
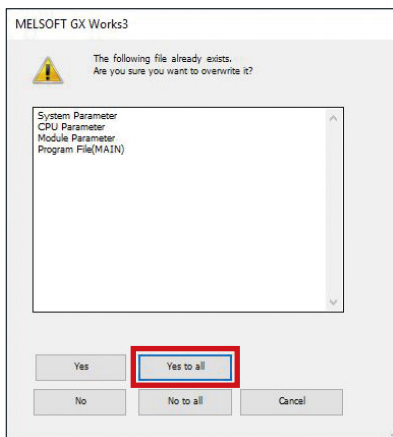
7 Click the [Yes] button.
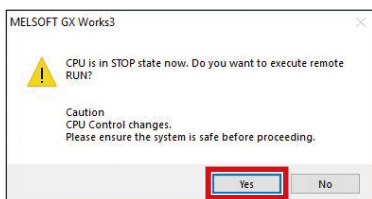
After the parameters and programs are written to the programmable controller, power OFF and ON the programmable controller (or reset the CPU module).

4. CHECKING COMMUNICATION STATUS

Connect the inverters to the programmable controller, and check the operation.
After the programmable controller is switched from STOP to RUN, it resets both inverters by sending the inverter reset command to these inverters.

Programmable controller
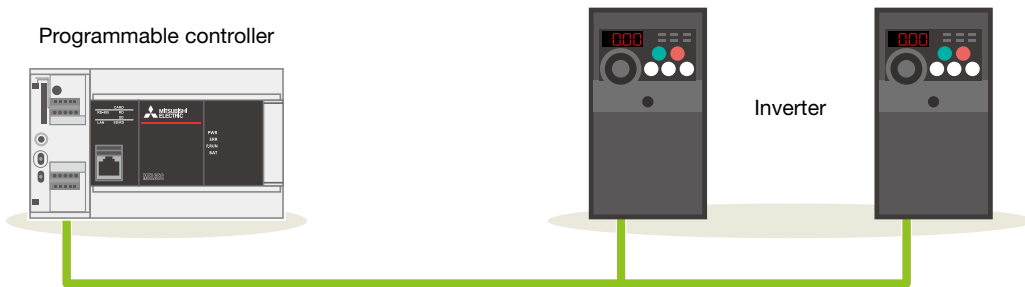
Inverter

*: Operations of the programmable controller and inverters can be checked regardless of the connection status of the personal computer.

▶ Normal operation

A successful inverter reset can be checked as follows.

| Checking with a sound | ➡ The inverters make a clicking sound. |

| Checking with 4-digit LED indication | ➡ The LEDs turn OFF for a moment. After the first inverter is reset, the second inverter will be reset. |

Reset start   Resetting   Reset complete
              ("Err." is displayed for a moment.)
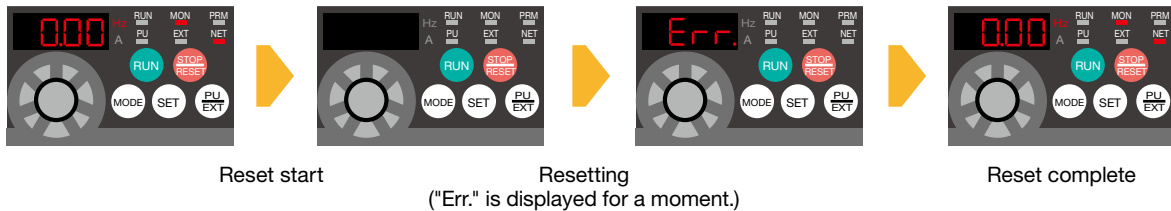
After checking the above, go to ➡ the next page.

▶ Faulty operation

If the programmable controller and the inverters are connected incorrectly or the parameters are set incorrectly, a faulty inverter reset can be checked as follows.

| Checking with a sound | ➡ The inverters make no sound. |

| Checking with 4-digit LED indication | ➡ The LEDs remain the same. |

Check the wiring and the parameter settings.

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5. EXAMPLE PROGRAMS

Operation   Operation Check

5.1 Operation

This section describes the program used for operation stop (X0), forward rotation (X1), and reverse rotation (X2) to control operations of the station number 0 (first inverter).
The frequency setting can be changed by changing the value set in D11.

1) Setting a running frequency

Programmable controller STOP
↓
RUN

Frequency setting (initial value) — D11=6000 (60 Hz)

Frequency change — No

Yes

M5 ON
D11=4000(40 Hz)
M5 OFF
D11=6000(60 Hz)

M6 ON
D11=2000(20 Hz)
M6 OFF
D11=6000(60 Hz)

2) Switching between forward and reverse rotation or stopping the operation

Operation selection

Reverse rotation

Forward rotation

X1 ON
Forward rotation

X2 ON
Reverse rotation

X0 ON
Stop
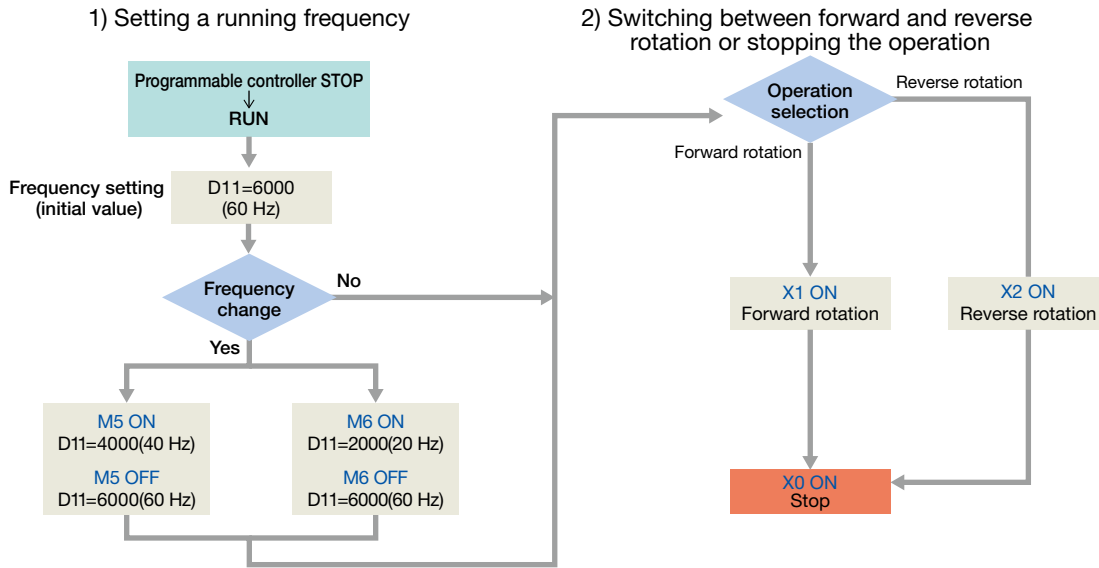
▶ Inverter operation control

The following example program use the IVMC instruction.
The IVMC instruction simplifies the programs and reduces communication time.

	(s1)	(s2)	(s3)	(d1)	(n)	(d2)
IVMC	K0	H0000	D10	D20	K1	M200

The programmable controller starts communicating with the inverters when the precondition turns ON.

