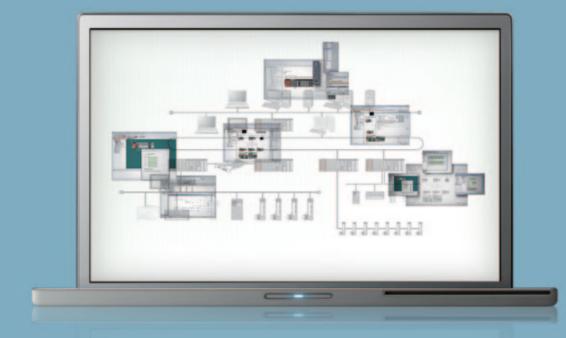




Mitsubishi iQ Platform Compatible FA Integrated Engineering Software MELSOFT iQ Works

## Introducing +MELSOFT Navigator



Navigating to an intuitive engineering environment





# Engineering innovations start from MELSOFT Navigator





Here's a more interactive and visible engineering style.

Revolutionizing everything from the way you design system specifications and develop programs, to the way you perform field adjustments, operations, and maintenance.

Experience the ease-of-use

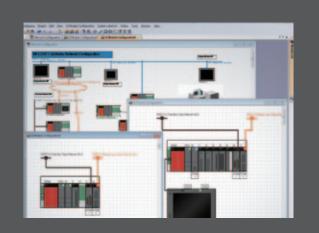


### **MELSOFT iQ Works**

System Management Software

### **MELSOFT Navigator**

MELSOFT Navigator, along with GX Works2, MT Works2, GT Works3, and RT ToolBox2, facilitates system level design and acts as the interface between each software. Useful functions include design of system configuration, parameter batch setting, system labels, and batch read.



#### Redefining engineering with

### + MELSOFT Navigator

Programmable Controller Engineering Software

#### **MELSOFT GX Works2**



This is the main programming and maintenance software for the PLC. Incorporating legacy support of programs created with GX Developer, further improving its functionality resulting in reduced engineering costs.

Motion Controller Engineering Software

#### MELSOFT MT Works2



The motion control design and maintenance software includes intuitive graphic based programming together with a digital oscilloscope simulator, further helping to reduce a motion systems TCO.

HMI/GOT Screen Design Software

#### **MELSOFT GT Works3**



The GOT (Graphic Operation Terminal) screen creation software has been designed with 3 main features; Simplicity, Graphic Design, and Easy Usability, further helping to create graphic screens in fewer steps.

Robot Engineering Software

#### **MELSOFT RT ToolBox2**



The robot setup software supports various steps from programming, to commissioning, evaluation, and maintenance. In addition to improving preventative maintenance by using the integrated 3D evaluation simulator to visualize parameterization and connected devices.







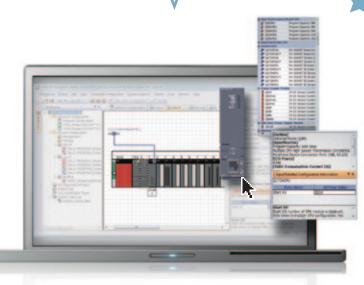


#### Ease-of-use at your fingertips

## → MELSOFT Navigator

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Displays available options in a list. Easily arrange suitable modules in the workspace.	03
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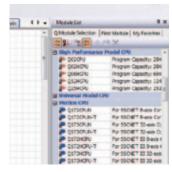
You'll be amazed at how quickly you can select the most suitable module.



#### Displays available options in a list. Easily arrange suitable modules in the workspace.

Catalogs to read, web sites to check. The first time-consuming task in designing a system is selecting the modules. With MELSOFT Navigator, all of current available modules are listed, and the specifications of selected modules can be easily confirmed. This simplifies the module selection process. Pick the most suitable module and drag & drop it into the system configuration.

Available modules are listed

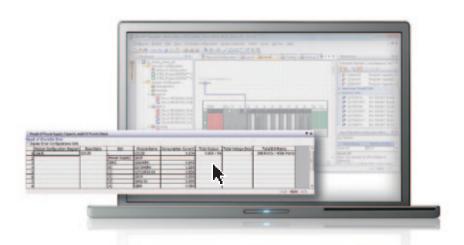


Selected module is illustrated





The power supply capacity and number of I/O points are automatically checked, so you don't need to rely on the manual!

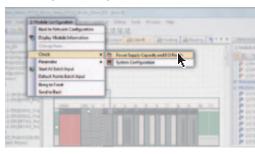


#### No need to look up manuals. Automatic check is available in module configuration.

Until now, referencing the manual was essential for calculating power supply capacity and looking up number of I/O points. Since making new selections in case of a mistake is bothersome, users often select extra large power supplies and CPU modules.

With MELSOFT Navigator, power supply capacity and number of I/O points of the selected module are automatically checked for the selected module configuration. This makes it easy to change the power supply and CPU modules when necessary.

Module configuration drawing

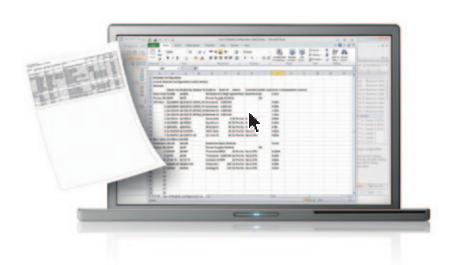


Automatic check of power supply capacity/Number of I/O points



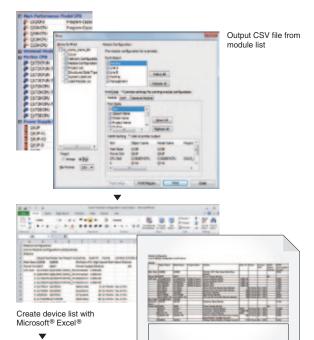


**Document your device lists** without having to manually input data!



#### Use CSV files to easily create lists with Microsoft® Excel®.

Manually inputting data into Microsoft® Excel® based on CAD drawings can make it quite timeconsuming to prepare device lists for orders. With MELSOFT Navigator, the list of devices in your system configuration drawing can be output as a CSV file which can be used to easily create and output device lists with Microsoft® Excel®.





Print out the device list

Effortlessly create system configurations without using Microsoft® Visio® or Microsoft® Word®!

Convenient!



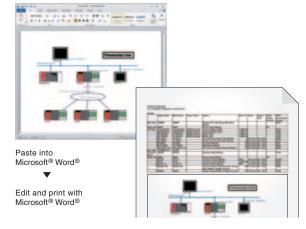
#### **Directly apply your system** designs in different locations.

Documenting your system configuration takes time and manpower. Do you still manually input your network configurations, module configurations and parameters settings with Microsoft® Visio® or Microsoft® Word®?

Design your system using MELSOFT Navigator and reuse the design details in other documents. There is no need to start from scratch each time.

#### System configuration







All relevant data are one-click away!

Convenient!

