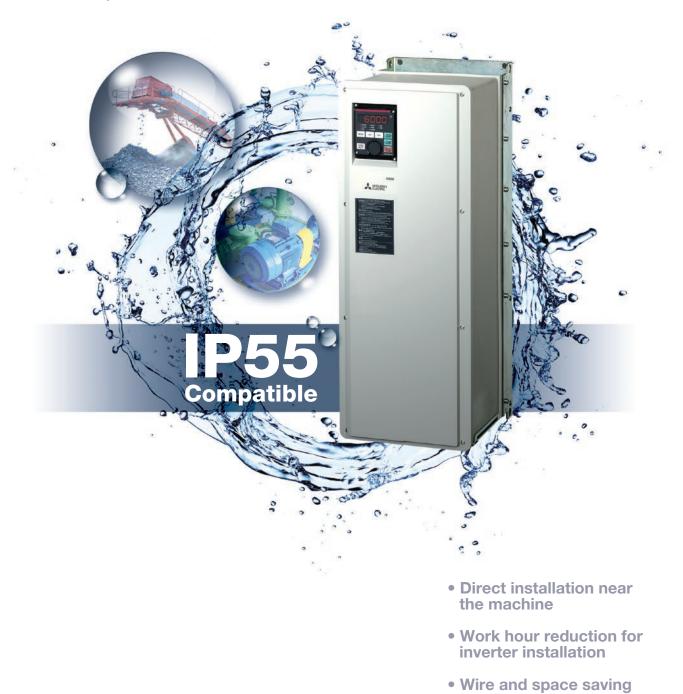


# FACTORY AUTOMATION

# INVERTER FR-A800

IP55 Compatible FR-A806



# GLOBAL IMPACT OF MITSUBISHI ELECTRIC



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future.

# Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better. Mitsubishi Electric is involved in many areas including the following

#### **Energy and Electric Systems**

A wide range of power and electrical products from generators to large-scale displays.

#### **Electronic Devices**

A wide portfolio of cutting-edge semiconductor devices for systems and products.

#### **Home Appliance**

Dependable consumer products like air conditioners and home entertainment systems.

#### Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

#### **Industrial Automation Systems**

Maximizing productivity and efficiency with cutting-edge automation technology.

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# **FR-A806 Inverter for Field Use**

The FR-A806 inverter has a highly protective structure with the IP55 rating, which enables installation near machines.

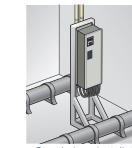
## Inverter for installation outside of the enclosure

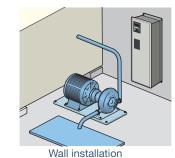
# 1. Direct installation near the machine

Since the inverter is compatible with hostile environments such as high humidity and dusty environments, you can easily install the inverter near the machine or in available spaces. By installing the inverter outside of the enclosure, the enclosure design becomes easier in terms of countermeasures against heat, and the enclosure is downsized as well.







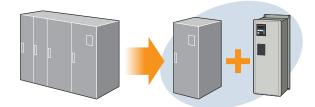


Installation on the side of the enclosure

Installation on the surface of the equipment

### **2.** Work hour reduction for inverter installation

There is no need to install more enclosures to use more inverters. The inverter can be installed easily without using an enclosure. At the time of the drive system upgrade by changing from the commercial power drive to the inverter drive, the inverter can be installed outside of the enclosure.

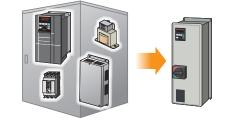


Stand-alone installation

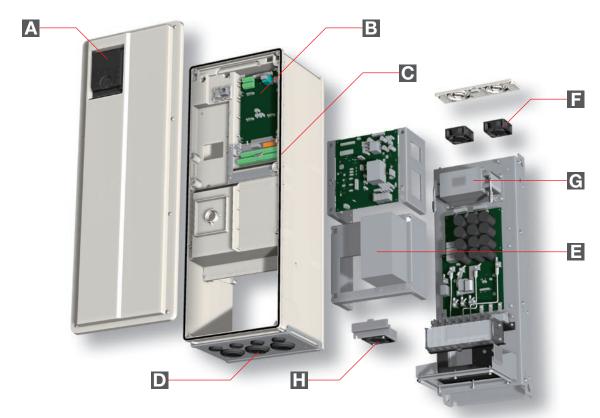
### 3. Wire and space saving

The inverter has a built-in DC reactor and EMC filter, requiring less wiring work for the peripheral devices.

The inverter with a built-in disconnecting switch<sup>\*1</sup> is also available. The remote switch enables turning ON/OFF of the input power when the power panel is located away from the inverter. \*1: For the details, please contact your sales representative.







Refer to page 22 for the details of main differences between the standard FR-A840 inverter and the IP55 compatible FR-A846 inverter.

## **Operation panel** (FR-DU08-01)

The FR-DU08-01 is compatible with the IP55 rating and detachable from the inverter. An optional LCD operation panel (FR-LU08-01) is available for replacement.

# Cable connection

To ensure compliance with the IP55 rating of the cable section, cable glands are available.



The inverter has a built-in DC reactor compatible with the EN 61000-3-2/12 standard.

# Circuit board coating

The coating conforms to IEC 60721-3-3 3C2/3S2 for improved environmental resistance.

## **EMC** filter

The inverter has a built-in filter for industrial environments (EN 61800-3 C3). A filter for residential environments (EN 61800-3 C2) is also available.

## Internal air circulation fan

The internal cooling fan (detachable) circulates air inside the inverter.



Reliable gasket sealing is provided.

# Waterproof fan

The cooling fan is compatible with the IP55 rating. It is detachable from the inverter without disconnecting the main circuit wiring. (The cooling fan is provided for the FR-A846-00250 or higher.)



# **Application examples**

The inverter is usable in many applications even where space is limited or in hostile environments.

### Waste transfer conveyor



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The inverter can be installed directly below the conveyor. The inverter is usable even where waste may fall off the line or water may splash.

## **PLC** function

When the signals from the object sensors are directly input to the inverter, whole control can be performed by the inverter only according to the operation of the peripherals.

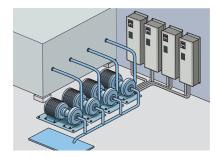
## **Building water pumps**

The inverter can be installed in a vacant space near the pump or in a narrow space. The inverter is usable even if water drops fall nearby.

### **PID** pre-charge function

This function is used to avoid rapid acceleration caused by starting the PID action while the pipe is empty, which prevents water hammer damage to pumps or other parts.





# Marine equipment

The FR-A846-C2 inverter is approved as compliant with ship classification standards, and usable in many applications on a ship. The inverter has a built-in EMC filter compliant with the ship classification standards.

|     | Certification body             |        | Certification body             |
|-----|--------------------------------|--------|--------------------------------|
| NK  | (Nippon Kaiji Kyokai)          | DNV GL | (DNV GL AS)                    |
| ABS | (American Bureau of Shipping)  | CCS    | (China Classification Society) |
| BV  | (Bureau Veritas)               | KR     | (Korean Register of Shipping)  |
| LR  | (Lloyd's Register of Shipping) |        |                                |



For details, refer to the Application Catalog for Ships (L(NA)06105ENG).

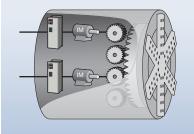
## Shield machine



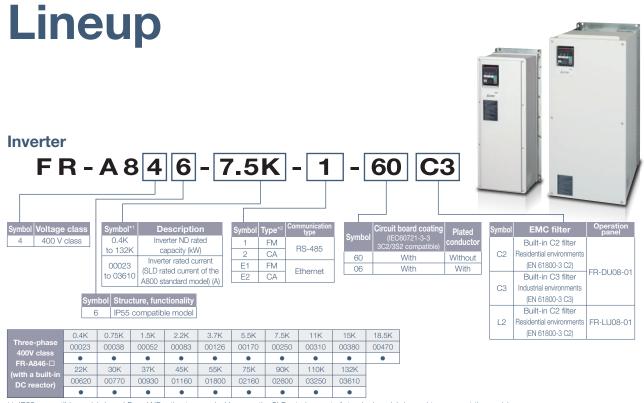
The inverter can be installed near the cooling pipe of the watercooled motor, minimizing the cable length between the inverter and the motor. The inverter is usable in dusty environments.

## **Real sensorless vector control**

The motor control without using an encoder improves reliability in an unfavorable operating environment, such as where vibrations exist.



### **Features**



\*1: IP55 compatible models have LD and ND rating types only. However, the SLD rated current of standard models is used to represent the model.