Inverter station number

When H0000 is specified

(s3) : Operation command (extended)
(s3)+1 : Set frequency (RAM)
(d1) : Inverter status monitor (extended)
(d1)+1 : Output frequency (rotation speed)

Outputting instruction execution status (3 points are occupied.)

During instruction execution : M200 is ON.
When instruction is completed normally : M201 turns ON.
When instruction ends in error : M202 turns ON.

Communication channel

Inverter status read

Write

D10: Operation command (extended)

D11: Set frequency (RAM)

D20: Information on inverter status monitor (extended)

M100 to M115	M100	Inverter running
	M101	Forward rotation
	M102	Reverse rotation
	⋮	
	M115	Alarm occurrence

The information on inverter status read through communication is stored to M devices.

D21: Output frequency (rotation speed) monitor value → D50

The output frequency is transferred to another data register.

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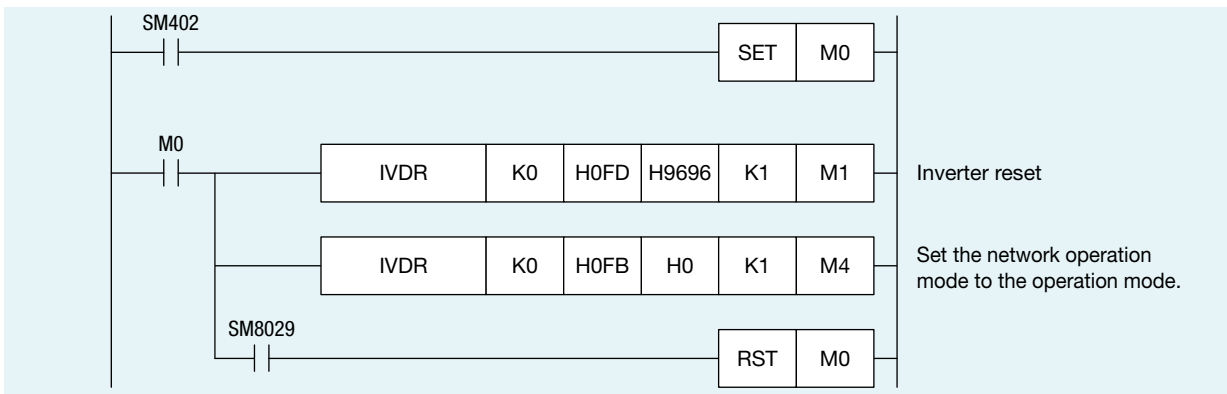APPENDIX

5.1.1 Example programs
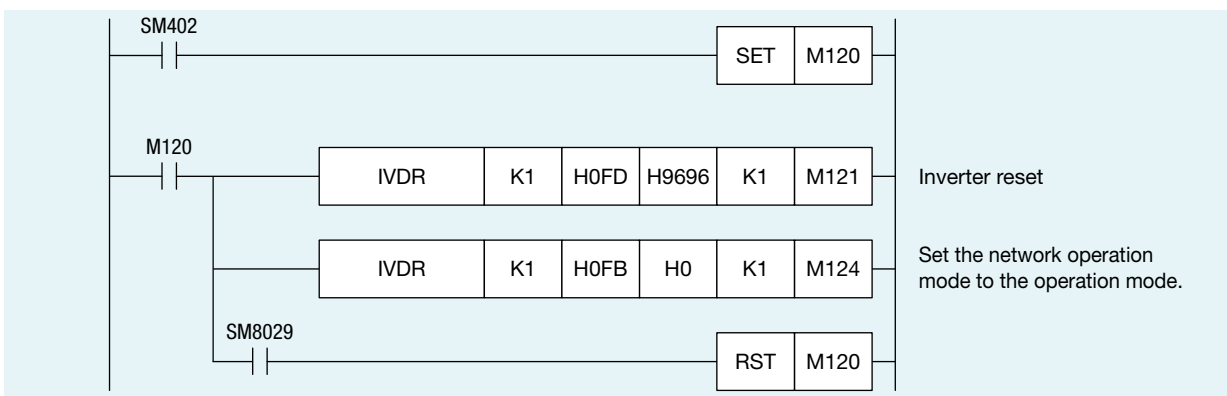
This program is used for operation stop (X0), forward rotation (X1), and reverse rotation (X2) to control operations of the inverter. The frequency setting can be changed by changing the value set in D11.

▶ **Ladder diagram for the station number 0 (first inverter)**

Frequency switching

RUN monitor SM400 | Switch command (Speed 1) M5 | Switch command (Speed 2) M6 | MOVP | K6000 | D11 | Initial value at start-up: 60 Hz

Switch command (Speed 1) M5 | Switch command (Speed 2) M6 | MOVP | K4000 | D11 | Operation speed: 40 Hz

Switch command (Speed 1) M5 | Switch command (Speed 2) M6 | MOVP | K2000 | D11 | Operation speed: 20 Hz

When the operation speed is set to D11, it is stored in (s3) + 1 of the IVMC instruction as the data to be written to the inverter.

Operation stop / cancel

Operation stop command X0 | SET | M15 | Operation stop (HF9 b1 and b2: OFF)

Forward rotation command X1 | Operation stop command X0 | RST | M15 | Operation stop cancel (HF9 b1 or b2: ON)

Reverse rotation command X2

Forward/reverse rotation switching

Operation stop M15 | Forward rotation command X1 | Reverse rotation command X2 | (M21) | Forward rotation command (HF9 b1: ON)

Reverse rotation command X2 | Forward rotation command X1 | (M22) | Reverse rotation command (HF9 b2: ON)

Information on the forward/reverse rotation command is transferred to D10 using the MOV instruction. The information in D10 is stored in (s3) of the IVMC instruction as the data to be written to the inverter.

Inverter operation control and status check

RUN monitor SM400 | MOV | K4M20 | D10 | Operation command write

(s1) (s2) (s3) (d1) (n) (d2)
IVMC | K0 | H0000 | D10 | D20 | K1 | M200

The set frequency (RAM) and operation command (extended) are written. The inverter status (extended) and output frequency (rotation speed) are read.

Head bit device number for instruction execution status output (M200 to M202 are occupied.)

Communication channel: 1

Head device for storing read values (D20 and D21 are occupied.)

Head device for writing data (D10 and D11 are occupied.)

Send/receive data type specification

Inverter station number: 0

Operation command

MOV | D20 | K4M100 | Inverter status information read to D20 using the IVMC instruction → The information is stored to M100 to M115 using the MOV instruction.

Inverter running M100 | (Y0)

Forward rotation M101 | (Y1)

Reverse rotation M102 | (Y2)

Status details (as needed)

Alarm occurrence M115 | (Y3)

Status check

MOV | D21 | D50 | Output frequency (rotation speed) monitor value → Transferred to D50.

Output frequency check

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5. EXAMPLE PROGRAMS

Operation | Operation Check

This program is used for operation stop (X10), forward rotation (X11), and reverse rotation (X12) to control operations of the inverter. The frequency setting can be changed by changing a value set in D31.

▶ **Ladder diagram for the station number 1 (second inverter)**

Frequency switching

RUN monitor SM400 — Switch command (Speed 1) M7 — Switch command (Speed 2) M8 — MOVP | K6000 | D31 — Initial value at start-up: 60 Hz

Switch command (Speed 1) M7 — Switch command (Speed 2) M8 — MOVP | K4000 | D31 — Operation speed: 40 Hz

Switch command (Speed 1) M7 — Switch command (Speed 2) M8 — MOVP | K2000 | D31 — Operation speed: 20 Hz

When the operation speed is set to D31, it is stored in (s3)+1 of the IVMC instruction as the data to be written to an inverter.