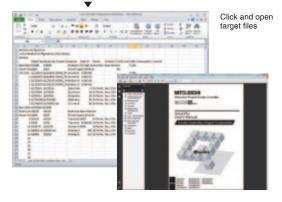


## Manage files in a similar fashion as in Microsoft® Windows® desktop.

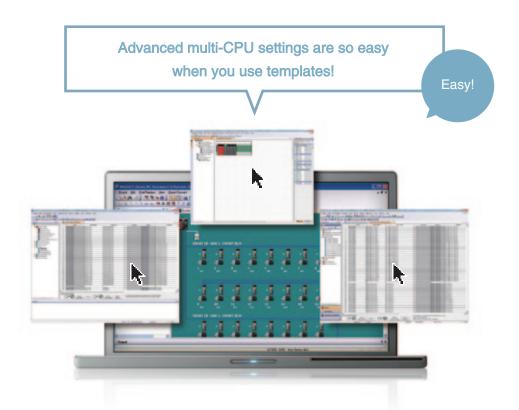
Saving and managing vast amounts of reference documents used for designing is always a headache. In MELSOFT Navigator, link files to mechanical drawings and past design materials can be pasted into the system configuration. To open the file, just click on the icon as in a Microsoft® Windows® desktop. There is no need to search for each file individually. With link files to design documents readily available, MELSOFT Navigator becomes a convenient portal.



Paste the link file for reference and design documents

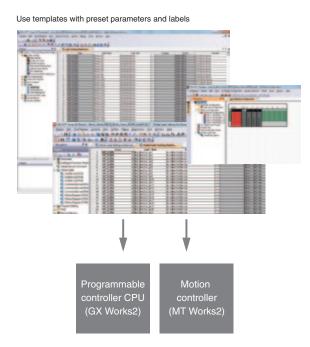






## Templates with preset parameters and labels are available.

Just as settings for a programmable controller CPU can be complicated, so can settings for a motion controller. MELSOFT Navigator provides multiple templates to facilitate setting up multi-CPU configurations that include a programmable controller CPU and a motion controller. The parameters and labels are preset, allowing you to focus on the programming.





Apply parameters from the system configuration to each station's programmable controller/GOT in one shot!

MELSOFT collaboration



## Batch set parameters for multiple systems.

Just when you thought you were finished, you have to set the parameters for the next system... In the programming stage, setting the parameters for multiple systems is bothersome.

With MELSOFT Navigator, the information set in the system configuration is applied in batch onto each GX Works2, MT Works2 or GT Works3 project. There's no need to start each software and check the consistency.

\*Detailed parameters must be set with each tool.



Parameter setting information in system configuration



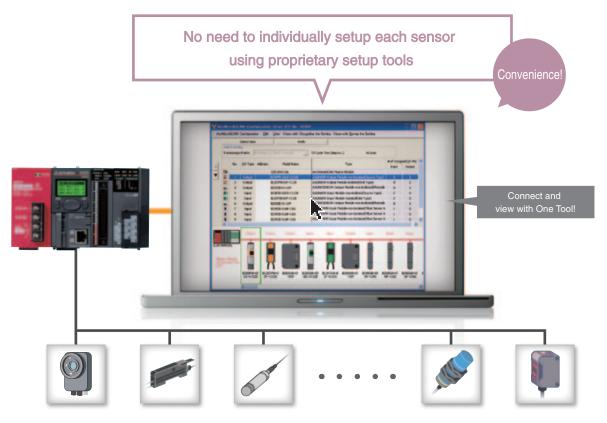
Applied in batch onto each development tool's data







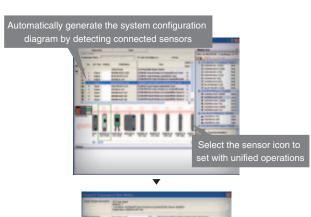




## One Tool to set parameters even between different sensor manufacturers

Setting parameters for each sensor can be difficult as setting methods can vary between setup tools. However, by using MELSOFT Navigator and GX Works2, the parameters for different iQSS\*1 compatible sensors can be setup all from the same setup screen. There's no need to use a dedicated tool for each sensor, resulting an efficient way of setting various sensors all in one operation. In addition, sensors supporting CC-Link and AnyWireASLINK\*2 networks, can be detected automatically within the system configuration diagram.

- \*1 Innovative solution for reducing TCO. iQ Sensor Solution
- \*2 Sensor network that centrally monitors (visualizes) the sensor statuses from the programmable controller, and contributes to improving operating rates and reducing engineering time.
- \*3 Refer to the iQSS catalog for further details. (Sensor Solution iQ Sensor Solution)
- \*4 AnyWireASLINK products are not available in some countries.
  Please consult your local Mitsubishi Electric representative for details.



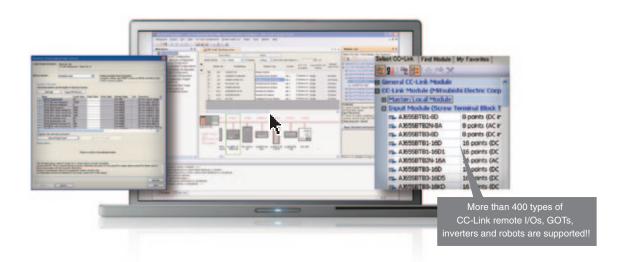






Can you really set the CC-Link/AnyWireASLINK network without referring to a manual?!

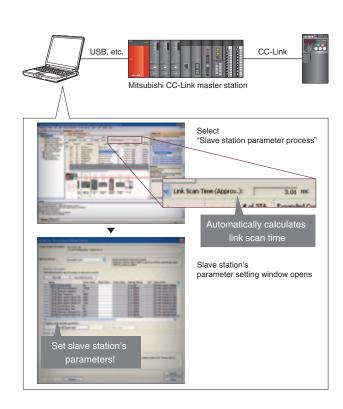
Easv



## Just select the device, ready for the design stage!

MELSOFT Navigator and GX Works2 use drag & drop and graphic based screens to create a intuitive setting environment for the CC-Link / AnyWireASLINK network. Easy operations mean the process from setting the various parameters to automatic calculation of the link scan time can be carried out at once. In addition, the slave station parameters settings can be confirmed and changed when required. New modules can be added to CC-Link by installing the CSP+\*1 released from CLPA\*2.

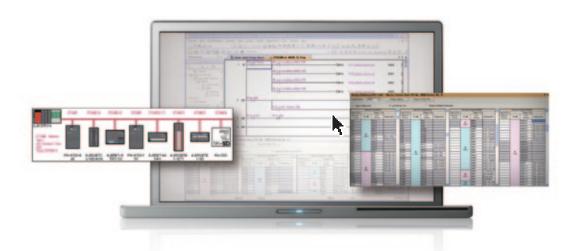
- \*1 CC-Link Association
- \*2 Profile prepared by vendors developing CC-Link family compatible products
- \*3 GX Works2 also supports CC-Link IE Field.





No need to consider device addresses!

Easy!



## Automatically generate device assignments from the configuration screen.

By using the new CC-Link configuration editor as part of the GX Works 2 package, device assignment tasks have been made much simpler. Just rearrange the illustrations on the editor screen using the mouse to complete the device configuration and finish programming. The devices are then automatically assigned and listed in an easy-to-view list.

This feature can be easily utilized for label programming.



Create the device configuration with the configuration editor



Automatically generate a list of device assignments



Program the ladder diagram while viewing the device assignments.



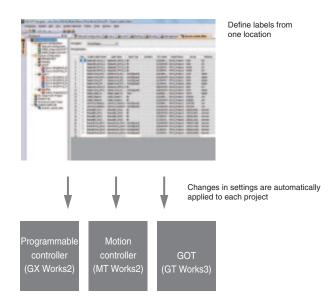
Assign devices for multiple projects just by changing one setting!