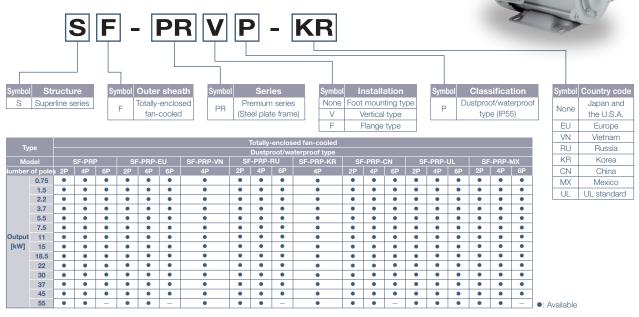
\*2: Specification differs by the type as follows.

|   | Туре                        | Monitor output                                     | Initial setting     |               |                 |                                    |  |  |
|---|-----------------------------|--|---------------------|---------------|-----------------|------------------------------------|--|--|
|   | туре                        |  | Built-in EMC filter | Control logic | Rated frequency | Pr.19 Base frequency voltage       |  |  |
|   | FM                          | Terminal FM (pulse train output)                   | OFF                 | Sink logic    | 60 Hz           | 9999                               |  |  |
| ( | terminal FM equipped model) | Terminal AM (analog voltage output (0 to ±10 VDC)) | OIT                 | On in logic   | 00112           | (same as the power supply voltage) |  |  |
|   | CA                          | Terminal CA (analog current output (0 to 20 mADC)) | ON                  | Source logic  | 50 Hz           | 8888                               |  |  |
| ( | terminal CA equipped model) | Terminal AM (analog voltage output (0 to ±10 VDC)) | ON                  | Source logic  | 30112           | (95% of the power supply voltage)  |  |  |

## Motor

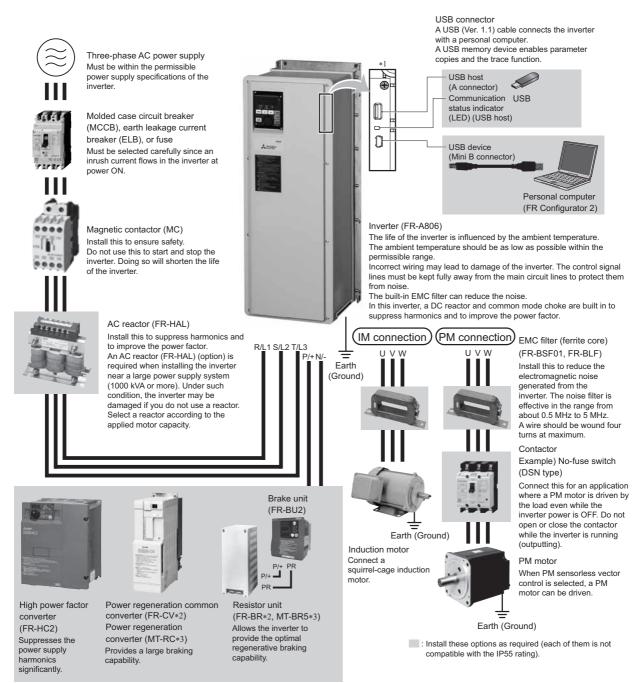
#### Premium efficiency dustproof/waterproof type motor SF-PRP

The motor is compliant with the dust test and water test specifications in JIS C 4034-5. The motor ensures reliability in environments exposed to plenty of water.



For the delivery time, please contact your sales representative.

# **Connection Example**



The figure shows the area when the front cover is removed. \*1

- Compatible with the FR-A846-01800(55K) or lower. Compatible with the FR-A846-02160(75K) or higher. \*2
- \*3

# **Standard Specifications**

## Rating

## 400 V class

|   |                                     |                               | 00023                                   | 00038                 | 00052   | 00083     | 00126    | 00170  | 00250    | 00310    | 00380    | 00470    | 00620  | 00770    | 00930 | 01160 | 01800 | 02160 | 02600 | 03250 | 03610 |
|---|-------------------------------------|-------------------------------|---|-----------------------|---------|-----------|----------|--------|----------|----------|----------|----------|--------|----------|-------|-------|-------|-------|-------|-------|-------|
|   | Model FR-A84                        | ю-[](- <b>⊏</b> )             | 0.4K                                    | 0.75K                 | 1.5K    | 2.2K      | 3.7K     | 5.5K   | 7.5K     | 11K      | 15K      | 18.5K    | 22K    | 30K      | 37K   | 45K   | 55K   | 75K   | 90K   | 110K  | 132K  |
| ۸   | unite a bla un atau                 | LD                            |   | 1.5                   | 2.2     | 3.7       | 5.5      | 7.5    | 11       | 15       | 18.5     | 22       | 30     | 37       | 45    | 55    | 75    | 90    | 110   | 132   | 160   |
|   |                                     | ND (initial setting)          | 0.4                                     | 0.75                  | 1.5     | 2.2       | 3.7      | 5.5    | 7.5      | 11       | 15       | 18.5     | 22     | 30       | 37    | 45    | 55    | 75    | 90    | 110   | 132   |
|   | Rated                               | LD                            | 1.6                                     | 2.7                   | 3.7     | 5.8       | 8.8      | 12     | 18       | 22       | 27       | 33       | 43     | 53       | 65    | 81    | 110   | 137   | 165   | 198   | 248   |
|   |                                     | ND (initial setting)          | 1.1                                     | 1.9                   | 3       | 4.6       | 6.9      | 9.1    | 13       | 18       | 24       | 29       | 34     | 43       | 54    | 66    | 84    | 110   | 137   | 165   | 198   |
|   |                                     | LD                            | 2.1                                     | 3.5                   | 4.8     | 7.6       | 11.5     | 16     | 23       | 29       | 35       | 43       | 57     | 70       | 85    | 106   | 144   | 180   | 216   | 260   | 325   |
| rt  | current (A)                         | ND (initial setting)          | 1.5                                     | 2.5                   | 4       | 6         | 9        | 12     | 17       | 23       | 31       | 38       | 44     | 57       | 71    | 86    | 110   | 144   | 180   | 216   | 260   |
| Output                                    | Overload                            | LD                            | 120%                                    | 60 s, 15              | 50% 3 s | s (inver  | se-time  | charac | teristic | s) at su | rroundi  | ng air t | empera | iture of | 40°C  |       |       |       |       |       |       |
| 0   | current                             | ND (initial setting)          | 150%                                    | 60 s, 20              | 00% 3 s | s (inver  | se-time  | charac | teristic | s) at su | irroundi | ng air t | empera | iture of | 40°C  |       |       |       |       |       |       |
| Rated voltage *4 Three-phase 380 to 500 V |                                     |                               |   |                       |         |           |          |        |          |          |          |          |        |          |       |       |       |       |       |       |       |
|   | Regenerative                        | Maximum<br>brake<br>torque *5 | 10% to                                  | 10% torque/continuous |         |           |          |        |          |          |          |          |        |          |       |       |       |       |       |       |       |
|   | Rated input<br>AC voltage/frequency |                               | Three-phase 380 to 500 V 50 Hz/60 Hz *8 |                       |         |           |          |        |          |          |          |          |        |          |       |       |       |       |       |       |       |
|   | Permissible A<br>fluctuation        | C voltage                     | 323 to                                  | 550 V 9               | 50 Hz/6 | 60 Hz     |          |        |          |          |          |          |        |          |       |       |       |       |       |       |       |
| supply                                    | Permissible fro                     | nissible frequency<br>uation  |   | ±5%                   |         |           |          |        |          |          |          |          |        |          |       |       |       |       |       |       |       |
|   |                                     | LD                            | 2.1                                     | 3.5                   | 4.8     | 7.6       | 11.5     | 16     | 23       | 29       | 35       | 43       | 57     | 70       | 85    | 106   | 144   | 180   | 216   | 260   | 325   |
| Power                                     | current (A) *6                      | ND (initial setting)          | 1.5                                     | 2.5                   | 4       | 6         | 9        | 12     | 17       | 23       | 31       | 38       | 44     | 57       | 71    | 86    | 110   | 144   | 180   | 216   | 260   |
|   | Power supply capacity               | LD                            | 1.6                                     | 2.7                   | 3.7     | 5.8       | 9        | 12     | 18       | 22       | 27       | 33       | 43     | 53       | 65    | 81    | 110   | 137   | 165   | 198   | 248   |
|   | (kVA) *7                            | ND (initial setting)          | 1.1                                     | 1.9                   | 3       | 4.6       | 6.9      | 9      | 13       | 18       | 24       | 29       | 34     | 43       | 54    | 66    | 102   | 110   | 137   | 165   | 198   |
| Pn  | otective                            | IEC 60529                     | Dust- a                                 | and wat               | er-proc | of type ( | (IP55) * | 10     |          |          |          |          |        |          |       |       |       |       |       |       |       |
| str                                       | ructure                             | UL50                          | UL Typ                                  | 0e12 *9               |         |           |          |        |          |          |          |          |        |          |       |       |       |       |       |       |       |
| Сс  | ooling system                       | •                             | Self co                                 | oling +               | interna | al fan    |          |        | Forced   | l-air-co | oling +  | interna  | l fan  |          |       |       |       |       |       |       |       |
| DC  | C reactor                           |                               | Built-ir                                | 1                     |         |           |          |        |          |          |          |          |        |          |       |       |       |       |       |       |       |
| Approx. mass (kg)                         |                                     | 1)                            | 15                                      | 15                    | 15      | 15        | 16       | 17     | 26       | 26       | 27       | 27       | 59     | 60       | 63    | 64    | 147   | 150   | 153   | 189   | 193   |

\*1 The applicable motor capacity indicated is the maximum capacity applicable for use of the Mitsubishi Electric 4-pole standard motor.