Operation stop / cancel
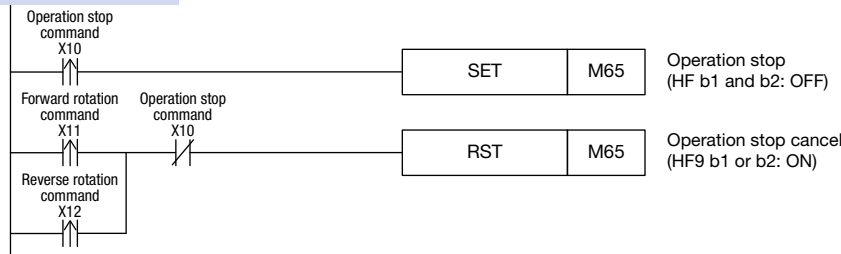
Operation stop command X10 — SET | M65 — Operation stop (HF b1 and b2: OFF)

Forward rotation command X11 — Operation stop command X10 — RST | M65 — Operation stop cancel (HF9 b1 or b2: ON)

Reverse rotation command X12

Forward/reverse rotation switching

Operation stop M65 — Forward rotation command X11 — Reverse rotation command X12 — (M41) — Forward rotation command (HF9 b1: ON)

Reverse rotation command X12 — Forward rotation command X11 — (M42) — Reverse rotation command (HF9 b2: ON)

Information on the forward and reverse rotation commands is transferred to D30 using the MOV instruction. The information in D30 is stored in (s3) of the IVMC instruction as the data to be written to an inverter.

Inverter operation control and status check
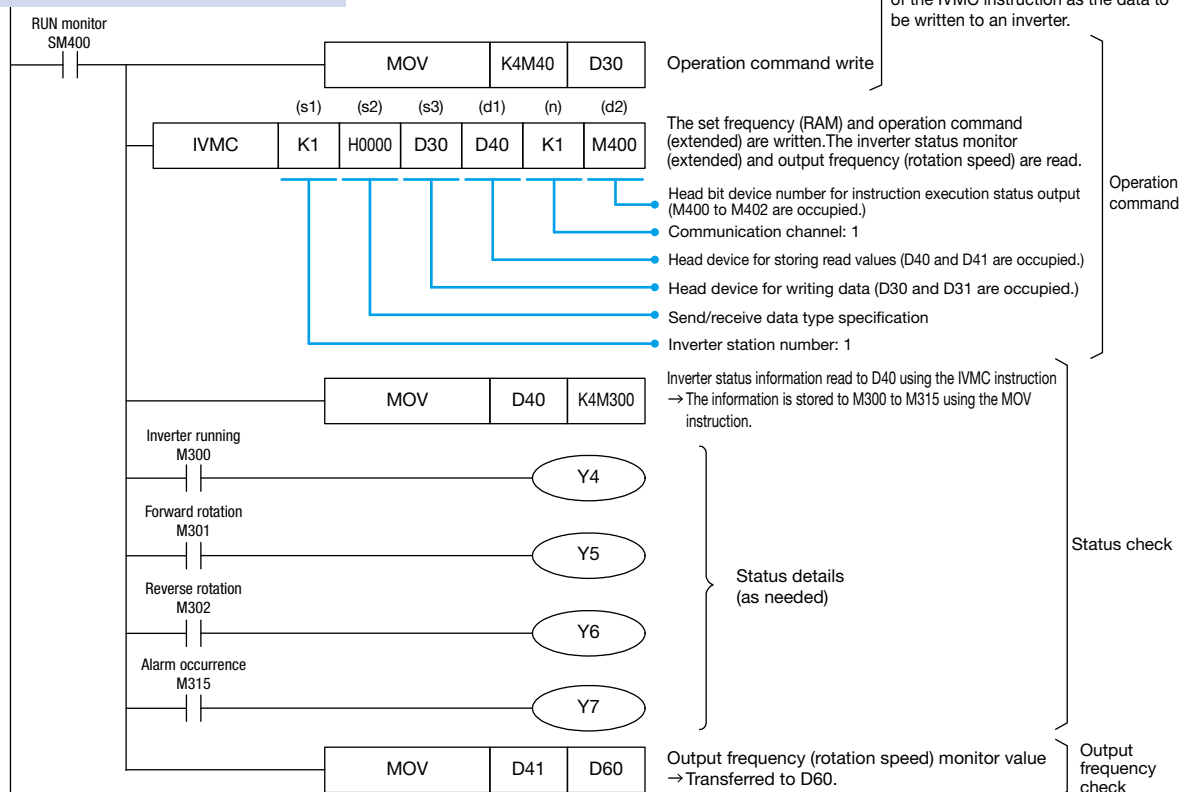
RUN monitor SM400 — MOV | K4M40 | D30 — Operation command write

(s1) (s2) (s3) (d1) (n) (d2)
IVMC | K1 | H0000 | D30 | D40 | K1 | M400

The set frequency (RAM) and operation command (extended) are written. The inverter status monitor (extended) and output frequency (rotation speed) are read.

- Head bit device number for instruction execution status output (M400 to M402 are occupied.)
- Communication channel: 1
- Head device for storing read values (D40 and D41 are occupied.)
- Head device for writing data (D30 and D31 are occupied.)
- Send/receive data type specification
- Inverter station number: 1

Operation command

MOV | D40 | K4M300 — Inverter status information read to D40 using the IVMC instruction → The information is stored to M300 to M315 using the MOV instruction.

Inverter running M300 — (Y4)

Forward rotation M301 — (Y5)

Reverse rotation M302 — (Y6)

Status details (as needed)

Alarm occurrence M315 — (Y7)

Status check

MOV | D41 | D60 — Output frequency (rotation speed) monitor value → Transferred to D60.

Output frequency check

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Operation | Operation Check

5.2 Operation Check

Write the programs and parameters by following the procedure described in Section 3.4 (Page 23) and check that the programmable controller and inverters communicate data without an error.

Change the programmable controller state from STOP to RUN and check the following.

▶ Turning ON the forward rotation command input

Programmable controller

Station number 0: Turn ON X1 (Forward rotation command).
Station number 1: Turn ON X11(Forward rotation command).

Programmable controller operation

Station number 0
The output display LEDs, Y0 (Inverter running) and Y1 (Forward rotation), are ON.

Station number 1
The output display LEDs, Y4 (Inverter running) and Y5 (Forward rotation), are ON.

Inverter operation

The 4-digit LED display changes from 0.00 to 60.00 (initial value) sequentially.

<Checking communication status with LEDs>

RS-485 SD and RD LEDs flash.

For the forward rotation at 60 Hz, "60.00" is displayed on the operation panel.

Inverter

Programmable controller

▶ Changing the frequency to 40 Hz (when the forward rotation command remains ON)

Programmable controller

Station number 0: Turn ON M5 (Switch command for speed 1).
Station number 1: Turn ON M7 (Switch command for speed 1).

Programmable controller operation

Station number 0
The output display LEDs, Y0 (Inverter running) and Y1 (Forward rotation), are ON.