MELSOFT collaboration!



## Changes are automatically reflected in all related projects.

In the past, if the device assignments changed, the same corrections had to be made for each of the projects. This problem has been resolved by using MELSOFT Navigator which can share labels between the programmable controller, motion controller and GOT. If, for example, a device assignment is changed in a programmable controller project, those changes are automatically applied on the motion controller and GOT projects. This greatly reduces setting time and setting mistakes.





Can you really backup multiple devices without connecting cables to each one?

MELSOFT collaboration!

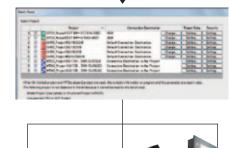


## Read out project data for multiple devices in batch.

Programmable controller, motion controller and GOT... The more equipment you connect to the system, the longer it takes to read out project data for backup. With MELSOFT Navigator, if a cable is connected to the master station's programmable controller, to which multiple devices are connected via bus or network (MELSECNET/CC-Link IE/Ethernet), the project data for the multiple devices can be read out in batch. It is unnecessary to connect cables to each device.



Cable connection to programmable controller (master station, etc.)



Motion controller

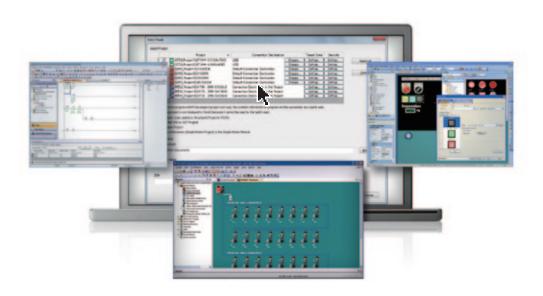
Read project data in batch



Programmable controller

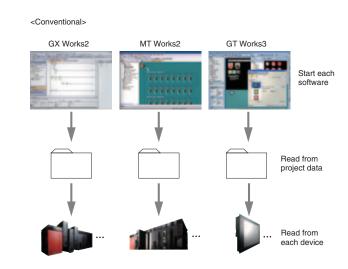
No more operation mistakes
or overdue backups!

MELSOFT
collaboration!



### Read in batch without starting each software.

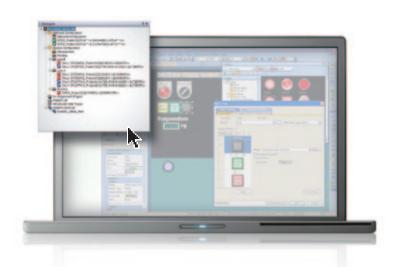
Previously, to read out each device's project data, the operator had to start up each software (GX Works2, MT Works2, GT Works3), read from the project file, and then read data from the device. This process took several minutes per device. As the number of connected devices increased, the possibility of operation mistakes and overlooked backups increased. Now, with MELSOFT Navigator, after initial connections are defined for each software, data can be batch read without having to start up each software. This dramatically improves the efficiency of periodic backups and prevents data from being missed.







MELSOFT collaboration!

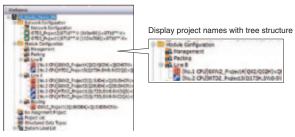


## Finding required data is a breeze with the workspace management method.

Have you ever felt that when folders are made for each process and managed in nests, it's still hard to find that project data you want to maintain? Once you find the folder, there are several files, and you don't know which one to open.

With MELSOFT Navigator, the project data for several devices such as the programmable controller, motion controller, GOT or robot can be managed as workspaces for a factory or a line. The project names are displayed with a tree structure in the workspace, and you can use Explorer to quickly find the project you need, etc.

#### Manage project data with workspaces



Search for corresponding project



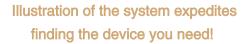






Click to read data



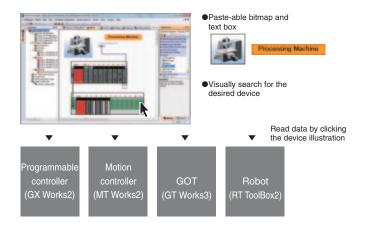


MELSOFT collaboration



### Click on the illustration to read its device data.

In MELSOFT Navigator, you can insert bitmap images to facilitate visualization of the system, and text boxes to write comments. The illustrations make searching for the desired device intuitive and fast. Reading project data is also made easy by simply clicking on the illustration.





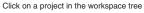
How easy! Click on the corresponding project to start up the right software!

MELSOFT collaboration!



## The right software automatically starts up.

Various software, including GX Developer, GX Works2, MT Works2, GT Works3 and RT ToolBox2, are used to edit project data used in a factory or line. It is often hard to know which software to start up. With MELSOFT Navigator, clicking on a project listed in the system configuration or workspace tree, starts up its corresponding software. The MELSOFT iQ Works Suite includes the license for these tools so you no longer need to manage licenses.





Click on a device in the system configuration

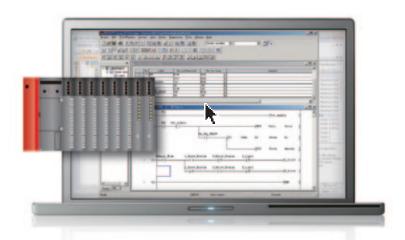






Hassle-free management covers programs even for older equipment.

MELSOFT collaboration



## Sequence programs for older equipment can be managed together.

Are you having trouble managing your sequence programs for older equipment? With MELSOFT Navigator, you can work with GX Developer which is capable of editing A Series\* sequence programs. Even when using systems consisting of older and newer programmable controllers, the project data for each programmable controller can be managed together with MELSOFT Navigator.

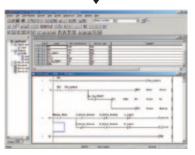
\*Excludes some modules.





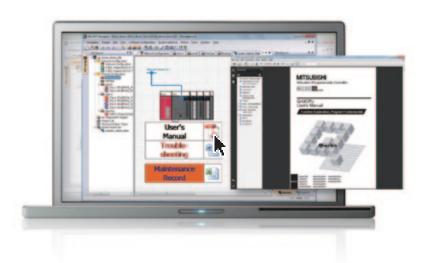
Start GX Developer from

workspace tree





From now on, find the target instruction manual at a glance!

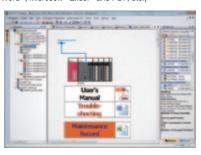


## Find target files instantaneously! Quickly and easily manage data.

It's hard to find the equipment's instruction manual file when you need it most. MELSOFT Navigator manages GX Developer, GX Works2, MT Works2, GT Works3 and RT ToolBox2 project, and allows document files created with tools such as Microsoft® Word®, Microsoft® Excel® or PDF to be pasted into the system configuration.

This ease-of-use is just like a portal tool for equipment related documents. Greatly improve the efficiency of design document and instruction manual data management.

Insert link files to documents and data
(Microsoft® Word® Microsoft® Excel® and PDE etc.)



Create a portal site of equipment-related documents

Click to display the target instruction file









MELSOFT MT Works2

MELSOFT GT Works

MELSOFT BT ToolBo



Programmable Controller Engineering Software

MELSOFT GX Works2

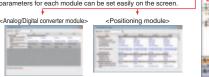
#### Integrating simulation functions with configuration functions! No need to purchase GX Simulator and GX Configurator separately

In addition to programmable controller programming, GX Works2 integrates simulation and various intelligent module setting functions.