\*2 \*3

The rated output capacity indicated assumes that the output voltage is 440 V. The % value of the overload current rating indicated is the ratio of the overload current to the inverter's rated output current. For repeated duty, allow time for the inverter and motor to return to or below the temperatures under 100% load.

The maximum output voltage does not exceed the power supply voltage. The maximum output voltage can be changed within the setting range. \*4 However, the maximum point of the voltage waveform at the inverter output side is the power supply voltage multiplied by about  $\sqrt{2}$ . \*5 Value for the ND rating.

The rated input current indicates a value at a rated output voltage. The impedance at the power supply side (including those of the input reactor \*6 and cables) affects the rated input current.

\*7 The power supply capacity is the value when at the rated output current. It varies by the impedance at the power supply side (including those of the input reactor and cables).

For the power voltage exceeding 480 V, set **Pr.977 Input voltage mode selection**. \*8

UL Type 12 Enclosure-Suitable for Installation in a Compartment Handling Conditioned Air (Plenum)
 For compliance with IP55, remove the protective bushes and install the recommended cable glands.

# • Common specifications

| _                               |  | · · · · ·                          |  |
|---------------------------------|--|------------------------------------|--|
|                                 | Control method   |                                    | Soft-PWM control, high carrier frequency PWM control (selectable among V/F control, Advanced magnetic flux vector control, Real sensorless vector control), Optimum excitation control, vector control*1, and PM sensorless vector control   |
|                                 | Output frequence   | y range                            | 0.2 to 590 Hz (The upper-limit frequency is 400 Hz under Advanced magnetic flux vector control, Real sensorless vector control, vector control <sub>*1</sub> , and PM sensorless vector control.)  |
|                                 | Frequency setting  | Analog<br>input                    | 0.015 Hz/60 Hz (0 to 10 V/12 bits for terminals 2 and 4)<br>0.03 Hz/60 Hz (0 to 5 V/11 bits or 0 to 20 mA/approx. 11 bits for terminals 2 and 4, 0 to ±10 V/12 bits for terminal 1)<br>0.06 Hz/60 Hz (0 to ±5 V/11 bits for terminal 1)  |
|                                 | resolution   | Digital<br>input                   | 0.01 Hz  |
| ations                          | Frequency  | Analog<br>input                    | Within ±0.2% of the max. output frequency (25°C ±10°C)   |
| ecifica                         | accuracy   | Digital<br>input                   | Within 0.01% of the set output frequency   |
| <b>Control specifications</b>   | Voltage/frequent<br>characteristics  | су                                 | Base frequency can be set from 0 to 590 Hz. Constant-torque/variable-torque pattern or adjustable 5 points V/F can be selected.  |
| Cont                            | Starting torque  |                                    | LD rating: 150% 0.3 Hz, ND rating: 200%*6 0.3 Hz<br>(Real sensorless vector control, vector control*1)   |
|                                 | Torque boost   |                                    | Manual torque boost  |
|                                 | Acceleration/det   | celeration                         | 0 to 3600 s (acceleration and deceleration can be set individually), linear or S-pattern acceleration/deceleration mode, backlash countermeasures acceleration/deceleration can be selected.   |
|                                 | DC injection bra<br>(induction moto  |                                    | Operation frequency (0 to 120 Hz), operation time (0 to 10 s), operation voltage (0 to 30%) variable   |
|                                 | Stall prevention<br>level  | operation                          | Activation range of stall prevention operation (LD rating: 0 to 150%, ND rating: 0 to 220%). Whether to use the stall prevention or not can be selected (V/F control, Advanced magnetic flux vector control)   |
|                                 | Torque limit leve  | el                                 | Torque limit value can be set (0 to 400% variable).<br>(Real sensorless vector control, vector control∗1, PM sensorless vector control)  |
|                                 | Frequency  | Analog<br>input                    | Terminals 2 and 4: 0 to 10 V, 0 to 5 V, 4 to 20 mA (0 to 20 mA) are available.<br>Terminal 1: -10 to +10 V, -5 to +5 V are available.  |
|                                 | setting signal   | Digital<br>input                   | Input using the setting dial of the operation panel or parameter unit<br>Four-digit BCD or 16-bit binary (when used with option FR-A8AX)   |
|                                 | Start signal   |                                    | Forward and reverse rotation or start signal automatic self-holding input (3-wire input) can be selected.  |
|                                 | Input signals<br>(twelve terminals)  |                                    | Low-speed operation command, Middle-speed operation command, High-speed operation command, Second function selection, Terminal 4 input selection, Jog operation selection, Selection of automatic restart after instantaneous power failure, flying start, Output stop, Start self-holding selection, Forward rotation command, Reverse rotation command, Inverter reset The signal to be input can be changed using <b>Pr.178 to Pr.189 (Input terminal function selection)</b> .   |
| ion                             | Pulse tr   | ain input                          | 100 kpps   |
| <b>Operation specifications</b> | Operational fund   | ctions                             | Maximum and minimum frequency settings, multi-speed operation, acceleration/deceleration pattern, thermal protection, DC injection brake, starting frequency, JOG operation, output stop (MRS), stall prevention, regeneration avoidance, increased magnetic excitation deceleration, DC feeding, frequency jump, rotation display, automatic restart after instantaneous power failure, electronic bypass sequence, remote setting, automatic acceleration/deceleration, retry function, carrier frequency selection, fast-response current limit, forward/reverse rotation prevention, operation mode selection, slip compensation, droop control, load torque high-speed frequency control, speed smoothing control, traverse, auto tuning, applied motor selection, gain tuning, RS-485 communication, Ethernet communication*2, PID control, PID pre-charge function, easy dancer control, cooling fan operation selection, stop selection (deceleration stop/coasting), power-failure deceleration stop function, stop-on-contact control, PLC function, life diagnosis, maintenance timer, current average monitor, multiple rating, orientation control*1, speed control, torque control, position control, pre-excitation, torque limit, test run, 24 V power supply input for control circuit, safety stop function, anti-sway control |
|                                 | Output signal<br>Open collector o<br>(five terminals)<br>Relay output<br>(two terminals) | output                             | Inverter running, Up to frequency, Instantaneous power failure/undervoltage, Overload warning, Output frequency detection, Fault<br>The signal to be output can be changed using <b>Pr.190 to Pr.196 (Output terminal function selection)</b> .<br>Fault codes of the inverter can be output (4 bits) from the open collector.   |
|                                 | Pulse tr   | ain output                         | 50 kpps  |
|                                 |  | Pulse train<br>output<br>(FM type) | Max. 2.4 kHz: one terminal (output frequency)<br>The monitored item can be changed using <b>Pr.54 FM/CA terminal function selection.</b>   |
| ation                           | For meter  | Current<br>output<br>(CA type)     | Max. 20 mADC: one terminal (output frequency)<br>The monitored item can be changed using <b>Pr.54 FM/CA terminal function selection.</b>   |
| Indication                      |  | Voltage<br>output                  | Max. 10 VDC: one terminal (output frequency)<br>The monitored item can be changed using <b>Pr.158 AM terminal function selection.</b>  |
|                                 | Operation  | Operating<br>status                | Output frequency, Output current, Output voltage, Frequency setting value<br>The monitored item can be changed using <b>Pr.52 Operation panel main monitor selection</b> .   |
|                                 | panel  | Fault<br>record                    | Fault record is displayed when a fault occurs. Past 8 fault records (output voltage/current/frequency/cumulative energization time immediately before the fault occurs) are stored.  |

10

| w           | Protective/<br>arning function | Protective<br>function | Overcurrent trip during acceleration, Overcurrent trip during constant speed, Overcurrent trip during deceleration<br>or stop, Regenerative overvoltage trip during acceleration, Regenerative overvoltage trip during constant speed,<br>Regenerative overvoltage trip during deceleration or stop, Inverter overload trip, Motor overload trip, Heatsink<br>overheat, Instantaneous power failure, Undervoltage, Input phase loss+5, Stall prevention stop, Loss of<br>synchronism detection+5, Brake transistor alarm detection, Output side earth (ground) fault overcurrent, Output<br>short circuit, Output phase loss, External thermal relay operation+5, PTC thermistor operation+5, Option fault,<br>Communication option fault, Parameter storage device fault, PU disconnection, Retry count excess+5, CPU fault,<br>Operation panel power supply short circuit, 24 VDC power fault, Abnormal output current detection+5, Inrush<br>current limit circuit fault, Communication fault, Analog input fault, USB communication fault, Safety circuit fault,<br>Overspeed occurrence+5, Speed deviation excess detection+1+5, Signal loss detection+1+5, Ercessive position<br>fault+1+5, Brake sequence fault+5, Encoder phase fault+1+5, 4 mA input fault+5, Pre-charge fault+5, PID signal fault+5,<br>Opposite rotation deceleration fault+5, Internal circuit fault, User definition error by the PLC function, Abnormal<br>internal temperature, Magnetic pole position unknown+1 |  |  |
|-------------|--------------------------------|------------------------|---|--|--|
|             |                                | Warning<br>function    | Fan alarm, Stall prevention (overcurrent), Stall prevention (overvoltage), Electronic thermal relay function pre-<br>alarm, PU stop, Speed limit indication*s, Safety stop, Maintenance signal output*s, USB host error, Home position<br>return setting error*s, Home position return uncompleted*s, Home position return parameter setting error*s,<br>Operation panel lock*s, Password locked*s, Parameter write error, Copy operation error, 24 V external power<br>supply operation, Internal-circulation fan alarm, Continuous operation during communication fault, Ethernet<br>communication fault*2  |  |  |
| f           | Ambient tem                    | perature               | -10°C to +40°C (non-freezing)   |  |  |
| Environment | Surrounding air humidity       |                        | 95% RH or less (non-condensing),  |  |  |
| onr         | Storage temperature*3          |                        | -20°C to +65°C  |  |  |
| nvir        | Atmosp                         | here                   | Indoors (without corrosive gas, flammable gas, oil mist, dust and dirt, etc.)   |  |  |
| ш           | 교 Altitude/vibration           |                        | Maximum 1000 m*4, 5.9 m/s <sup>2</sup> *7 or less at 10 to 55 Hz (directions of X, Y, Z axes)   |  |  |

Available when a vector control compatible option is mounted. Available for the FR-A806-E only. Temperature applicable for a short time, e.g. in transit. For the installation at an altitude above 1,000 m up to 2,500 m, derate the rated current 3% per 500 m. This protective function is not available in the initial status. In the initial setting for the the FR-A846-00170(5.5K) or higher, it is limited to 150% by the torque limit level.