Station number 1
The output display LEDs, Y4 (Inverter running) and Y5 (Forward rotation), are ON.

Inverter operation

The 4-digit LED display changes from 0.00 to 60.00 (initial value) sequentially.

<Checking communication status with LEDs>
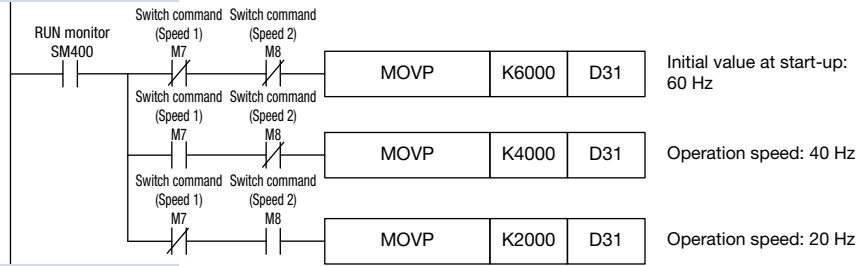
Flashing

Programmable controller

Inverter

LED status of the programmable controller (RS-485)		Operating status
RD	SD	
Flashing	Flashing	Data is being sent and received from/to the inverters.

When the above operation cannot be observed, refer to ➡ P.30.

Point

When changing a frequency, a switch command, such as M5 and M7, can be turned ON forcibly by following the procedure below.
1) Make sure that the ladder diagram is displayed on GX Works3, and press the [F3] key. (The status changes to monitoring.)
2) Place a cursor on the device, such as M5 and M7, to be turned ON.
3) Hold down the [Shift] key and press the [Enter] key to turn ON. (Hold down the [Shift] key and press the [Enter] key again to turn OFF.)
Press the [F2] key to clear the monitor execution status.

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Checking Procedure | Checking the LED Status | Checking the Error Code

6.1 Checking Procedure

1 Checking the LED status ➡ P.31

If data communications between the programmable controller and the inverters are not performed as described on Page 29, check the communication status with the LEDs of the programmable controller.

2 Checking the error code ➡ P.32 to P.34

Check the following depending on the error code stored in the programmable controller.

Wiring ➡ P.8

- Are the cables properly connected?
- Are the LAN connectors fully plugged?

SG SDB SDA RDB RDA

Set the terminating resistor selector switch to the 110 Ω position.

1) Orange and white
2) Orange
3) Green and white
4) Blue
5) Blue and white
6) Green
7) Brown and white
8) Brown

3) Green and white
6) Green

Programmable controller

Terminal block

(Brown, Black, Brown, Gold)
Terminating resistor 100 Ω, 1/2 W
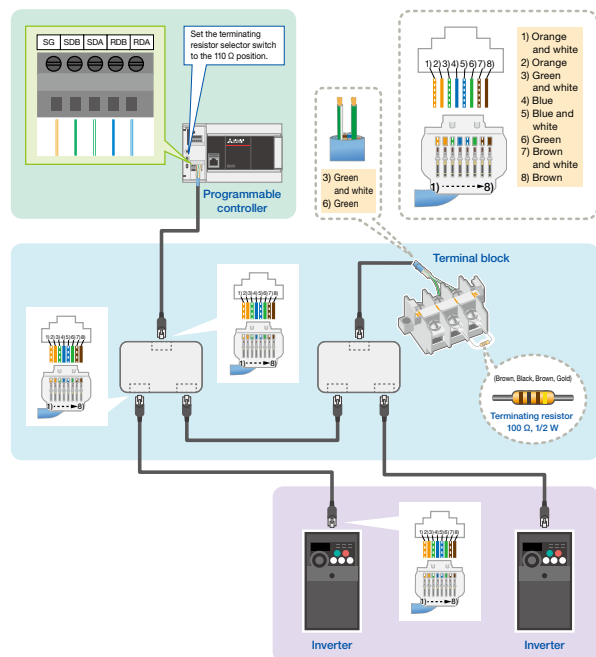
Inverter   Inverter

Communication settings ➡ P.14 to P.19

- Do the parameters set using GX Works3 and the parameters written to the inverters match?

▶ Basic settings

Programmable controller

*: If any parameter is set incorrectly, correct the value. Then, power OFF and ON the programmable controller (or reset the CPU module) to reflect the corrected value.

Inverter

*: If any parameter is set incorrectly, correct the value. Then, power OFF and ON the inverter to reflect the corrected value.
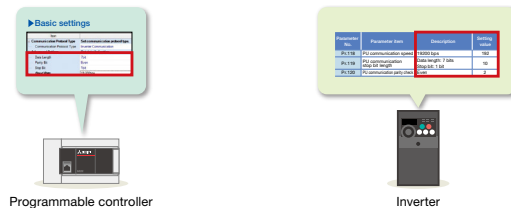
Programs ➡ P.27 to P.29

- Are the programs created as shown in the example programs?

Frequency switching

RUN monitor SM400 Switch command (Speed 1) Switch command (Speed 2) MOVP K6000 D11 Initial value at start-up: 60 Hz

Switch command (Speed 1) Switch command (Speed 2) MOVP K4000 D11 Operation speed: 40 Hz

Switch command (Speed 1) Switch command (Speed 2) MOVP K2000 D11 Operation speed: 20 Hz

When the operation speed is set to D11, it is stored in (s3) + 1 of the IVMC instruction as the data to be written to an inverter.
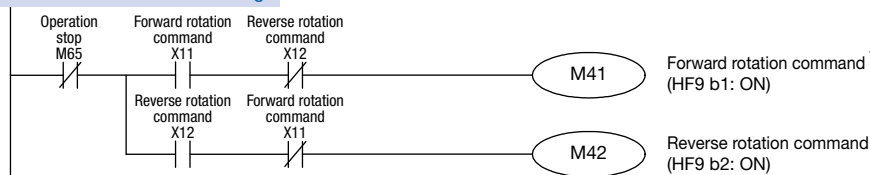
Operation stop / cancel

Operation stop command X0 SET M15 Operation stop (HF9 b1 and b2: OFF)

Forward rotation command X1 Operation stop command X0 RST M15 Operation stop cancel (HF9 b1 or b2: ON)

Reverse rotation command

6. TROUBLESHOOTING

6.2 Checking the LED Status

If data communications between the programmable controller and the inverter are not performed when the example program is executed, an error occurs.

▶ Turning ON the forward rotation command input

Programmable controller
Station number 0: Turn ON X1 (Forward rotation command). Station number 1: Turn ON X11 (Forward rotation command).

Programmable controller operation

- The ERR LED turns ON.

Station number 0
- The output display LEDs, Y0 (Inverter running) and Y1 (Forward rotation), turn OFF.
- Y3 (Alarm occurrence) turns ON.

Station number 1
- The output display LEDs, Y4 (Inverter running) and Y5 (Forward rotation), turn OFF.
- Y7 (Alarm occurrence) turns ON.

Inverter operation

- The LED indication (0.00) remains unchanged.
- The corresponding error code is displayed.

<Checking communication status with LEDs>

LED status of the programmable controller (RS-485)		Operating status
RD	**SD**	
ON	OFF	The programmable controller receives data but does not send data.
OFF	ON	The programmable controller sends data but does not receive data.
OFF	OFF	The programmable controller does not send and receive data.