### [ Integration of simulation function ] The simulator can be started easily with a single button allowing debuggin in the same circumstances as online even without an actual machine.

Debugging can be started with a personal Operations can be confirmed while viewing computer immediately after designing even without wining a programmable controller. designs can be completed without revorking

### [Integration of configuration function] By opening the setting screen from the project window, the parameters for each module can be set easily on the screen



### Directly write operations into ladders with inline ST!

Input options are automatically listed during command and label inputs. When inputting in an inline ST, label and command options are displayed.



Operation processes can be written directly in the ladder program. There's no need to add multiple lines of ladders

or function blocks.



#### Easily perform continuous searches of devices with user-friendly operations!

Reduce operation steps and input mistakes with candidate displays!

Read mode supports quick searches. Perform a continuous search by pressing the Enter key.





Press Ctril + F keys to search the first "Auto" When the search option is designated, a continuous Press the Enter key to search the next "Auto" (cursor moves) search is made each time the Enter key is pressed

#### Identify similar devices in a glance!

Comments can be set for each bit and for word devices.

A comment can be set for a bit-specified word device and displayed on the ladder circuit.





#### Quickly find where the device is being used!

Cross reference information for the device pinpointed with the cursor is automatically displayed.





#### One-touch displayable help function!

Help for the selected command is displayed immediately when the F1 key is pressed.





#### Making it easier to use intelligent function modules through buffer memory and I/O signal comments!



■ For intelligent function module
The intelligent function's
buffer memory and X/Y
comments are supported.



Easily apply predefined comments from the right-click menu.

▶ ▶ Refer to the GX Works2 Catalog <L(NA)08122E> for details.

Intuitive operations on graphical screens. Smoothly set even large-scale programs.

Motion Controller Engineering Software

MELSOFT MT Works2

#### **Programming**

Motion controller programming is supported with various convenient functions.

- Graphical motion SFC program and mechanical system program
- Label, device comment and cross-reference
- Command wizard and Instruction help allow you to program without a manual.



#### **System Design**

Easily set servo amplifiers and modules on the graphical system setting screen. Parameters also can be set quickly without a manual by checking One-point help.

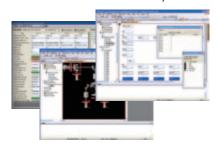


#### Startup and Adjustment

Supporting startup of the servo system with diverse functions.

#### ■ Variety of monitor function

A vast array of monitor functions allow the operation status of the motion controller to be confirmed easily.



#### ■ Digital oscillation function

Data which is synchronized with the motion operation cycle can be collected and displayed. It is possible to set the requested data simply with specified purpose probe setting. Collected data can be saved in CSV format and analyzed with other tools.



#### ■ Various test operation functions

In the test mode, basic startup can be confirmed without a program. Using the simulator function, theoretical debugging can be performed without an actual machine. In addition, the debug function is capable of step execution and break point settings.



#### ■ Collaboration with MR Configurator2

Use the servo setup software "MR Configurator?", filled with Mitsubishi Electric's servo knowhow, to adjust your servo system effortlessly. Multi-axes servo system can also be adjusttuned via motion controller from PC.



► MELSOFT GT Works3 MELSOFT RT ToolBox

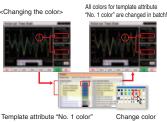
#### Such easy steps from "New Screen" to "Transfer to GOT".

#### Screen Design Software **MELSOFT GT Works3**

#### **Screen Creation**

#### ■ "Templates" reduce screen creation steps

Common screens and parts have been prepared as templates. Adjust these templates to quickly and easily create screens to match your target and applications with fewer screen creation steps.



- Historical trend graph line colors ● Numerical display value colors ● Character colors
- <Device monitor (bit)> <Historical (graph + list)>





#### ■ "Data Browser" simplifies setting confirmation and revisions The settings for graphics used in the

project are all listed.



"Help Function" shows the information you need When the F1 key is pressed, help for the currently active dialog opens immediately! Easily check the information you need.









The device list for the connected devices being set is displayed There's no need to open your manual

on the Lamp Setting screen





need from the Table of

Related items are also displayed

#### **Security Control**

#### ■ The User (OEM/End User) Security Function prevents your valuable data from being leaked or changed!

Protect your project data by setting access authority (availability of displaying and editing a project) with a five-stage access level not only for the project but also for screens. When the several people are involved in designing the screen, a specific screen can be protected by setting different access authority for each screen. The availability of displaying or editing the project can be confirmed with the work tree or the screen image list.





#### Simulation

#### ■ Confirm operations with a single click

Screen data movements (alarm confirmations, screen transitions and device monitoring, etc.) can be confirmed on your personal computer. Efficiently debug while correcting your screen.

Communication/Monitor

n function | < | GT Works2 Simulator (virtual programmable controller)



Click with mouse to touch

Device values and ON/OFF states can be changed.

revised, just click "Update"!

#### ■ Simple simulation with "Screen Preview"

Simple simulations and screen changeovers can be confirmed with screen preview. A specific switch display can be turned ON and OFF, device values can be input, and random screen images can be printed and saved. making it easy to prepare specifications and operation procedures.

<Confirming screen change switch>



screen preview. The editing screen can be opened in sequence with the preview screen so corrections confirming on the preview screen.

change switch is clicked

▶ ▶ Refer to the GT Works3 Catalog <L(NA)08170ENG> for details.

Total support from program creation, to start up, adjustment and maintenance.

Robot Engineering Software

MELSOFT RT ToolBox2

#### **Programming**

#### ■ Program editing

- Create programs with MELFABASIC IV, V or Movemaster languages.
- Efficiently perform work with multi-window method.
- With instruction templates and help functions, there's no need to refer to manuals.



#### Startup and Adjustment

#### ■ Debugging function

A variety of convenient functions make it easy to confirm operations such as program step execution, break point setting and direct execution.





#### ■ Monitor function

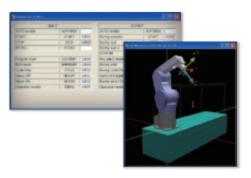
Monitor the program execution state, variables and input/output signals, etc. In addition, monitor the servo statuses such as the axis load status and current value.



#### Setting

#### ■3D Viewer

Visually confirm the limit values for the user defined areas, etc., with 3D Viewer.



Use 3D Viewer to confirm the robot's posture and motions, and to virtually arrange the peripheral devices with basic objects.



#### Maintenance

#### ■ Maintenance function

- Various maintenance functions include the maintenance forecast function that notifies operators of the robot grease up timing and battery consumption time, etc., and functions to restore the position in the event of trouble. These functions are effective for preventive maintenance and for shortening the recovery time.
- The entire system can be backed up in a batch using the project unit data control.



#### Contact information

- Q Who do we consult with to make a purchase?
- A Contact your nearest Mitsubishi Electric branch office or dealer.
- Q Who do we contact for information on the product technology?
- A Contact your nearest Mitsubishi Electric branch office or dealer. Please see the back cover for contact information.

#### Lineup

- Q Our personal computers use DVD. Is MELSOFT iQ Works available on DVD?
- A MELSOFT iQ Works is available on CD and DVD. Select the medium which works on your system.