\*1 \*2 \*3 \*4 \*5 \*6

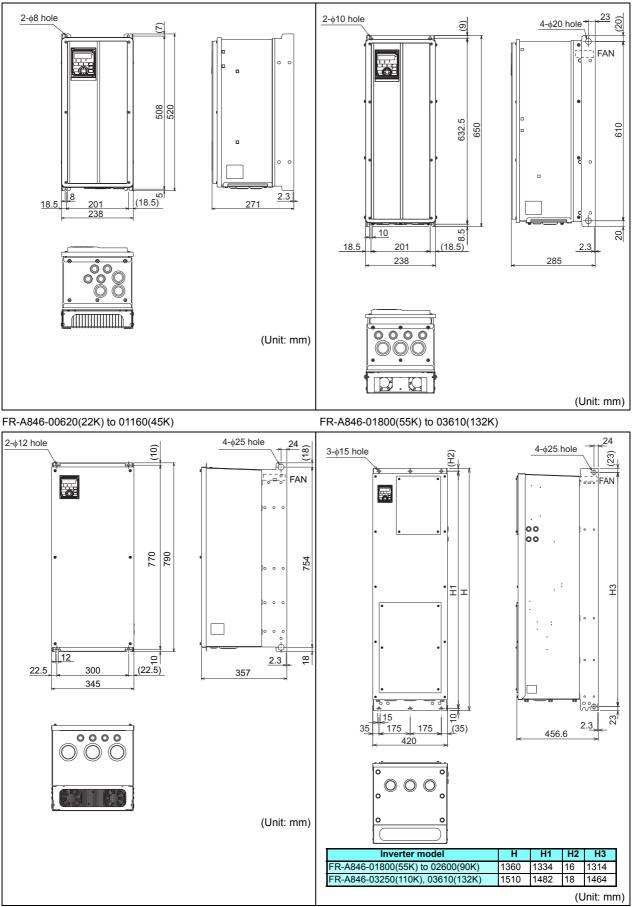
\*7 2.9 m/s<sup>2</sup> or less for the FR-A846-01800(55K) or higher.

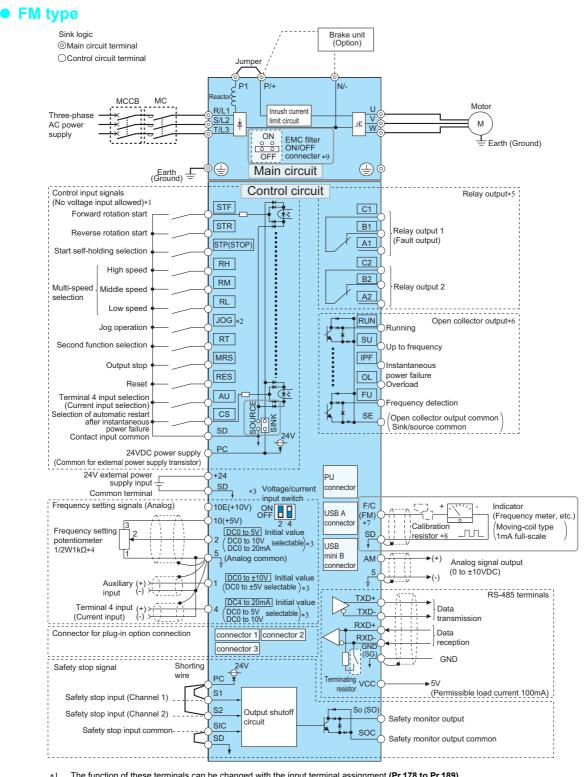
# **Outline Dimension Drawings**

FR-A846-00023(0.4K) to 00170(5.5K)

12

FR-A846-00250(7.5K) to 00470(18.5K)

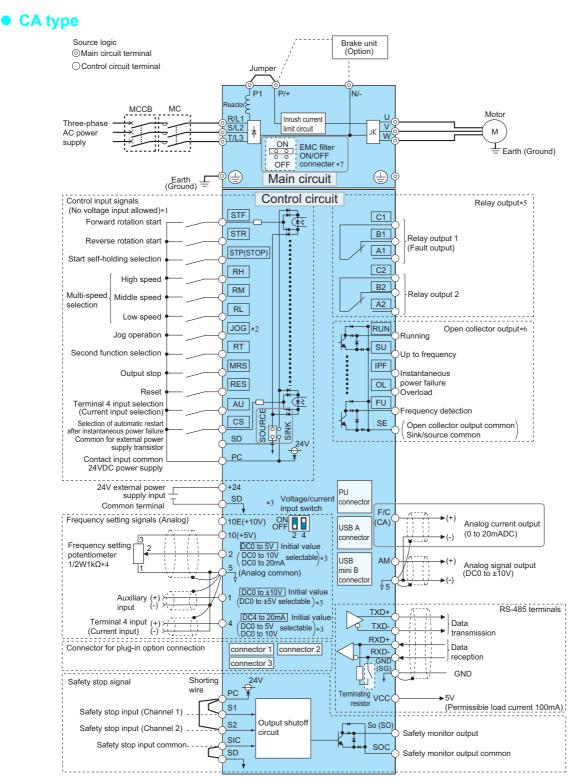




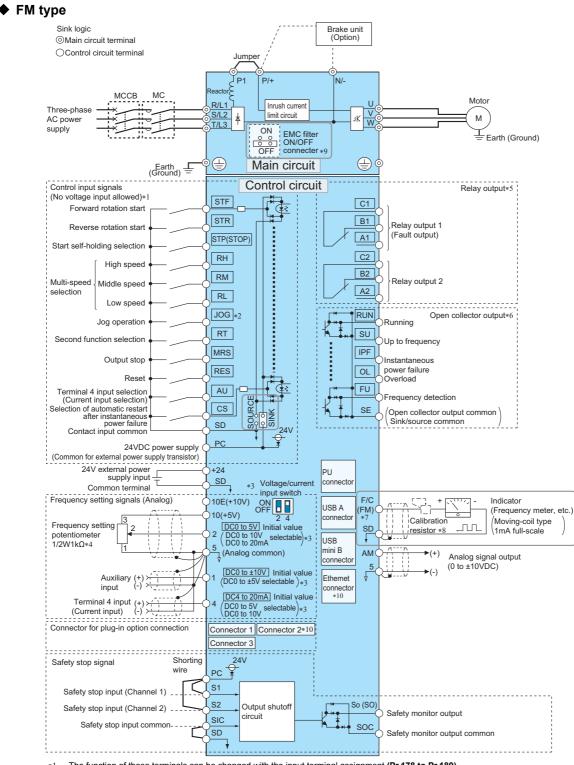
# **Terminal Connection Diagrams**

The function of these terminals can be changed with the input terminal assignment (**Pr.178 to Pr.189**) Terminal JOG is also used as a pulse train input terminal. Use **Pr.291** to choose JOG or pulse. \*2

- Terminal input specifications can be changed by analog input specification switchover (Pr.73, Pr.267). To input a voltage, set the voltage/current \*3 input switch OFF. To input a current, set the voltage/current input switch ON. Terminals 10 and 2 are also used as a PTC input terminal. (**Pr.561**) It is recommended to use 2 W 1 k $\Omega$  when the frequency setting signal is changed frequently. The function of these terminals can be changed with the output terminal assignment (**Pr.195**, **Pr.196**).
- \*4
- \*5
- \*6 The function of these terminals can be changed with the output terminal assignment (Pr.190 to Pr.194).
- \*7 The terminal FM can be used to output pulse trains as open collector output by setting **Pr.291**. Not required when calibrating the scale with the operation panel.
- \*8
- Do not change the initially set ON (enabled) position of the EMC filter ON/OFF connector in the case of the inverter with a built-in C2 filter. The Class C2 compatibility condition is not satisfied with the EMC filter OFF. The FR-A846-00250(7.5K)-C2/L2 to FR-A846-00470(18.5K)-C2/L2 are \*9 not provided with the EMC filter ON/OFF connector. The EMC filter is always ON.