When the programmable controller has one of the above errors, check the error code.
➡ To the next page
For details on the error codes displayed on the FR-D700, refer to
➡ Section 5.2 List of fault or alarm indications in the FR-D700 INSTRUCTION MANUAL (Applied) (IB(NA)-0600366ENG).

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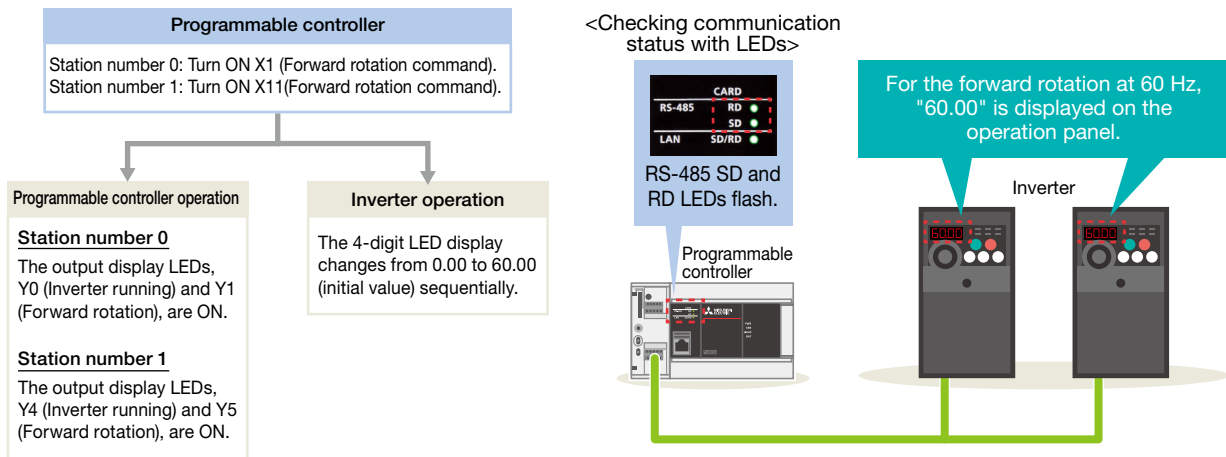
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Checking Procedure | Checking the LED Status | **Checking the Error Code**

6.3 Checking the Error Code

When an error occurs in serial communications, the corresponding error code is stored in the special register (SD8500). The error code can be checked with the following devices.

Device (CH1)	Name	Description
SM8500	Serial communication error (CH1)	Turns ON when an error occurs in serial communications.
SD8500	Serial communication error code (CH1)	When an error occurs in serial communications, stores the corresponding error code.

▶ **Monitoring SD8500**

1 Select [Online] ➡ [Watch] ➡ [Register to Watch Window] ➡ [Watch Window 1].
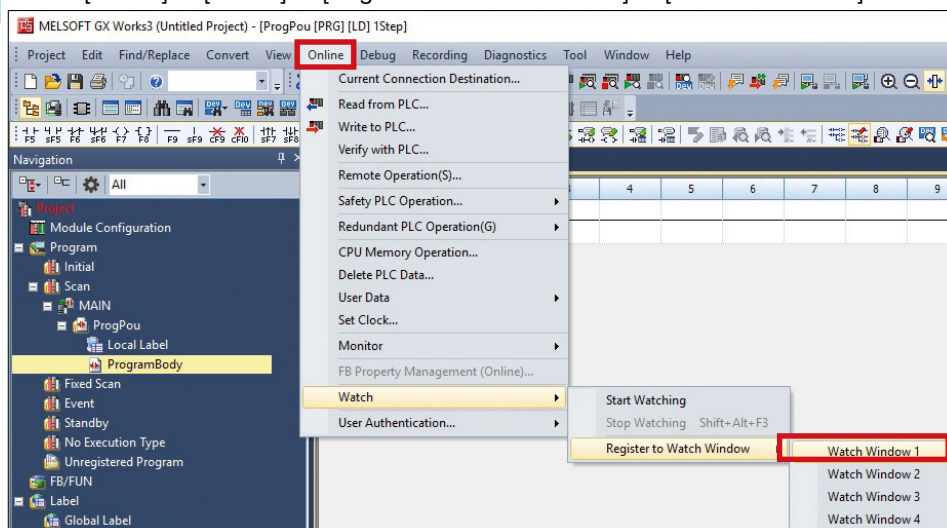
2 Enter "SD8500" in "Name", and select "Hexadecimal" in "Display Format". Right-click on "SD8500", and select [Start Watching].

An error code is displayed.

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Checking Procedure | Checking the LED Status | Checking the Error Code

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Error code (Hexadecimal)	Description		Cause and action	
			Programmable controller	Inverter
0000H	Normal end	(No Errors)	-	
7601H	-	No response from the inverter.	Check the wiring and parameter settings.	
7602H	Timeout error	Sending from inverter was aborted midway.	Check the wiring and parameter settings.	Check the wiring and existence of noise.
7603H	Station number error	An unspecified station gave response.	Check the parameter settings.	Check Pr.117 (PU communication station number) setting.
7604H	Sum check error	The sum of data sent back by the inverter did not match.	Check the parameter settings and operating environment (including existence of noise).	Check the parameter settings, wiring, and existence of noise.
7608H	Sending timeout error	Sending to the inverter was not completed within the specified time.		
7609H	Receive data error	Wrong data was received from the inverter.		
7620H	Computer NAK error	Inverter sent the error code H0. The number of retries exceeded the allowable number because of an error in the transfer request data.		
7621H	Parity error	Inverter sent the error code H1. The contents are different from the specified parity.	Check the parameter settings.	Check Pr.120 (PU communication parity check) setting.
7622H	Sum check error	Inverter sent the error code H2. The sum check code in the computer is different from the sum value calculated from the data received by the inverter.		Check the wiring and existence of noise.
7623H	Protocol error	Inverter sent the error code H3. There is a syntax error in data received by the inverter. Or, data reception is not completed within a certain amount of time. CR/LF does not match parameter setting.		
7624H	Framing error	Inverter sent the error code H4. The stop bit length is different from the initial set value.		
7625H	Overrun error	Inverter sent the error code H5. Before receiving the completed data in the inverter, the computer sent the next set of data.	Check the program.	-
7627H	Character error	Inverter sent the error code H7. An unused character (other than 0 to 9, A to F and control codes) was received.	Check the wiring, existence of noise, or other factors.	-
762AH	Mode error	Inverter sent the error code HA. A parameter was written in a mode other than computer link operation mode, or while the inverter was operating.	Check the program.	Check the operation mode and operation command source, such as Pr.77, Pr.79, and Pr.340, of the inverter.
762BH	Instruction code error	Inverter sent the error code HB. Non-existing instruction code was specified.		
762CH	Data range error	Inverter sent the error code HC. In writing a parameter or operation frequency, data outside the allowable range was specified.		-

The following table lists the error codes stored in SD8500.

For details on the error codes, refer to

➡ Section 5.9 Troubleshooting in the MELSEC iQ-F FX5 User's Manual (Serial Communication) (JY997D55901).