#### Main Specifications

#### List of Software Functions

		Model	Outline
			Mitsubishi Electric iQ Platform compatible FA Integrated Engineering Software suite with Additional Integrated Functions, CD-ROM Version
			Mitsubishi Electric iQ Platform compatible System Management Software [MELSOFT Navigator]
			+ Mitsubishi Electric iQ Platform compatible Programmable Controller Engineering Software [MELSOFT GX Works2]
		SW1DNC-IQWK-E	+ Mitsubishi Electric iQ Platform compatible Motion Controller Engineering Software [MELSOFT MT Works2]
MEI COET IO Warks			+ Mitsubishi Electric iQ Platform compatible Screen Design Software [MELSOFT GT Works 3]
		+ Mitsubishi Electric iQ Platform compatible Robot Engineering Software [MELSOFT RT ToolBox2 mini]	
iQ Platform	MELSOFT iQ Works		Mitsubishi Electric iQ Platform compatible FA Integrated Engineering Software suite with Additional Integrated Functions, DVD-ROM Version
compatible FA Integrated Engineering Software			Mitsubishi Electric iQ Platform compatible System Management Software [MELSOFT Navigator]
		SW1DND-IQWK-E	+ Mitsubishi Electric iQ Platform compatible Programmable Controller Engineering Software [MELSOFT GX Works2]
			+ Mitsubishi Electric iQ Platform compatible Motion Controller Engineering Software [MELSOFT MT Works2]
			+ Mitsubishi Electric iQ Platform compatible Screen Design Software [MELSOFT GT Works 3]
			+ Mitsubishi Electric iQ Platform compatible Robot Engineering Software [MELSOFT RT ToolBox2 mini]
	MELSOFT GX Works2	SW1DNC-GXW2-E	MELSEC Programmable Controller Programming SW Programming Function + Intelligent Module Function + Simulator Function
	MELSOFT MT Works2	SW1DNC-MTW2-E	Mitsubishi Electric iQ Platform compatible Motion Controller Engineering Software
	MELSOFT GT Works3	SW1DNC-GTWK3-E	Screen Design Software for GOT + Simple Data Conversion Function + GT SoftGOT 1000 Function + Simulator Function
	MELOOFT DT To JD	3D-11C-WINE	Robot Engineering Software with Simulation Function CD-ROM Version
	MELSOFT RT ToolBox2	3D-12C-WINE	Robot Engineering Software mini Simple Version CD-ROM Version

#### MELSOFT iQ Works operation environment

		Details	
OS*	Microsoft® Windows® 2000 Professional Service Pack4 Microsoft® Windows® XP Professional Service Pack2,3 Microsoft® Windows® XP Home Edition Service Pack2,3 Microsoft® Windows® Vista® Home Basic Service Pack1,2 Microsoft® Windows® Vista® Home Premium Service Pack1,2 Microsoft® Windows® Vista® Ultimate Service Pack1,2 Microsoft® Windows® Vista® Business Service Pack1,2 Microsoft® Windows® Vista® Enterprise Service Pack1,2	Microsoft® Windows® 7 Ultimate Service Pack1 Microsoft® Windows® 7 Enterprise Service Pack1 Microsoft® Windows® 7 Professional Service Pack1 Microsoft® Windows® 7 Home Premium Service Pack1 Microsoft® Windows® 7 Starter Service Pack1 Microsoft® Windows® 8 Microsoft® Windows® 8 Pro Microsoft® Windows® 8 Enterprise	
CPU	Desktop: Celeron 2.8 GHz or more recommended	Laptop personal computer: PentiumM 1.7 GHz or more recommended	
Memory	1 GB or more recommended		
Display	XGA (1024×768) or more		
Free space	At installation: HD1GB (+ 390MB when installing manual)	During operation: 512 MB of free virtual memory	

<sup>\* 32-</sup>bit OS supported. Microsoft® Windows® 7 and Microsoft® Windows® 8 supported with 64-bit version.

#### MELSOFT iQ Works compatible version

MELOOT I IQ Works compatible version		
	Details	
MELSOFT GX Works2	Version 1.492N and higher	
MELSOFT MT Works2	Version 1.62Q and higher	
MELSOFT GT Works3	Version 1.74C and higher	
MELSOFT RT ToolBox2	Version 2.50C and higher	

#### Compatible Networks

Ethernet
MELSECNET/H
CC-Link IE Controller Network
CC-Link IE Field Network
CC-Link
AnyWire ASLINK

#### Compatible Programmable Controller (MELSEC-Q Series)

Compatible	Category	Model
	Jatogory	Q00JCPU
	Basic model QCPU	Q00CPU
	basic model QCPU	Q01CPU
		Q02CPU
		Q02HCPU
	High postermones model OCBH	
	High-performance model QCPU	Q06HCPU
		Q12HCPU
		Q25HCPU
		Q00UJCPU
		Q00UCPU
		Q01UCPU
		Q02UCPU
		Q03UDCPU
		Q03UDECPU
		Q03UDVCPU
		Q04UDHCPU
		Q04UDEHCPU
		Q04UDVCPU
		Q06UDHCPU
		Q06UDEHCPU
	Universal model QCPU	Q06UDVCPU
		Q10UDHCPU
		Q10UDEHCPU
CPU		Q13UDHCPU
		Q13UDEHCPU
		Q13UDVCPU
		Q20UDHCPU
		Q20UDEHCPU
		Q26UDHCPU
		Q26UDEHCPU
		Q26UDVCPU
		Q50UDEHCPU
		Q100UDEHCPU
		Q172CPUN
		Q172CPUN-T
		Q173CPUN
		Q173CPUN-T
		Q172HCPU
	Motion CPU	Q172HCPU-T
	INOUGH OF O	Q173HCPU
		Q173HCPU-T
		Q172DCPU
		Q173DCPU
	C Controller CPU	Q172DSCPU
		Q173DSCPU
		Q06CCPU-V
	C Controller CPU	Q12DCCPU-V
		Q33B
		Q35B
Base module	Main base	Q38B
		Q312B
		Q35DB

	Category	Model
	Category	Q38DB
	Main base	Q312DB
		Q32SB
	Clim type main been	Q33SB
	Slim type main base	
	Deducates a succession bearing to a second	Q35SB
Dana madala	Redundant power supply main base	Q38RB
Base module		Q63B
		Q65B
	Extension base	Q68B
		Q612B
		Q52B
		Q55B
	Redundant power supply extension base	Q68RB
		Q61P
		Q61P-A1
		Q61P-A2
	Power supply module	Q61P-D
D	r ower supply module	Q62P
Power supply module		Q63P
module		Q64P
		Q64PN
	Slim type power supply	Q61SP
		Q63RP
	Redundant power supply	Q64RP
		QX10
		QX10-TS
		QX28
		QX40
		QX40-TS
		QX40-13
		QX40H
		QX41
		QX41-S1
		QX41-S2
		QX42
		QX42-S1
	Input	QX50
		QX70
		QX70H
		QX71
		QX72
		QX80
		QX80-TS
I/O module		QX80H
		QX81
		QX81-S2
		QX82
		QX82-S1
		QX90H
		QY10
		QY10-TS
		QY18A
		QY22
Output		QY40P
		QY40P-TS
	QY41H	
	Su.put	QY41P
		QY42P
		QY50
		QY68A
		QY70
		QY71
		QY80

<sup>\*</sup> Above listed modules are compatible with MELSOFT Navigator (Ver. 1.62Q).

These modules differ from the MELSOFT GX Works2, MELSOFT MT Works2, MELSOFT GT Works3 and MELSOFT RT ToolBox2 compatible modules.