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FR-A806-E

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## **Terminal Connection Diagrams**

CA type Source logic Brake unit (Option) Main circuit terminal O Control circuit terminal Jumper I<sub>P1</sub> ĺν/-P/+ MCCB MC Motor R/L1 Inrush current Three-phase JK W /L2 limit circuit 本 М AC power 7L3 supply ON ON ON/OFF OFF connecter \*7 Earth (Ground)  $( \pm )$ (\_) ¢ Main circuit Earth (Ground) -Control circuit Control input signals Relav output\*5 (No voltage input allowed)\*1 STF C1 दि Forward rotation start STR B1 Relay output 1 Reverse rotation start (Fault output) A1 STP(STOP) Start self-holding selection C2 RH High speed B2 RM Relay output 2 Multi-speed Middle speed A2 . selectior RL Low speed JOG \*2 RUN Open collector output\*6 Jog operation Runnina RT SU Second function selection Up to frequency MRS IPF Output stop Instantaneous power failure Overload RES OL Reset 4 FU Terminal 4 input selection AU requency detection (Current input selection) SOURCE CS SE Selection of automatic restart after instantaneous power failure SINK Open collector output common<sup>1</sup> 24V Sink/source common SD Common for external power supply transistor PC Contact input common 24VDC power supply 24V external power +24 PU supply input Voltage/current input switch SD \*3 conr Common terminal F/C Frequency setting signals (Analog) 10E(+10V) ON OFF ►(+) (CA) Analog current output USB A (0 to 20mADC) 10(+5V) connecto ·(-) DC0 to 5V Initial value (DC0 to 10V DC0 to 20mA selectable)\*3 Frequency setting potentiometer 1/2W1kΩ\*4 2 USB AM Analog signal output (DC0 to ±10V) 5 ר (Analog common) mini B connector √5 DC0 to ±10V Initial value (DC0 to ±5V selectable)\*3 Auxiliary Ethernet (+) (-) input onnecto DC4 to 20mA Initial value (DC0 to 5V selectable)\*3 DC0 to 10V Terminal 4 input (+)  $\xrightarrow{r}$  (Current input) (-)  $\xrightarrow{r}$  (-)  $\xrightarrow{r}$ Connector for plug-in option connection Connector 1 Connector 2\*8 Connector 3 Shorting 24V Safety stop signal wire PC I sı Safety stop input (Channel 1) S2 Output shutoff So (SO) Safety stop input (Channel 2) circuit Safety monitor output Lsic Safety stop input common-SOC I SD Safety monitor output common

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# **Terminal Specification Explanation**

Input signal function of the terminals in \_\_\_\_\_ can be selected by setting **Pr.178 to Pr.196 (I/O terminal function selection)**. Terminal names and terminal functions are those of the factory set.

| Т                            | уре               | Terminal<br>Symbol  | Terminal Name  | Description   |   |  |  |  |  |  |  |
|------------------------------|-------------------|---------------------|--|---|---|--|--|--|--|--|--|
|                              |                   | R/L1, S/L2,<br>T/L3 | AC power input   | Connect these terminals to the commercial power supply.<br>Do not connect anything to these terminals when using the high power fact<br>power regeneration common converter (FR-CV).  | or converter (FR-HC2) or the  |  |  |  |  |  |  |
| :                            | Ħ                 | U, V, W             | Inverter output  | Connect these terminals to a three-phase squirrel cage motor or a PM moto   |   |  |  |  |  |  |  |
|                              | Main circuit      | P/+, N/-            | Brake unit connection  | Connect the brake unit (FR-BU2, FR-BU, BU), power regeneration common regeneration converter (MT-RC), high power factor converter (FR-HC2), or feeding mode).   | DC power supply (under DC   |  |  |  |  |  |  |
|                              | Ň                 | P/+, P1             | _  | Do not remove the jumper across terminals P/+ and P1 except for connecting the power regeneration<br>common converter (FR-CV) or the high power factor converter (FR-HC2).  |   |  |  |  |  |  |  |
|                              |                   |                     | Earth (Ground)   | For earthing (grounding) the inverter chassis. This must be earthed (ground   | led).   |  |  |  |  |  |  |
|                              |                   | STF                 | Forward rotation<br>start  | Turn ON the STF signal to start forward rotation and turn it OFF to stop.   | When the STF and STR<br>signals are turned ON   |  |  |  |  |  |  |
|                              |                   | STR                 | Reverse rotation<br>start  | Turn ON the STR signal to start reverse rotation and turn it OFF to stop.   | simultaneously, the stop command is given.  |  |  |  |  |  |  |
|                              |                   | STP<br>(STOP)       | Start self-holding<br>selection  | Turn ON the STP (STOP) signal to self-hold the start signal.  |   |  |  |  |  |  |  |
|                              |                   | RH, RM,<br>RL       | Multi-speed<br>selection   | Multi-speed can be selected according to the combination of RH, RM and F  | 5   |  |  |  |  |  |  |
|                              |                   | Jog mode selection  |  | Turn ON the JOG signal to enable JOG operation (initial setting) and turn C STR) to start JOG operation.  | N the start signal (STF or  |  |  |  |  |  |  |
|                              |                   |                     | Pulse train input  | Terminal JOG is also used as a pulse train input terminal. To use as a pulse the <b>Pr.291</b> setting. (maximum input pulse: 100 k pulses/s)   | e train input terminal, change  |  |  |  |  |  |  |
|                              |                   | RT                  | Second function selection  | Turn ON the RT signal to enable the second function.<br>When the second function such as "second torque boost" and "second V/F<br>turning ON the RT signal enables the selected function.   | (base frequency)" is set,   |  |  |  |  |  |  |
|                              |                   | MRS                 | Output stop  | Turn ON the MRS signal (20 ms or more) to stop the inverter output.<br>Use this signal to shut off the inverter output when stopping the motor with   | 5   |  |  |  |  |  |  |
|                              | Contact input     | RES                 | Reset  | Use this signal to reset a fault output provided when a protective function is activated. Turn ON the RES<br>signal for 0.1 s or longer, then turn it OFF.<br>In the initial setting, reset is set always-enabled. By setting <b>Pr.75</b> , reset can be set enabled only at fault<br>occurrence. The inverter recovers about 1 s after the reset is released.   |   |  |  |  |  |  |  |
|                              | Conta             | AU                  | Terminal 4 input selection   | The terminal 4 function is available only when the AU signal is turned ON.<br>Turning the AU signal ON makes terminal 2 invalid.  |   |  |  |  |  |  |  |
| nal                          |                   | CS                  | Selection of<br>automatic restart<br>after instantaneous<br>power failure                                  | /hen the CS signal is left ON, the inverter restarts automatically at power restoration. Note that restart etting is necessary for this operation. In the initial setting, a restart is disabled.   |   |  |  |  |  |  |  |
| ıt sig                       |                   |                     | Contact input<br>common (sink)*1 Common terminal for the contact input terminal (sink logic), terminal FM. |   |   |  |  |  |  |  |  |
| Control circuit/input signal |                   | SD                  | External transistor common (source)*2  | Connect this terminal to the power supply common terminal of a transistor output (open collector output) device, such as a programmable controller, in the source logic to avoid malfunction by undesirable current.  |   |  |  |  |  |  |  |
| l circ                       |                   |                     | 24 VDC power<br>supply common  | Common terminal for the 24 VDC power supply (terminal PC, terminal +24)<br>Isolated from terminals 5 and SE.  |   |  |  |  |  |  |  |
| ontro                        |                   |                     | External transistor<br>common (sink)*1   | Connect this terminal to the power supply common terminal of a transistor of<br>device, such as a programmable controller, in the sink logic to avoid malfun  | output (open collector output) ction by undesirable currents.   |  |  |  |  |  |  |
| 0                            |                   | PC                  | Contact input<br>common (source)*2   | Common terminal for contact input terminal (source logic).  |   |  |  |  |  |  |  |
|                              |                   |                     | 24 VDC power<br>supply   | Can be used as a 24 VDC 0.1 A power supply.   |   |  |  |  |  |  |  |
|                              |                   | 10E                 | Frequency setting  | When connecting the frequency setting potentiometer at an initial status, connect it to the terminal 10.  | 10 VDC<br>Permissible load current<br>10 mA   |  |  |  |  |  |  |
|                              |                   | 10                  | power supply   | Change the input specifications of the terminal 2 using <b>Pr.73</b> when connecting it to the terminal 10E.  | 5 VDC<br>Permissible load current<br>10 mA  |  |  |  |  |  |  |
|                              | / setting         | 2                   | Frequency setting<br>(voltage)   | Inputting 0 to 5 VDC (or 0 to 10 V, 0 to 20 mA) provides the maximum output frequency at 5 V (10 V, 20 mA) and makes input and output proportional. Use <b>Pr.73</b> to switch among input 0 to 5 VDC (initial setting), 0 to 10 VDC, and 0 to 20 mA. Set the voltage/current input switch in the ON position to select current input (0 to 20 mA).   | When voltage is input: Input resistance 10 k $\Omega \pm 1$ k $\Omega$ Maximum permissible                                    |  |  |  |  |  |  |
|                              | Frequency setting | 4                   | Frequency setting<br>(current)   | Inputting 4 to 20 mADC (or 0 to 5 V, 0 to 10 V) provides the maximum output frequency at 20 mA and makes input and output proportional. This input signal is valid only when the AU signal is ON (terminal 2 input is invalid). Use <b>Pr.267</b> to switch among input 4 to 20 mA (initial setting), 0 to 5 VDC, and 0 to 10 VDC. Set the voltage/current input switch in the OFF position to select voltage input (0 to 5 V/0 to 10 V). Use <b>Pr.858</b> to switch terminal functions. | voltage 20 VDC<br>When current is input:<br>Input resistance 245 $\Omega$ ±5 $\Omega$<br>Permissible maximum<br>current 30 mA |  |  |  |  |  |  |
|                              |                   | 1                   | Frequency setting auxiliary  | Inputting 0 to $\pm$ 5 VDC or 0 to $\pm$ 10 VDC adds this signal to terminal 2 or 4 frequency setting signal. Use <b>Pr.73</b> to switch between input 0 to $\pm$ 5 VDC and 0 to $\pm$ 10 VDC (initial setting). Use <b>Pr.868</b> to switch terminal functions.  | Input resistance 10 k $\Omega$ ±1 k $\Omega$<br>Permissible maximum<br>voltage ±20 VDC  |  |  |  |  |  |  |
|                              |                   | 5                   | Frequency setting<br>common  | Common terminal for frequency setting signal (terminal 2, 1 or 4) and analo<br>not earth (ground).  | g output terminal AM, CA. Do  |  |  |  |  |  |  |