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The following table lists the error codes stored in SD8500 when an error occurs in the send data of the IVMC instruction.

| IVMC | (s1) | (s2) | (s3) Send data 1 | (d1) | (n) | (d2) |

(s3)+1 Send data 2

Error code (Hexadecimal)	Description		Cause and action	
	Send data 1 (s3)	Send data 2 (s3) + 1	Programmable controller	Inverter
7640H	• Mode error A parameter was written in a mode other than computer link operation mode or while inverter was operating.	Normal value	Check the program.	Check the parameter settings.
7641H	• Instruction code error Non-existing instruction code was specified.			-
7642H	• Data range error Data outside the allowable range was specified.			-
7643H	Normal value	• Mode error A parameter was written in a mode other than computer link operation mode or while inverter was operating.		Check the parameter settings.
7644H		• Instruction code error Non-existing instruction code was specified.		-
7645H		• Data range error Data outside the allowable range was specified.		-
7646H	Mode error	Mode error		Check the operation mode and operation command source, such as Pr.77, Pr.79, and Pr.340, of the inverter.
7647H	Mode error	Instruction code error		
7648H	Mode error	Data range error		
7649H	Instruction code error	Mode error		-
764AH	Instruction code error	Instruction code error		
764BH	Instruction code error	Data range error		
764CH	Data range error	Mode error		
764DH	Data range error	Instruction code error		
764EH	Data range error	Data range error		

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Inverter Communication Instructions

Programmable controller

[IVWR instruction]
Writes a parameter value, such as maximum frequency, to an inverter.

[IVRD instruction]
Reads a parameter value, such as minimum frequency, from an inverter.

[IVBWR instruction]
Writes multiple parameter values to an inverter at one time.

[IVMC instruction]
Writes two types of settings (operation command and set frequency) to an inverter, and reads two types of data (inverter status monitor, output frequency, etc.) from the inverter at the same time.

[IVDR instruction]
Writes a control value required for operation to an inverter.

[IVCK instruction]
Reads the operating status of an inverter, such as output frequency.

Inverter

Parameter

Pr.0: Torque boost

Pr.1 : Maximum frequency

Pr.2: Minimum frequency

Pr.3: Base frequency

Pr.4: Multi-speed setting
(high speed)

Pr.5: Multi-speed setting
(middle speed)

Pr.6: Multi-speed setting
(low speed)

Instruction code

Write area
HF0 : Multiple instructions
HFB: Operation mode
HFA: Operation command

Read area
H7B: Operation mode
H6F: Output frequency

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▶ Inverter operation monitoring instruction [IVCK]

This instruction reads the operating status of an inverter and stores the read value in (d1) when an instruction code set in the computer link operation of the inverter is specified.

| IVCK | (s1) | (s2) | (d1) | (n) | (d2) |
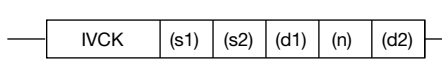
Example program

The following program reads the status (H7A) of the inverter (station number 0), stores the read value in M100 to M107 of the programmable controller, and outputs it externally.

RUN monitor SM400

| IVCK | K0 | H7A | K2M100 | K1 | M200 |

Inverter status monitor: M100 to M107

- Head bit device number for instruction execution status output
- Communication channel: K1 to K4
- Read value storage destination
- Inverter instruction code (hexadecimal)
- Inverter station number: 0 to 31

Inverter running M100 — Y0

Forward rotation M101 — Y1

Reverse rotation M102 — Y2

Alarm occurrence M107 — Y3

Status details (as needed)

Inverter instruction code (H7A)	[Example 1] H02: During forward rotation

b7 .... b0

| 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 |

Programmable controller internal devices K2M100 = M100 to M107	M107	M106	M105	M104	M103	M102	M101	M100

Programmable controller output devices	Y7	Y6	Y5	Y4	Y3	Y2	Y1	Y0

[Contents]
b0: RUN
b1: During forward rotation (fixed)
b2: During reverse rotation (fixed)
b3: SU (up-to-frequency) (fixed)
b4: OL (overload) (fixed)
b5: -
b6: FU (frequency detection) (fixed)
b7: ABC

*: Make sure not to use devices being used in other control operations.

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▶ Inverter operation control instruction [IVDR]

This instruction writes the value set in (s3) to a specified inverter parameter when an instruction code set in the computer link operation of the inverter is specified.

| IVDR | (s1) | (s2) | (s3) | (n) | (d) |
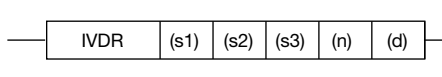
Example program

The following program switches the operation speed (HED) of the inverter (station number 0) using the switch command with 60 Hz as the initial value at start-up.

*: Make sure not to use devices being used in other control operations.

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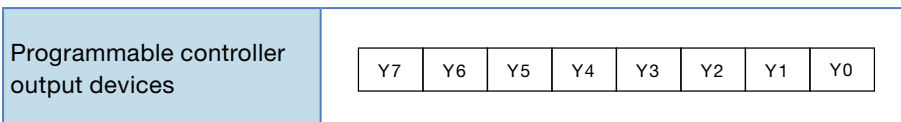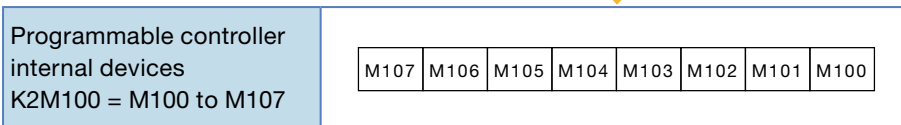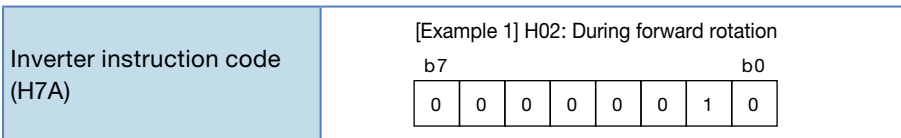
▶ Inverter parameter read [IVRD]

This instruction reads an inverter parameter value and stores the read value in (d1) when a parameter number is specified.

IVRD	(s1)	(s2)	(d1)	(n)	(d2)

Example program

The following program reads the maximum frequency (Pr.1) of the inverter (station number 0) and stores the read value in D100 of the programmable controller.

Reading contact X1 — SET M0

Command contact M0 — IVRD K0 K1 D100 K1 M200   Maximum frequency: D100
- Head bit device number for instruction execution status output
- Communication channel: K1 to K4
- Read value storage destination
- Inverter parameter number (decimal)
- Inverter station number: 0 to 31