Compatible Programmable Controller (MELSEC-Q Series)

	Category	Model
		QY80-TS
	Output	QY81P
		QY82P
I/O module		QH42P
	I/O	QX48Y57
		QX41Y41P
	Interrupt input	Q160
		Q68ADV
		Q62AD-DGH
		Q68ADI
		Q64AD
		Q64ADH
	Analog input	Q64AD-GH
		Q64AD2DA
		Q68AD-G
		Q66AD-DG
		Q61LD
		Q68DAVN
		Q68DAV
		Q68DAIN
		Q68DAI
		Q62DAN
	Analog output	Q62DA
		Q62DA-FG
		Q64DAN
Analog I/O		Q64DA
module		Q64DAH
		Q66DA-G
		Q64RD
		Q64RD-G
		Q68RD3-G
	Temperature input	Q64TD
		Q64TDV-GH
		Q68TD-G-H01
		Q68TD-G-H02
		Q64TCRT
		Q64TCRTBW
		Q64TCTT
	Temperature control	Q64TCTTBW
		Q64TCRTN
		Q64TCRTBWN
		Q64TCTTN
		Q64TCTTBWN
	Loop control	Q62HLC
	2000 00.1	Q68CT
Simple	With SSCNET III/H	QD77MS2
motion	connectivity	QD77MS4
motion	Connectivity	QD77MS16
		QD72P3C3
		QD73A1
		QD75P1
		QD75P2
		QD75P4
		QD70P4
		QD70P8
Positioning		QD70P8 QD75D1
		QD75D2
		OD75D4
		QD75D4
		QD70D4
		QD70D4 QD70D8
		QD70D4

Positioning    QD75M2		Category	Model
Positioning		J. ,	
Positioning			QD75MH2
Positioning			
DD74MH8	Positioning		
OD74MH16			
High-speed counter			
CD63P6	High-speed co	punter	
Channel isolated pulse input	3 4		
Channel isolated pulse input			QD63P6
Channel isolated pulse input			QD64D2
Destary   Destary			QD65PD2
Design   D	Channel isolat	ed pulse input	QD60P8-G
Design   D			QE81WH
GESWH4W   QE84WH     Isolation monitoring   QE82LG     Web Server   QJ71WS96     MES interface   QJ71MES96     High-speed data logger   QD81DL96     GU71E71-100   QJ71E71-100     Ethernet   QJ71E71-B5   QJ71C24N-R2     QJ71C24N-R2   QJ71C24N-R4     Intelligent communication   QD51   QD51-R24     Optical loop (SI)   QJ71LP21-25   QJ71LP21S-25     QJ71LP21S-25   QJ71LP21G   QJ71LP21G     Coaxial bus   QJ71BR11     Twisted bus   QJ71BR11     Twisted bus   QJ71BR11     CC-Link   QJ61CL12     Ver. 2.00   QJ71E71-T-F01   QJ71E71-T-F01     Ver. 2.00   QJ71F171-B2-F01     FL-net (OPCN-2)   QJ71F171-B2   QJ71F171-TB2     CC-Link   E Controller Network   QJ71GP21-SX   QJ71GP21-SX     QJ71GP21-SX   QJ71GP21-SX   QJ71GP21-SX     QJ71GP21-SX   QJ71GP11-T2   QJ71GP11-T2     AnyWireASLINK   QJ51AW12AL   Q172EX-S1   Q172EX-S1   Q172EX-S2   Q172EX-S3   Q172EX-S			QE81WH4W
Isolation monitoring	Energy Measu	ırıng	QE83WH4W
Isolation monitoring			QE84WH
Web Server         QJ71WS96           MES interface         QJ71MES96           High-speed data logger         QD81DL96           Ligh-speed data logger         QD81DL96           QJ71E71-B2         QJ71E71-B2           QJ71C24N-R2         QJ71C24N-R2           QJ71C24N-R2         QJ71C24N-R4           Intelligent communication         QD51           MELSECNET/H         QD51 R24           QJ71LP21-25         QJ71LP21S-25           QJ71LP21S-25         QJ71LP21G           Qoxial bus         QJ71BR11           Twisted bus         QJ71NT11B           CC-Link         QJ61CL12           QJ71FL71-B2         QJ71FL71-F01           QJ71FL71-B2-F01         QJ71FL71-B2-F01           QJ71FL71-B2-F01         QJ71FL71-B2-F01           QJ71FL71-B5         QJ71GP21-SX           QJ71GP21-SX         QJ72GPX           QJ72EX-	Isolation monit	toring	
MES interface		9	
High-speed data logger			
Ethernet			
Ethernet	inigii-speed da	ita ioggei	
Serial communication			
Serial communication	Ethernet		
Serial communication			
DJ71C24N-R4			
Intelligent communication	Serial commun	nication	QJ71C24N-R2
Optical loop (SI)			QJ71C24N-R4
Optical loop (SI)	Intelligent com	munication	QD51
MELSECNET/H	intelligent com	inunication	QD51-R24
MELSECNET/H		Optical loop (SI)	QJ71LP21-25
Coaxial bus			QJ71LP21S-25
Coaxial bus	MELSECNET/H	Optical loop (GI)	QJ71LP21G
Twisted bus			QJ71BR11
CC-Link		Twisted bus	
Ver. 2.00	CC-Link	1	
Ver. 2.00			_
Ver. 2.00	OO-LIIIIVLI		
PL-net (OPCN-2)		Vor 2.00	
Ver. 1.00		Ver. 2.00	
Ver. 1.00			
AS-i	(OFCN-2)	.,	
AS-i		Ver. 1.00	
CC-Link IE Controller Network			_
CC-Link IE Controller Network	AS-i		
CC-Link IE Field Network	CC-Link IE Co	entroller Network	
Servo external signal input	CC-LITIK IE CONTIONEI NETWORK		QJ71GP21S-SX
Servo external signal input	CC-Link IE Fie	eld Network	QJ71GF11-T2
Servo external signal input	AnyWireASLIN	NK .	QJ51AW12AL
Motion module  Synchronous encoder input (synchronization between master/slave)  Manual pulse generator input (2173PX  Manual pulse generator inpu		Compositional district	Q172LX
Motion module  Synchronous encoder input (synchronization between master/slave)  Synchronous encoder input (synchronization between master/slave)  Q172EX-S1 Q172EX-S2 Q172EX-S3 Q172EX-S3 Q172EX-S3 Q172DEX Q173PX Q173PX Q173PX U101-01		Servo external signal input	Q172DLX
Synchronous encoder input (synchronization between master/slave)   Q172EX-S1   Q172EX-S2   Q172EX-S3   Q172DEX   Q173PX   Q173PX-S1   Q173PX   Q1			
Synchronous encoder input (synchronization between master/slave)			
(synchronization between master/slave)	Motion		
Q172DEX   Q173PX			
Manual pulse generator input Q173PX Q173PX-S1 Q173DPX			
Manual pulse generator input Q173PX-S1 Q173DPX Patters U01-01			
Q173DPX		Manual nules savantania	
Partner IIO1-01		ivianuai puise generator input	
Partner Displacement sensor control UQ1-01			
	Partner	Displacement sensor control	
products UQ1-02			1 1104 00

<sup>\*</sup> Above listed modules are compatible with MELSOFT Navigator (Ver. 1.62Q).