# **Terminal Specification Explanation**

| Т                             | уре                            |                     | minal<br>mbol   | Terminal Name   | Descriptio   | on  |  |  |  |  |  |
|-------------------------------|--------------------------------|---------------------|-----------------|---|--|---|--|--|--|--|--|
| input signal                  | Thermistor                     |                     | 10<br>2         | PTC thermistor<br>input                                     | For receiving PTC thermistor outputs. When PTC thermistor is valid ( <b>Pr.561</b> $\neq$ "9999"), the term available for frequency setting.   | inal 2 is not   | Applicable PTC thermistor<br>specification<br>Overheat detection<br>resistance:<br>$0.5$ to 30 k $\Omega$<br>(Set by <b>Pr.561</b> ) |  |  |  |  |
| Control circuit/input signal  | External power<br>supply input | 4                   | ·24             | Input voltage 23 to 25.5 VDC<br>Input current 1.4 A or less |  |   |  |  |  |  |  |
|                               | Relay                          |                     | 31, C1          | Relay output 1<br>(alarm output)                            | 1 changeover contact output that indicates that an inverter<br>function has been activated and the outputs are stopped.<br>Fault: discontinuity across B and C (continuity across A a<br>Normal: continuity across Band C (discontinuity across A  | nd C),  | Contact capacity<br>230 VAC 0.3 A<br>(power factor = 0.4)<br>30 VDC 0.3 A  |  |  |  |  |
|                               |                                | A2, I               | 32, C2          | Relay output 2  | 1 changeover contact output  | aual ta ar highar   | 00 100 0.011   |  |  |  |  |
|                               |                                | R                   | UN              | Inverter running  | Switched to LOW when the inverter output frequency is e<br>than the starting frequency (initial value 0.5 Hz). Switched<br>stop or DC injection brake operation.   |   | Permissible load 24 VDC  |  |  |  |  |
|                               | or                             |                     | SU              | Up to frequency   | Switched to LOW when the output frequency is within the set frequency range $\pm 10\%$ (initial value). Switched to HIGH during acceleration/deceleration and at a stop.   |   | (maximum 27 VDC) 0.1 A<br>(The voltage drop is 2.8 V at<br>maximum while the signal is   |  |  |  |  |
|                               | Open collector                 | (                   | DL              | Overload warning  | Switched to LOW when stall prevention is activated by the stall prevention function. Switched to HIGH when stall prevention is canceled.   | Fault code (4   | ON.)<br>LOW is when the open<br>collector output transistor is   |  |  |  |  |
| nal                           | oen                            | 1                   | PF              | Instantaneous<br>power failure                              | Switched to LOW when an instantaneous power failure occurs or when the undervoltage protection is activated.   | bits) output.   | ON (conducted).<br>HIGH is when the transistor   |  |  |  |  |
| Control circuit/output signal | Ō                              |                     | Ū               | Frequency<br>detection                                      | Switched to LOW when the inverter output frequency is equal to or higher than the preset detection frequency, and to HIGH when it is less than the preset detection frequency.   |   | is OFF (not conducted).  |  |  |  |  |
| uit/                          |                                |                     | SE              | Open collector<br>output common                             | Common terminal for terminals RUN, SU, OL, IPF, FU   |   |  |  |  |  |  |
| ontrol circ                   | e                              | F                   | M               | For meter   |  | Output item:<br>Output<br>frequency (initial<br>setting)                                    | Permissible load current<br>2 mA<br>For full scale<br>1440 pulses/s  |  |  |  |  |
| ŏ                             | Pulse                          | *3                  |                 | NPN open collector<br>output                                | Outputs a selected monitored item (such as output<br>frequency) among several monitored items. The signal is<br>not output during an inverter reset.   | This terminal<br>can be used for<br>open collector<br>outputs by<br>setting <b>Pr.291</b> . | Maximum output pulse<br>50k pulses/s<br>Permissible load current<br>80 mA  |  |  |  |  |
|                               | Analog                         | AM                  |                 | Analog voltage<br>output                                    | The output signal is proportional to the magnitude of the corresponding monitoring item. Use <b>Pr.55</b> , <b>Pr.56</b> , and <b>Pr.866</b> to set full scales for the monitored output frequency, output current, and torque.  | Output item:<br>Output<br>frequency (initial  | Output signal<br>0 to ±10 VDC,<br>Permissible load current<br>1 mA<br>(load impedance 10 kΩ or<br>more)<br>Resolution 8 bits         |  |  |  |  |
|                               | A                              |                     | <b>CA</b><br>*4 | Analog current<br>output                                    |  | setting)  | Load impedance<br>$200 \Omega$ to $450 \Omega$<br>Output signal<br>0 to 20 mADC  |  |  |  |  |
|                               |                                |                     |                 | PU connector  | With the PU connector, communication can be made thro<br>only)<br>Conforming standard: EIA-485 (RS-485)<br>Transmission format: Multidrop link<br>Communication speed: 4800 to 115200 bps<br>Wiring length: 500 m  | ugh RS-485. (For  | connection on a 1:1 basis  |  |  |  |  |
|                               | RS-485                         | 5<br>Is             | TXD+,<br>TXD-   | Inverter<br>transmission<br>terminal                        | The RS-485 terminals enables the communication by RS   | -485 (not available   | e for the FR-A806-E).  |  |  |  |  |
| u                             |                                | RS-485<br>terminals | RXD+<br>RXD-    | Inverter reception<br>terminal                              | Conforming standard: EIA-485 (RS-485)<br>Transmission format: Multidrop link<br>Communication speed: 300 to 115200 bps<br>Overall length: 500 m  |   |  |  |  |  |  |
| cati                          |                                | -                   | GND<br>(SG)     | Earth (Ground)  |  |   |  |  |  |  |  |
| Communication                 | Ethernet                       |                     | _               | Ethernet connector  | Communication can be made via Ethernet (only available<br>Category: 100BASE-TX/10BASE-T<br>Data transmission speed: 100 Mbps (100BASE-TX) / 10<br>Transmission method: Baseband<br>Maximum segment length: 100 m between the hub and ti<br>Number of cascade connection stages: Up to 2 (100BAS<br>Interface: RJ-45<br>Number of interfaces available: 1<br>IP version: IPv4 | Mbps (10BASE-T)<br>he inverter  | )  |  |  |  |  |
|                               | USB A conne                    |                     |                 | USB A connector   | A connector (receptacle)   | troop function  | Interface:   |  |  |  |  |
|                               | USB                            |                     | _               | USB B connector   | A USB memory device enables parameter copies and the<br>Mini B connector (receptacle)<br>Connected to a personal computer via USB to enable set<br>test operations of the inverter by FR Configurator 2.   |   | Conforms to USB1.1<br>(USB2.0 full-speed<br>compatible)<br>Transmission speed: 12<br>Mbps  |  |  |  |  |

| Туре     | Terminal<br>Symbol | Terminal Name  | Description   |  |
|----------|--------------------|--|---|--|
|          | S1                 | Safety stop input<br>(Channel 1)                       | The terminals S1 and S2 are used for the safety stop input signal for the safety relay module. The terminals S1 and S2 are used at the same time (dual channel). Inverter output is shutoff by shortening/opening between terminals S1 and  | Input resistance 4.7 kΩ  |
| signal   | S2                 | Safety stop input<br>(Channel 2)                       | SIC, or between S2 and SIC.<br>In the initial status, terminals S1 and S2 are shorted with the terminal PC by<br>shorting wires. The terminal SIC is shorted with the terminal SD. Remove<br>the shorting wires and connect the safety relay module when using the<br>safety stop function.   | (with 24 VDC input)  |
| stop s   | SIC                | Safety stop input<br>terminal common                   | Common terminal for terminals S1 and S2.  |  |
| Safety s | So (SO)            | Safety monitor<br>output<br>(open collector<br>output) | Indicates the safety stop input signal status.<br>Switched to LOW when the status is other than the internal safety circuit<br>failure. Switched to HIGH during the internal safety circuit failure status.<br>(LOW is when the open collector output transistor is ON (conducted). HIGH<br>is when the transistor is OFF (not conducted).)<br>Refer to the Safety stop function instruction manual (BCNA23228-001)<br>when the signal is switched to HIGH while both terminals S1 and S2 are<br>open. (Please contact your sales representative for the manual.) | Permissible load 24 VDC<br>(27 VDC at maximum) 0.1 A<br>(The voltage drop is 3.4 V at<br>maximum while the signal is<br>ON.) |
|          | SOC                | Safety stop input<br>terminal common                   | Common terminal for terminal SO.  |  |