Instruction execution completed flag SM8029 — RST M0
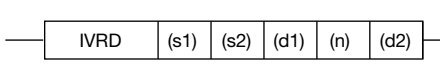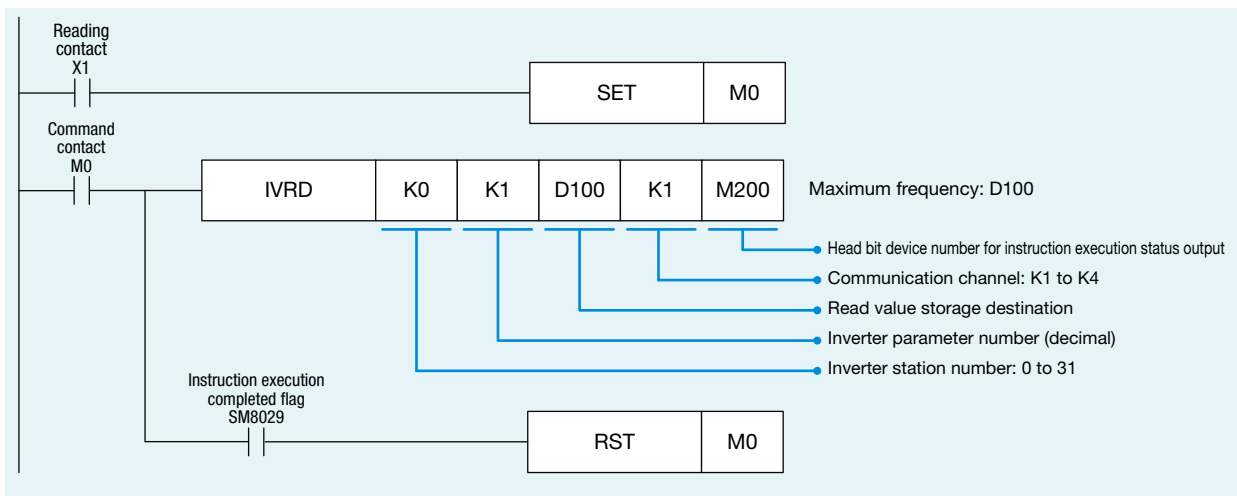
*: Make sure not to use devices being used in other control operations.

▶ Inverter parameter write [IVWR]

This instruction writes a value set in (s3) to a specified inverter parameter when a parameter number is specified.

IVWR	(s1)	(s2)	(s3)	(n)	(d)
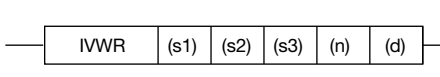
Example program

The following program writes 10 Hz as the setting value to the minimum frequency (Pr.2) of the inverter (station number 0).
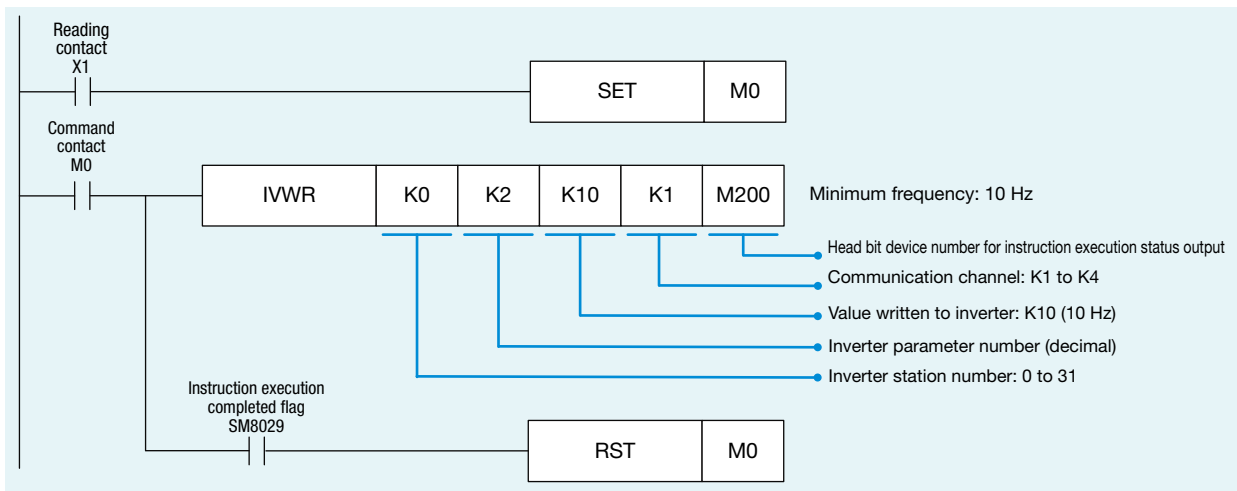
Reading contact X1 — SET M0

Command contact M0 — IVWR K0 K2 K10 K1 M200   Minimum frequency: 10 Hz
- Head bit device number for instruction execution status output
- Communication channel: K1 to K4
- Value written to inverter: K10 (10 Hz)
- Inverter parameter number (decimal)
- Inverter station number: 0 to 31

Instruction execution completed flag SM8029 — RST M0

*: Make sure not to use devices being used in other control operations.

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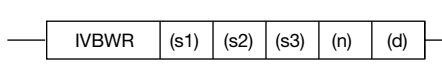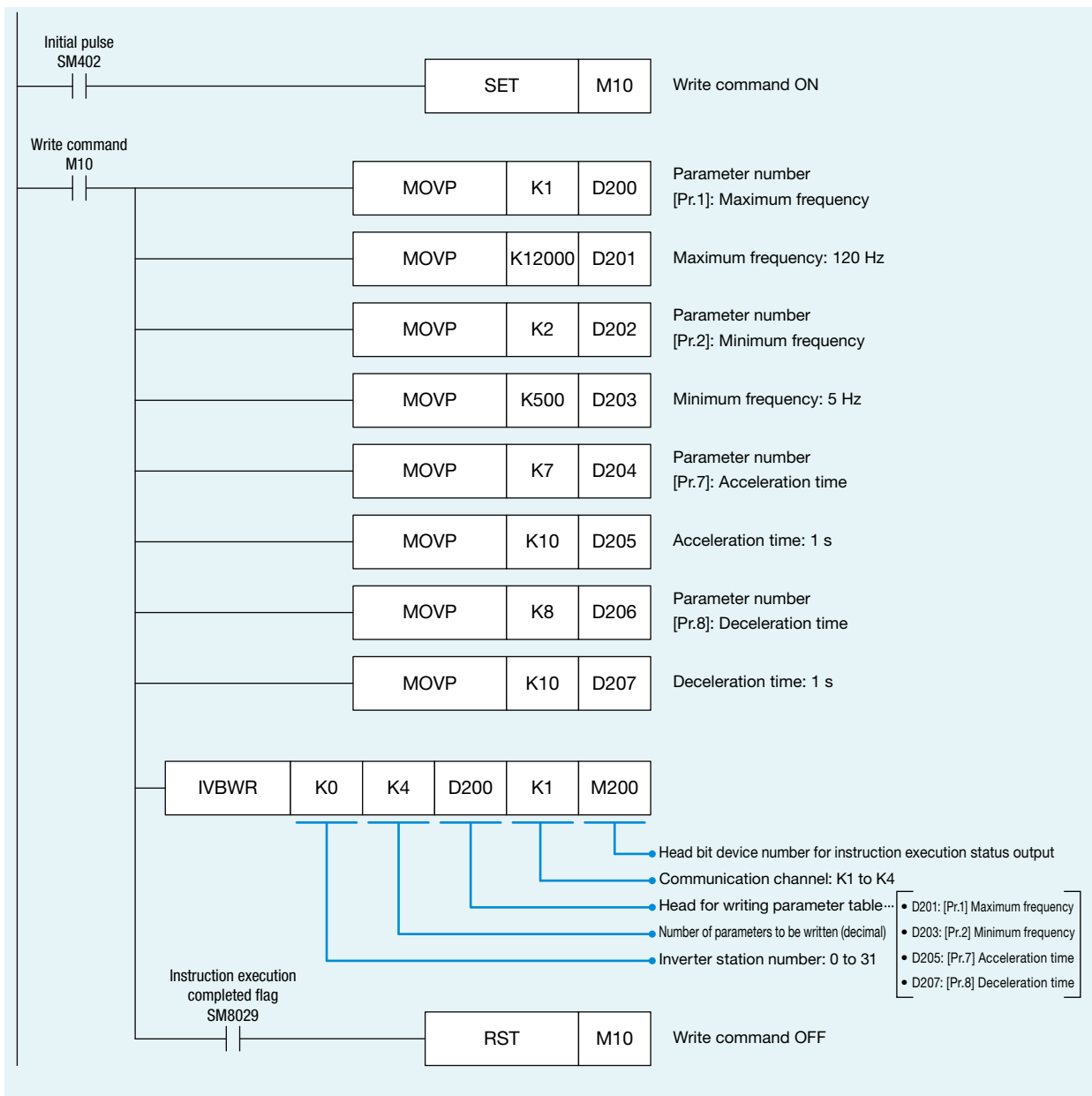Inverter Communication Instructions