These modules differ from the MELSOFT GX Works2, MELSOFT MT Works2, MELSOFT GT Works3 and MELSOFT RT ToolBox2 compatible modules.

#### Compatible Programmable Controller (MELSEC-L Series)

		oller (IVIELSEC-L Series)
Category		Model
-		L02SCPU
		L02SCPU-P
		L02CPU
		L02CPU-P
CPU		L06CPU
		L06CPU-P
		L26CPU
		L26CPU-P
		L26CPU-BT
		L26CPU-PBT
Branch / Extension	module	L6EXB
Branon / Extension	modulo	L6EXE
Power supply		L61P
1 Ower supply		L63P
RS-232 adaptor		L6ADP-R2
End cover		L6EC
Liiu covei	With error terminal	L6EC-ET
		LX10
		LX28
	Input	LX40C6
		LX41C4
		LX42C4
		LY10R2
I/O module		LY20S6
		LY41NT1P
		LY42NT1P
	Output	LY40NT5P
		LY40PT5P
		LY41PT1P
		LY42PT1P
		L60AD4
Analog I/O		L60AD4-2GH
Ü		L60DA4
		L60TCRT
		L60TCRTBW
Temperature Contro	ıl	L60TCTT
		L60TCTTBW
		LD77MH4
Simple motion		LD77MH16
		LD75P1
Positioning  High-speed counter		LD75P2
		LD75P4
		LD75D1
		LD75D2
		LD75D4
		LD62
		LD62D
	CC-Link IE Field Network	LJ71GF11-T2
CC-Link IE Field NetWork		LJ61BT11
	CC-Link/LT	LJ61CL12
Network	Ethernet interface	LJ71E71-100
		LJ71C24
	Serial communication	LJ71C24-R2
AnyWireASLINK		LJ51AW12AL
AllywileAstilan		LUJIAWIZAL

#### Compatible Programmable Controller (MELSEC-FX Series)

Category		Model	
	FX3G Series CPU	FX3G-**M	
CPU	FX3U Series CPU	FX3U-**M	
	FX3UC Series CPU	FX3UC-**M	
Special block	Ethernet block	FX3U-ENET*	

#### Compatible display

Category	Model
	GT16**-X
	GT16**-S
	GT16**-V
	GT165*-V
	GT15**-X
	GT15**-S
	GT15**-V
	GT155*-V
	GT15**-Q
GOT 1000 Series	GT14**-Q*BD
	GT14**-Q*BDE
	(Ethernet built-in)
	GT12**-V
	GT11**-Q
	GT11**-Q*BDQ (Q bus built-in)
	GT11**-Q*BDA (A bus built-in)
	GT10**-Q
	GT1030
	GT1020

<sup>\*</sup> Above listed modules are compatible with MELSOFT Navigator (Ver. 1.62Q).

These modules differ from the MELSOFT GX Works2, MELSOFT MT Works2, MELSOFT GT Works3 and MELSOFT RT ToolBox2 compatible modules.

#### Robot

Category		Model
Robot		RV-2SD
		RV-3SD Series
	SD Series	RV-6SD Series
		RV-12SD Series
		RH-SDH Series
	SQ Series	RV-2SQ
		RV-3SQ Series
		RV-6SQ Series
		RV-12SQ Series
		RH-SQH Series
	Ceiling mount type	RH-3SDHR/3SQHR
	RP Series	RP Series
	RV-TH/THL Series	L Series RV-TH/THL Series

#### AnyWireASLINK equipment (Anywire Corporation)

C	ategory	Model
		B280SB-02U-C1220
		B280SB-02US-C1220
		B281SB-02U-CC20
	Innut	B281SB-02US-CC20
	Input	B298SB-02U-M12
		B298SB-02US-M12
		BL287SB-02F-CC20
		BL287SB-02FS-CC20
		B280PB-02U-C1220
		B280PB-02US-C1220
		B281PB-02U-CC20
ASLINKER	Outenut	B281PB-02US-CC20
ASLINKER	Output	B298PB-02U-M12
		B298PB-02US-M12
		BL287PB-02F-CC20
		BL287PB-02FS-CC20
		B280XB-02U-C1220
		B280XB-02US-C1220
		B281XB-02U-CC20
	I/O	B281XB-02US-CC20
	1/0	B298XB-02U-M12
		B298XB-02US-M12
		BL287XB-02F-CC20
		BL287XB-02FS-CC20
		B289SB-01AF-CAM20
A OL INIIKANAD		B289SB-01AF-CAS
ASLINKAMP	Input	B289SB-01AP-CAM20
		B289SB-01AP-CAS
A OL INIKOENIOOD	Input	B283SB-01-1KC
ASLINKSENSOR	Output	B283SB-01-1KP
	la acat	BL296SB-08F-20
	Input	BL296SB-08FS-20
ACLINIZTEDMINIAL	Outout	BL296PB-08F-20
ASLINKTERMINAL	Output	BL296PB-08FS-20
	1/0	BL296XB-08F-20
	1/0	BL296XB-08FS-20

<sup>\*</sup> AnyWireASLINK products are not available in some countries.

Please consult your local Mitsubishi Electric representative for details.

<sup>\*</sup> Above listed modules are compatible with MELSOFT Navigator (Ver. 1.62Q).

These modules differ from the MELSOFT GX Works2, MELSOFT MT Works2, MELSOFT GT Works3 and MELSOFT RT ToolBox2 compatible modules.

#### **Automation related products**

#### $\mathsf{PLC}$

#### MELSEC-Q Series Universal Model



- ©Realize high-speed, high-accuracy machine control with various iQ Platform compatible controllers and multiple CPUs.
- ©Easily connect to GOTs and Programming tools using built-in Ethernet port.
- ©25 models from 10 k step small capacity to 1000 k step large capacity, are available.
- ©Seamless communication and flexible integration at any network level.







#### Programmable Controller | MELSEC-L Series

"Light & Flexible" condensing various functions easily and flexibly.

- ©CPU equipped as a standard with various functions including counter, positioning and CC-Link.
- ©The base-less structure with high degree of freedom saves space in the control panel.
- ©Easily confirm the system status and change the settings with the display unit.
- OSeven models are available in program capacities from 20 k steps to 260 k steps.

#### Product specifications

Program capacity	20 k steps/60 k steps/260 k steps
Number of input/output points [X/Y]	1024 points/4096 points
Number of input/output device points [X/Y]	8192 points
Basic instruction processing speed (LD instruction)	60 ns/ 40 ns/ 9.5 ns
External connection interface	USB, Ethernet, RS-232, SD memory card, CC-Link (L26CPU-BT/PBT)
Function modules	I/O, analog, high-speed counter, positioning, simple motion, temperature control, network module
Unit expansion style	Base-less structure
Network	Ethernet, CC-Link IE Field network, CC-Link, CC-Link/LT, SSCNETIII(/H), RS-232, RS-422



#### нмі

#### Graphic Operation Terminal GOT1000 Series GT16 Model

Full-flat face body integrating all the functions required of a HMI.



- ○All models are equipped with Ethernet, RS-422/485 and RS-232 interfaces enabling a diverse range of communications.
- OA multimedia unit and a video/RGB unit (optional) are supported for smooth recording and playback of moving images.
- OUSB host and device ports are provided as a standard on the front panel. Easily connect to a personal computer for data exchange.
- OLarge 15MB memory capacity allows you to use optional functions and real parts, etc., without worrying about memory space.