Sink logic is initially set for the FM-type inverter. Source logic is initially set for the CA-type inverter. Terminal FM is provided in the FM-type inverter. Terminal CA is provided in the CA-type inverter. \*1 \*2 \*3 \*4

# **Peripheral Devices**

## Molded case circuit breaker, magnetic contactor, cable gauge

| Voltage | Motor<br>output | Applicable inverter model    | Molded case circuit breaker (MCCB)*2<br>or earth leakage circuit breaker | Input side magnetic |                     | ed cable gauge<br>m <sup>2</sup> )∗4 |
|---------|-----------------|------------------------------|--|---------------------|---------------------|--------------------------------------|
| Volt    | (kW)*1          |                              | (ELB) (NF, NV type)  | contactor*3         | R/L1, S/L2,<br>T/L3 | U, V, W                              |
|         | 0.4             | FR-A846-00023(0.4K)          | 5A   | S-T10               | 2                   | 2                                    |
|         | 0.75            | FR-A846-00038(0.75K)         | 5A   | S-T10               | 2                   | 2                                    |
|         | 1.5             | FR-A846-00052(1.5K)          | 10A  | S-T10               | 2                   | 2                                    |
|         | 2.2             | FR-A846-00083(2.2K)          | 10A  | S-T10               | 2                   | 2                                    |
|         | 3.7             | FR-A846-00126(3.7K)          | 15A  | S-T10               | 2                   | 2                                    |
|         | 5.5             | FR-A846-00170(5.5K)          | 20A  | S-T12               | 2                   | 2                                    |
|         | 7.5             | FR-A846-00250(7.5K)          | 30A  | S-T21               | 3.5                 | 3.5                                  |
|         | 11              | FR-A846-00310(11K) 40A S-T21 |  | S-T21               | 5.5                 | 5.5                                  |
| class   | 15              | FR-A846-00380(15K)           | 50A  | S-T21               | 5.5                 | 5.5                                  |
| 2       | 18.5            | FR-A846-00470(18.5K)         | 60A  | S-T35               | 8                   | 8                                    |
| 400     | 22              | FR-A846-00620(22K)           | 75A  | S-T35               | 14                  | 14                                   |
| 4       | 30              | FR-A846-00770(30K)           | 100A   | S-T50               | 22                  | 22                                   |
|         | 37              | FR-A846-00930(37K)           | 100A   | S-T50               | 22                  | 22                                   |
|         | 45              | FR-A846-01160(45K)           | 125A   | S-T65               | 38                  | 38                                   |
|         | 55              | FR-A846-01800(55K)           | 150A   | S-T100              | 60                  | 60                                   |
|         | 75              | FR-A846-02160(75K)           | 200A   | S-T100              | 60                  | 60                                   |
|         | 90              | FR-A846-02600(90K)           | 225A   | S-N150              | 60                  | 60                                   |
|         | 110             | FR-A846-03250(110K)          | 225A   | S-N180              | 80                  | 80                                   |
|         | 132             | FR-A846-03610(132K)          | 350A   | S-N220              | 100                 | 100                                  |

Assumes the use of a Mitsubishi Electric 4-pole standard motor with the power supply voltage of 400 VAC 50 Hz. \*1 \*2 Select an MCCB according to the power supply capacity.

Install one MCCB per inverter. For the use in the United States or Canada, provide the appropriate UL and cUL listed fuse or UL489 molded case circuit breaker (MCCB) that is suitable for branch circuit protection.

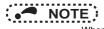


\*3

Magnetic contactor is selected based on the AC-1 class. The electrical durability of magnetic contactor is 500,000 times. When the magnetic contactor is used for emergency stops during motor driving, the electrical durability is 25 times If using an MC for emergency stop during motor driving, select an MC regarding the inverter input side current as JEM1038-AC-3 class rated current. When providing an MC on the inverter output side for switching to commercial power supply during general-purpose motor operation, select an MC regarding the rated motor current as JEM1038-AC-3 class rated current.

\*4 For the FR-A846-01800(55K) or lower, it is the gauge of a cable with the continuous maximum permissible temperature of 75°C (HIV cable (600 V grade heat-resistant PVC insulated wire), etc.). It assumes a surrounding air temperature of 50°C or lower and the wiring distance of 20 m or shorter

For the FR-A846-02160(75K) or higher, it is the gauge of the cable with the continuous maximum permissible temperature of 90°C or higher. (LMFC (heat resistant flexible cross-linked polyethylene insulated cable), etc.). It assumes a surrounding air temperature of 50°C or lower.



When the inverter capacity is larger than the motor capacity, select an MCCB and a magnetic contactor according to the inverter model, and select cables and reactors according to the motor output.

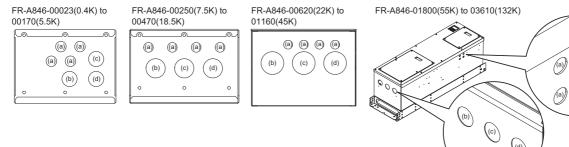
• When the breaker on the inverter's input side trips, check for the wiring fault (short circuit), damage to internal parts of the inverter etc. The cause of the trip must be identified and removed before turning ON the power of the breaker.

(d)

# • Cable glands and nuts

For wiring of the IP55 compatible model, fix the cables using a cable gland and a nut, according to the diameter of the holes of the wiring cover.

For the details such as wiring cover hole diameters and recommended cable glands, refer to the following table.



| Inverter capacity                      | Inverter capacity Symbol |                              | Hole<br>diameter<br>(mm) | Recommended cable gland<br>(Manufactured by LAPP KABEL)                  | Recommended nut<br>(Manufactured by LAPP<br>KABEL) |  |
|--|--------------------------|------------------------------|--------------------------|--|--|--|
|  | (a)                      | Control circuit wiring       | 20.3                     | SKINTOP MS-SC-M20 53112630 *1<br>SKINTOP MS-M20 53112020 *2              | SKINDICHT SM-M20 52103020                          |  |
| FR-A846-00023(0.4K)<br>to 00170(5.5K)  | (b)                      | AC power input wiring        |                          | SKINTOP MS-SC-M32 53112650 *1  |  |  |
| 10 00 170(3.5K)                        | (C)                      | Brake unit connection wiring | 32.3                     | SKINTOP MS-M32 BRUSH 53112677 *1   | SKINDICHT SM-M32 52103040                          |  |
|  | (d)                      | Inverter output wiring       |                          | SKINTOP MS-M32 53112040 *2   |  |  |
| FR-A846-00250(7.5K)<br>to 00470(18.5K) | (a)                      | Control circuit wiring       | 20.3                     | SKINTOP MS-SC-M20 53112630 *1<br>SKINTOP MS-M20 53112020 *2              | SKINDICHT SM-M32 52103020                          |  |
|  | (b)                      | AC power input wiring        |                          | SKINTOP MS-SC-M40 53112660 *1  |  |  |
|  | (C)                      | Brake unit connection wiring | 40.4                     |  | SKINDICHT SM-M40 52103050                          |  |
|  | (d)                      | Inverter output wiring       |                          | SKINTOP MS-M40 53112050 *2   |  |  |
|  | (a)                      | Control circuit wiring       | 20.3                     | SKINTOP MS-SC-M20 53112630 *1<br>SKINTOP MS-M20 53112020                 | SKINDICHT SM-M20 52103020                          |  |
| FR-A846-00620(22K)<br>to 02600(90K)    | (b)                      | AC power input wiring        |                          |  |  |  |
| 10 02000(90K)                          | (C)                      | Brake unit connection wiring | 63                       | SKINTOP MS-M63 BRUSH 53112680 *1<br>SKINTOP MS-M63 53112070 *2           | SKINDICHT SM-M63 52103070                          |  |
|  | (d)                      | Inverter output wiring       |                          |  |  |  |
|  | (a)                      | Control circuit wiring       | 20.3                     | SKINTOP MS-SC-M20 53112630 *1<br>SKINTOP MS-M20 53112020 *2              | SKINDICHT SM-M20 52103020                          |  |
| FR-A846-03250(110K)<br>to 03610(132K)  | (b)                      | AC power input wiring        |                          |  |  |  |
| 10 030 10(132K)                        | (C)                      | Brake unit connection wiring | 63                       | SKINTOP MS-M63 BRUSH PLUS 53112681 *1<br>SKINTOP MS-M63 PLUS 53112080 *2 | SKINDICHT SM-M63 52103070                          |  |
|  | (d)                      | Inverter output wiring       |                          |  |  |  |