▶ Inverter parameter block write [IVBWR]

This instruction writes the values set in (s3) to specified inverter parameters at one time when parameter numbers are specified.

```
──┤ IVBWR │ (s1) │ (s2) │ (s3) │ (n) │ (d) ├──
```

Example program

The following program writes the maximum frequency (Pr.1): 120 Hz, minimum frequency (Pr.2): 5 Hz, acceleration time (Pr.7): 1 s, and deceleration time (Pr.8): 1 s to the inverter (station number 0).

Initial pulse SM402			
──┤ ├──	SET	M10	Write command ON

Write command M10			
	MOVP	K1	D200	Parameter number [Pr.1]: Maximum frequency
	MOVP	K12000	D201	Maximum frequency: 120 Hz
	MOVP	K2	D202	Parameter number [Pr.2]: Minimum frequency
	MOVP	K500	D203	Minimum frequency: 5 Hz
	MOVP	K7	D204	Parameter number [Pr.7]: Acceleration time
	MOVP	K10	D205	Acceleration time: 1 s
	MOVP	K8	D206	Parameter number [Pr.8]: Deceleration time
	MOVP	K10	D207	Deceleration time: 1 s

IVBWR	K0	K4	D200	K1	M200

- Head bit device number for instruction execution status output
- Communication channel: K1 to K4
- Head for writing parameter table···
  - D201: [Pr.1] Maximum frequency
  - D203: [Pr.2] Minimum frequency
  - D205: [Pr.7] Acceleration time
  - D207: [Pr.8] Deceleration time
- Number of parameters to be written (decimal)
- Inverter station number: 0 to 31

Instruction execution completed flag SM8029			
──┤ ├──	RST	M10	Write command OFF

*: Make sure not to use devices being used in other control operations.

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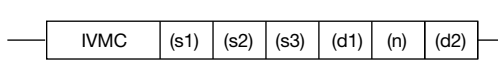COMMUNICATION STATUS

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APPENDIX

Inverter Communication
Instructions

▶ Multiple inverter commands [IVMC]

This instruction writes two types of settings (operation command and set frequency) to an inverter, and reads two types of data (inverter status monitor, output frequency, etc.) from the inverter at the same time.

| IVMC | (s1) | (s2) | (s3) | (d1) | (n) | (d2) |

Example program

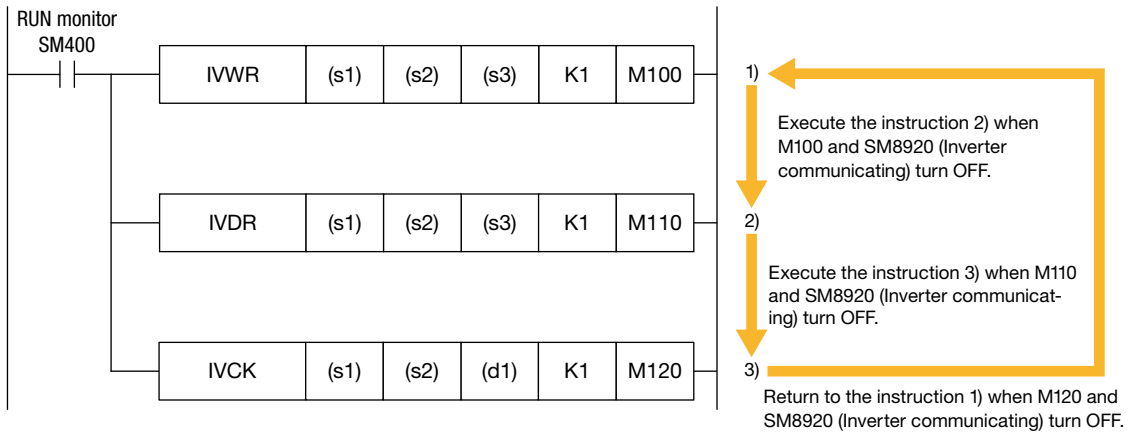Refer to ➡ P.27 (EXAMPLE PROGRAMS).

> ○ **Point**   (s3) and (d1) occupy two points each.

*: Make sure not to use devices being used in other control operations.

Others

▶ Simultaneous driving of instructions and communications

Two or more inverter communication instructions can be programmed, and driven at the same time.
When two or more instructions are driven at the same time for the serial port used for communications, the next inverter communication instruction in the program is executed after the current communications with the inverter have finished.

RUN monitor
SM400

| IVWR | (s1) | (s2) | (s3) | K1 | M100 |

1)

Execute the instruction 2) when M100 and SM8920 (Inverter communicating) turn OFF.

| IVDR | (s1) | (s2) | (s3) | K1 | M110 |

2)

Execute the instruction 3) when M110 and SM8920 (Inverter communicating) turn OFF.

| IVCK | (s1) | (s2) | (d1) | K1 | M120 |

3)

Return to the instruction 1) when M120 and SM8920 (Inverter communicating) turn OFF.

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▶ **MEMO**

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3 PROGRAMMABLE CONTROLLER SETTINGS

4 CHECKING COMMUNICATION STATUS

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▶ **MEMO**

1 PREPARATION

2 INVERTER SETTINGS

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WARRANTY

Please confirm the following product warranty details before using this product.

- WARRANTY in the FR-D700 INSTRUCTION MANUAL (Basic) (IB-0600438ENG)
- WARRANTY in the MELSEC iQ-F FX5U User's Manual (Hardware) (JY997D55301)
- WARRANTY in the MELSEC iQ-F FX5UC User's Manual (Hardware) (JY997D61401)

⚠ SAFETY PRECAUTIONS

- Before using the product introduced in this manual, please read the manuals for the product carefully to handle the product correctly.
- This product has been manufactured as a general-purpose part for general industries, and has not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the product for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, please contact Mitsubishi Electric sales office.
- The product has been manufactured under strict quality control. However when installing the product where major accidents or losses could occur if the product fails, install appropriate backup or failsafe functions into the system.
- For the design and wiring precautions, and other precautions, read "SAFETY PRECAUTIONS" in the relevant manuals.

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REVISIONS

*: The manual number is given on the bottom left of the back cover.

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Mitsubishi Electric Programmable Controller
MELSEC iQ-F Series

MITSUBISHI ELECTRIC CORPORATION