#### Product Specifications

r roduct opecifications	
Screen size	15", 12.1", 10.4", 8.4", 5.7"
Resolution	XGA, SVGA, VGA
Intensity adjustment	8-step or 4-step adjustment
Touch panel type	Analog resistive film
Built-in interface	RS-232, RS-422/485, Ethernet, USB, CF card
Applicable software	GT Works3
Input power supply voltage	100 to 240VAC (+10%, -15%), 24VDC (+25%, -20%)

#### AC Servo

#### Mitsubishi General-Purpose AC Servo MELSERVO-J4 Series



#### Industry-leading level of high performance servo

- Oldustry-leading level of basic performance: Speed frequency response (2.5kHz), 4,000,000 (4,194,304p/rev) encoder
- $\bigcirc$  Advanced one-touch tuning function achieves the one-touch adjustment of advanced vibration suppression control  $\mathbb{I}$ , etc.
- ©Equipped with large capacity drive recorder and machine diagnosis function for easy maintenance.
- ©2-axis and 3-axis servo amplifiers are available for energy-conservative, space-saving, and low-cost machines.

#### Product Specifications

Froduct Specifications	
Power supply specifications	1-phase/3-phase 200V AC, 3-phase 400V AC
Command interface	SSCNET II/H, SSCNET III (compatible in J3 compatibility mode), CC-Link IE Field Network interface with Motion, pulse train, analog
Control mode	Position/Speed/Torque/Fully closed loop
Speed frequency response	2.5kHz
Tuning function	Advanced one-touch tuning, advanced vibration suppression control II, robust filter, etc.
Safety function	STO, SS1 SS2, SOS, SLS, SBC, SSM (compatible when combined with motion controller)
Compatible servo motor	Rotary servo motor (rated output: 0.05 to 22kW), linear servo motor (continuous thrust 50 to 3000N), direct drive motor (rated torque: 2 to 240N • m)

#### Inverter

#### FR-A700 Series



#### High-function, high-performance inverter

- ⊚High-accuracy, high-response speed control using real sensor-less vector control is possible with a general-purpose inverter having no PLG (encoder) (200% torque/0.3 Hz (3.7 K or less)).
- ©Full-scale vector control is possible when used in combination with a motor with PLG (when using option).
- $\fill \ensuremath{{\mathbb O}}$  The built-in noise filter (EMC filter) helps reduce noise generated from the inverter.
- ©This series supports IPM motor operation. Use auto tuning to operate with the optimum motor characteristics.

#### Product Specifications

Inverter capacity	200V class: 0.4kW to 90kW, 400V class: 0.4kW to 500kW
Control method	IPM control, Soft-PWM control, high-carrier frequency PWM control (Select from V/F, advanced flux vector, or real sensor-less vector), vector control (when using options)
Output frequency range	0.2 to 400Hz (real sensor-less vector, upper frequency during vector control is 120Hz)
PM offline auto tuning	When using the MM-CF Series, the motor constants, etc., are automatically measured for operation with the optimum motor characteristics (IPM motors other than the MM-CF Series, and other IPM motor brands are also supported)
Starting torque	200% 0.3Hz (3.7K or less), 150% 0.3Hz (5.5K or more)
	(when using real sensor-less vector, vector control)

#### Robo<sup>.</sup>

#### MELFA F Series



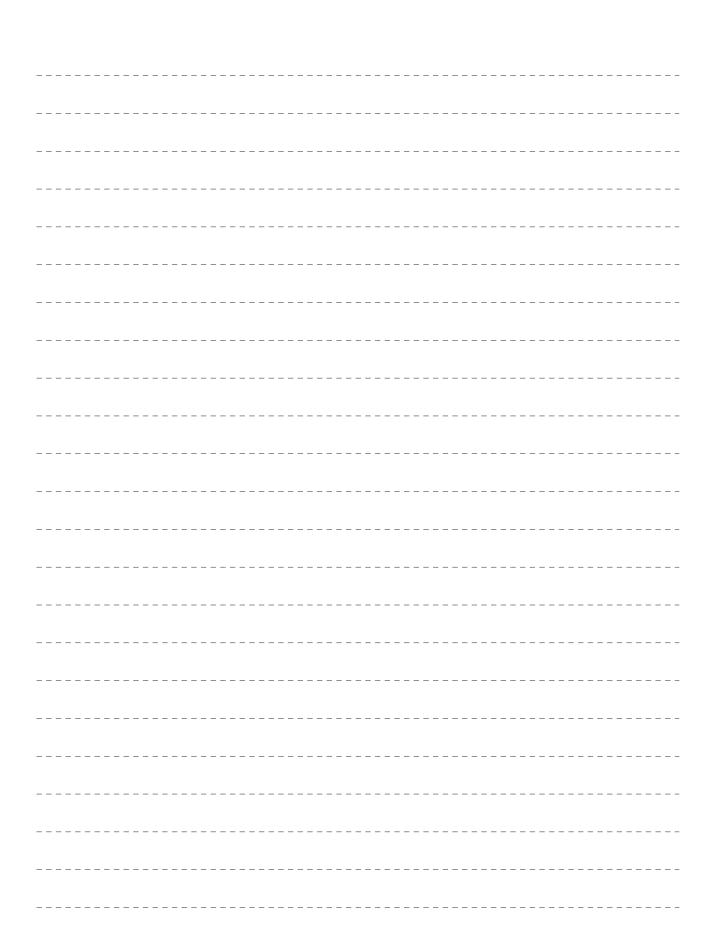
High speed, high precision and high reliability industrial robot

- ©Compact body and slim arm design, allowing operating area to be expanded and load capacity increased.
- The fastest in its class using high performance motors and unique driver control technology.
- Olmproved flexibility for robot layout design considerations.
- Optimal motor control tuning set automatically based on operating position, posture, and load conditions.

#### Product Specifications

Degrees of freedom	Vertical:6 Horizontal:4
Installation	Vertical:Floor-mount, ceiling mount, wall mount (Range of motion for J1 is limited) Horizontal:Floor-mount
Maximum load capacity	Vertical:2-20kg Horizontal:3-20kg
Maximum reach radius	Vertical:504-1503mm Horizontal:350-1,000mm

MEMO



MEMO











## Mitsubishi iQ Platform Compatible FA Integrated Engineering Software MELSOFT iQ Works

#### Precautions before use

This publication explains the typical features and functions of the products herein and does not provide restrictions and other information related to usage and module combinations. Before using the products, always read the product user manuals. Mitsubishi Electric will not be held liable for damage caused by factors found not to be the cause of Mitsubishi Electric; opportunity loss or lost profits caused by faults in Mitsubishi Electric products; damage, secondary damage, or accident compensation, whether foreseeable or not, caused by special factors; damage to products other than Mitsubishi Electric products; and to other duties.



- To use the products given in this publication properly, always read the relevant manuals before use.
- The products have been manufactured as general-purpose parts for general industries, and have not been designed or manufactured to be incorporated in a device or system used in purposes related to human life.
- Before using the products for special purposes such as nuclear power, electric power, aerospace, medicine or passenger movement vehicles, consult with Mitsubishi Electric.
- The products have been manufactured under strict quality control. However, when installing the products where major accidents or losses could occur if the products fail, install appropriate backup or fail-safe functions in the system.

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