EMC-compliant cable gland General-purpose cable gland \*1 \*2

# **Precautions for Use**

## Waterproof and dustproof performances

- The inverter is rated with an IPX5\*1 waterproof rating and an IP5X\*2 dustproof rating when the operation panel (FR-DU08-01), the front cover, the wiring cover, and the cable glands are securely fixed with screws.
- The items enclosed with the inverter such as the Instruction Manual or CD are not rated with the IPX5 waterproof or IP5X dustproof ratings.
- Although the inverter is rated with the IPX5 waterproof and IP5X dustproof ratings, it is not intended for use in water. Also, the
  ratings do not guarantee protection of the inverter from needless submersion in water or being washed under strong running water
  such as a shower.
- Do not pour or apply the following liquids over the inverter: water containing soap, detergent, or bath additives; sea water; swimming pool water; warm water; boiling water; etc.
- The inverter is intended for indoor\*4 installation and not for outdoor installation. Avoid places where the inverter is subjected to direct sunlight, rain, sleet, snow, or freezing temperatures.
- If the operation panel (FR-DU08-01) is not installed, if the screws of the operation panel are not tightened, or if the operation panel is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the operation panel, ask for an inspection and repair.
- If the screws of the front cover or the wiring cover are not tightened, if any foreign matter (hair, sand grain, fiber, etc.) is stuck between the inverter and the gasket, if the gasket is damaged, or if the front cover or the wiring cover is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the front cover, wiring cover, or the gasket of the inverter, ask for an inspection and repair.
- Cable glands are important components to maintain the waterproof and dustproof performances. Be sure to use cable glands of the
  recommended size and shape or equivalent. The standard protective bushes cannot sufficiently maintain the IPX5 waterproof
  performance and the IP5X dustproof performance.
- If a cable gland is damaged or deformed, the IPX5 waterproof performance and the IP5X dustproof performance are impaired. If any abnormalities are found on the cable glands, ask the manufacturer of the cable glands for an inspection and repair.
- To maintain the waterproof and dustproof performances of the inverter, daily and periodic inspections are recommended regardless
  of the presence or absence of abnormalities.
  - \*1 IPX5 refers to protection of the inverter functions against water jets from any direction when about 12.5-liter water-3 is injected from a nozzle with an inside diameter of 6.3 mm from the distance of about 3 m for at least 3 minutes.
  - \*2 IP5X refers to protection of the inverter functions and maintenance of safety when the inverter is put into a stirring device containing dust of 75 µm or smaller in diameter, stirred for 8 hours, and then removed from the device.
  - \*3 Water here refers to fresh water at room temperature (5 to 35°C).
     \*4 Indoor here refers to the environments that are not affected by climate conditions.

# Major differences between the standard model (FR-A840) and the IP55 compatible model (FR-A846)

|                 | Item   | FR-A840   | FR-A846   |
|-----------------|--|---|---|
| Prot            | tective structure  | Enclose type (IP20): FR-A840-00620(22K) or lower<br>Open type (IP00): FR-A840-00770(30K) or higher                                  | Dust-proof and waterproof type (IP55): All capacities           |
|                 | DC reactor   | Optional  | Built-in  |
| Interna         | I air circulation fan  | Without   | With  |
| Pro             | tective function   | -   | Internal fan alarm (FN2), Abnormal internal temperature (E.IAH) |
|                 | uit board coating<br>ning to IEC60721-3-3<br>3C2/3S2)                                      | With / Without (Selectable)   | With  |
| Environment     | Surrounding air temperature  | LD, ND, HD rating:<br>-10°C to +50°C (non-freezing)<br>SLD rating:<br>-10°C to +40°C (non-freezing)                                 | LD, ND rating:<br>-10°C to +40°C (non-freezing)                 |
| Enviro          | Surrounding air<br>humidity  | With circuit board coating:<br>95% RH or less (non-condensing)<br>Without circuit board coating:<br>90% RH or less (non-condensing) | 95% RH or less (non-condensing)                                 |
|                 | rake transistor<br>ble brake resistor)   | Built-in for the FR-A820-00046(0.4K) to 01250(22K)<br>Built-in for the FR-A840-00023(0.4K) to 01800(55K)                            | Without (Brake resistor is not applicable.)                     |
|                 | Iultiple rating<br>Iultiple rating setting)  | SLD, LD, ND (initial setting), HD rating<br>(Setting range: "0 to 3")   | LD, ND (initial setting) rating<br>(Setting range: "1 or 2")    |
| Pr.30 Re        | egenerative function selection   | Setting range:<br>"0 to 2, 10, 11, 20, 21, 100, 101, 110, 111, 120, or 121"   | Setting range:<br>"0, 2, 10, 20, 100, 110, or 120"              |
| Pr.70 S         | pecial regenerative<br>brake duty  | Available   | Not available   |
| (Ĕr.5<br>Pr.774 | erative brake duty<br>52, Pr.54, Pr.158,<br>4 to Pr.776, Pr.992,<br>o Pr.1034 setting "9") | Available (can be set)  | Not available (cannot be set)                                   |
| O               | peration panel   | FR-DU08: PU/EXT key   | FR-DU08-01: HAND/AUTO key                                       |
|                 | idio Waves Act<br>n Korea) (KC mark)   | Compliant   | Not compliant   |

For details including the common functions, options, and precautions, refer to the FR-A800 inverter catalog (L(NA)06075ENG).

# MEMO

# Global network for comprehensive support of



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# customers' manufacturing.



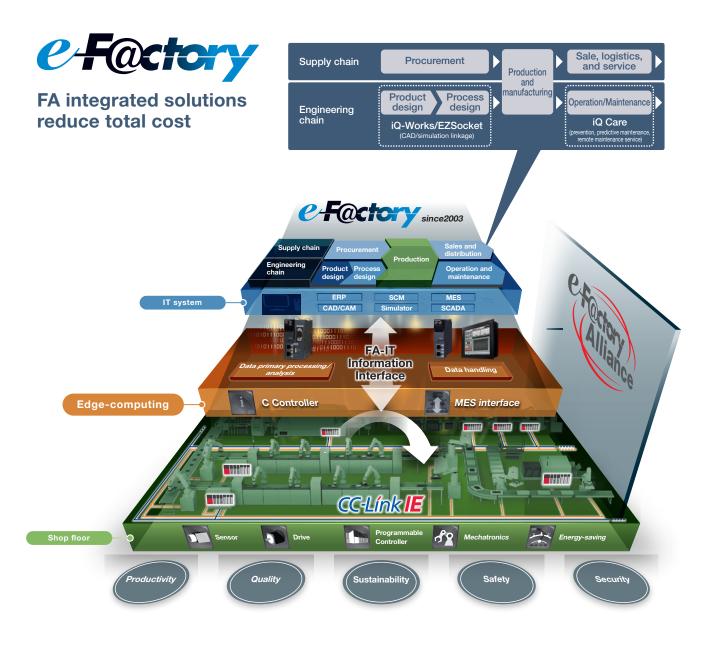
Service bases are established around the world to globally provide the same services as in Japan.

# Overseas bases are opened one after another to support business expansion of our customers.

| OVErSeas Dases As of July 2014 * Some includes distributors |                      |                       |                                 |                     |
|---|----------------------|-----------------------|---------------------------------|---------------------|
| Area  | Our overseas offices | FA Center (Satellite) | Bases providing<br>our products | Countries (Regions) |
| EMEA  | 11                   | 6 (2)                 | 146                             | 54                  |
| China   | 13                   | 4 (10)                | 171                             | 1                   |
| Asia  | 21                   | 13                    | 79                              | 10                  |
| America   | 14                   | 4 (0)                 | 130                             | 16                  |
| Others  | 1                    | 0                     | 3                               | 2                   |
| Total   | 60                   | 27 (12)               | 529                             | 83                  |

# This solution solves customers' issues and concerns by enabling visualization and analysis that lead to improvements and increase availability at production sites.

Utilizing our FA and IT technologies and collaborating with e-F@ctory Alliance partners, we reduce the total cost across the entire supply chain and engineeringchain, and support the improvement initiatives and one-step-ahead manufacturing of our customers.

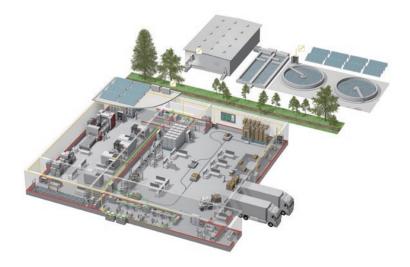


Overall production information is captured in addition to energy information, enabling the realization of efficient production and energy use (energy savings).

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Power monitoring, energy management



Compact and Modular Controllers



Inverters, Servos and Motors



Visualisation: HMIs



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Processing machines: EDM, Lasers, IDS



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# MITSUBISHI ELECTRIC CORPORATION

HEAD OFFICE: TOKYO BLDG., 2-7-3, MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN